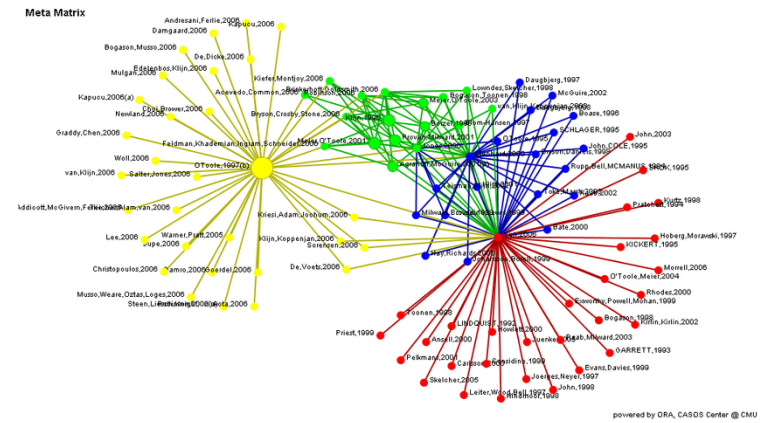
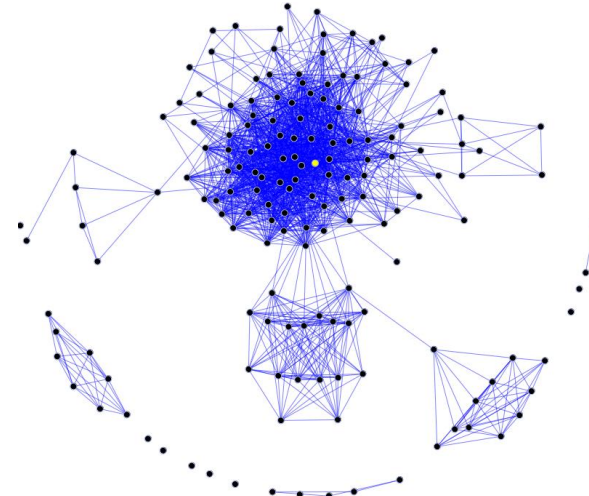
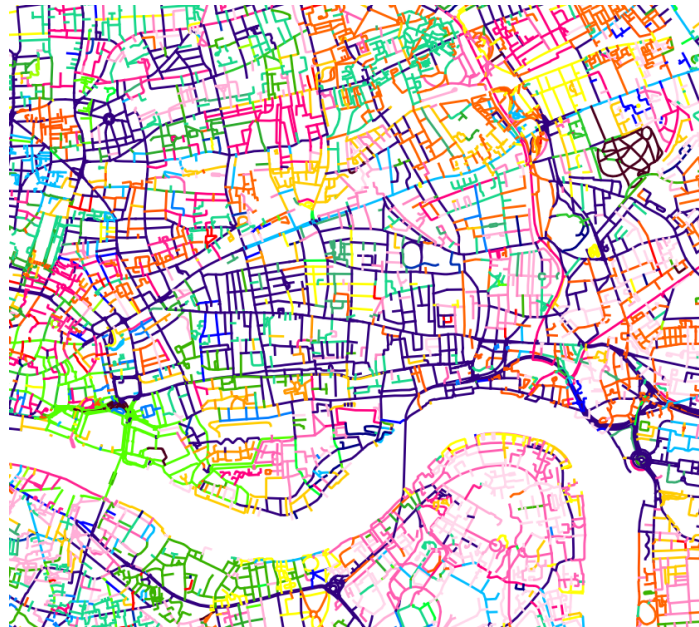
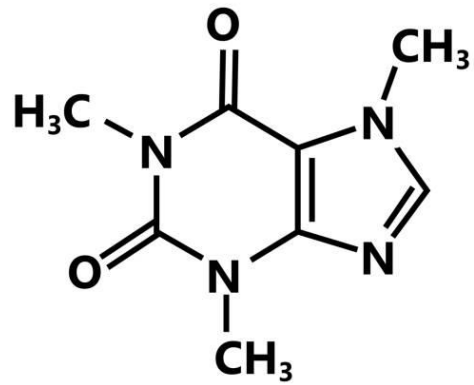


Graph Neural Networks – basics architectures

Giorgio Piatti

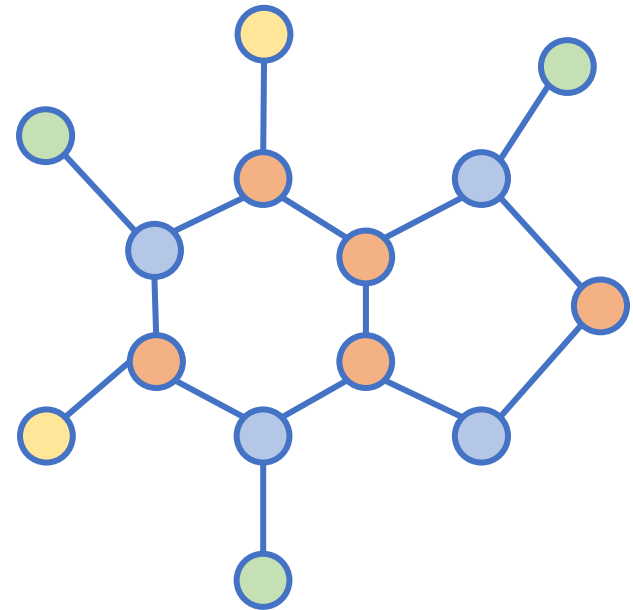
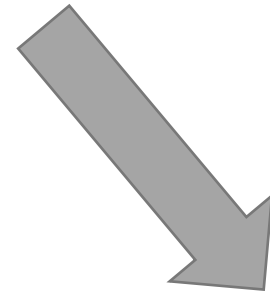
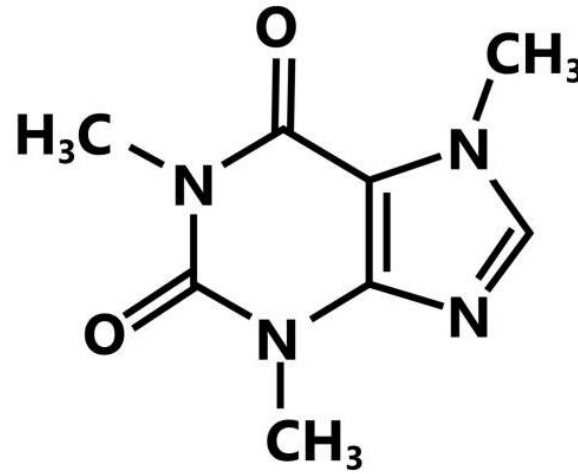
SiDNN – 08.03.2022

Motivation



Motivation

- Atoms as nodes
- Bonds as edges
- Features:
 - Atom type
 - Charge
 - Bond type



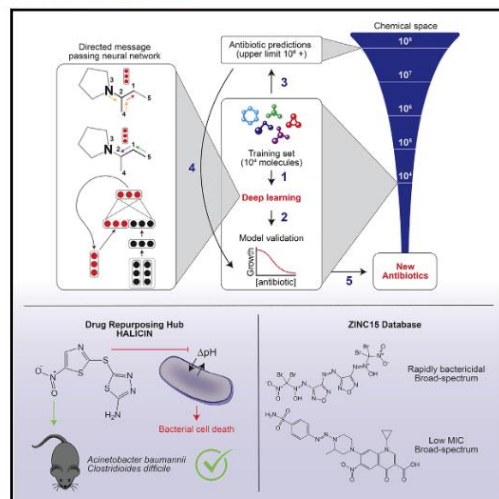
Motivation

Cell

Article

A Deep Learning Approach to Antibiotic Discovery

Graphical Abstract



Authors

Jonathan M. Stokes, Kevin Yang,
Kyle Swanson, ..., Tommi S. Jaakkola,
Regina Barzilay, James J. Collins

Correspondence

regina@csail.mit.edu (R.B.),
jimjc@mit.edu (J.J.C.)

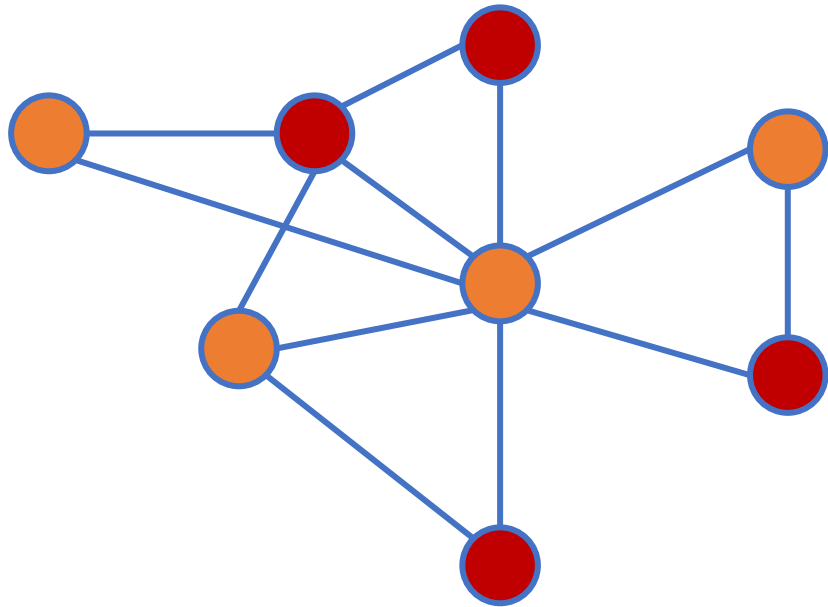
In Brief

A trained deep neural network predicts antibiotic activity in molecules that are structurally different from known antibiotics, among which Halicin exhibits efficacy against broad-spectrum bacterial infections in mice.

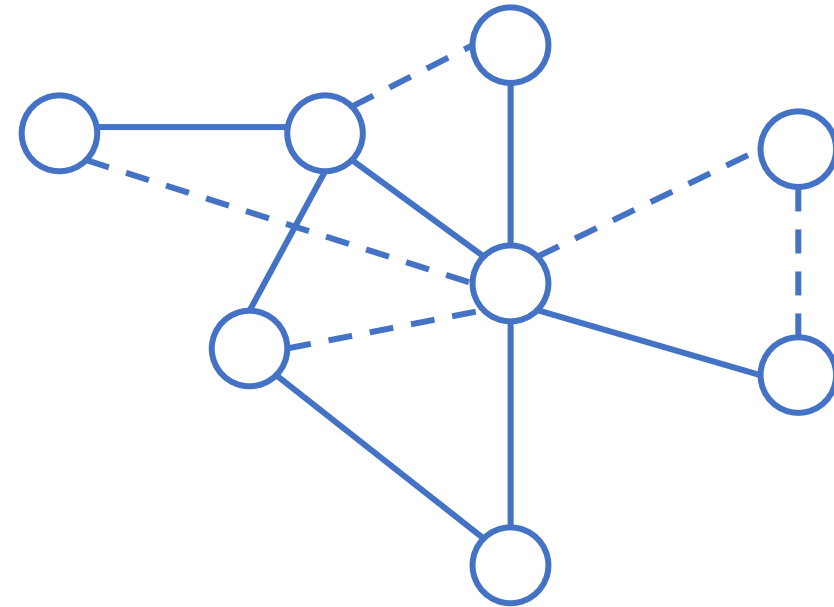
<https://doi.org/10.1016/j.cell.2020.01.021>

Learning problems

Node classification

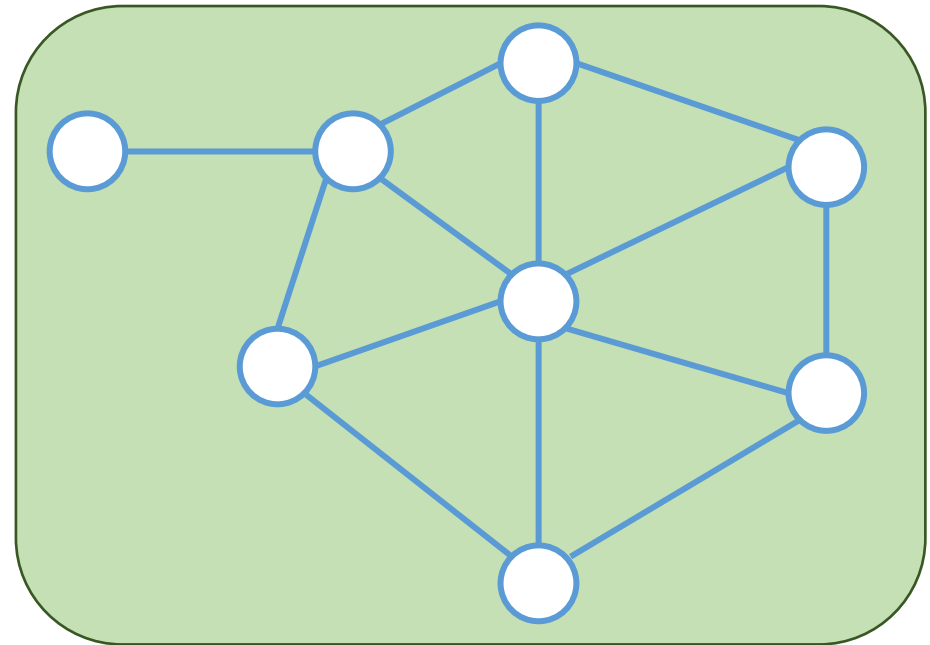
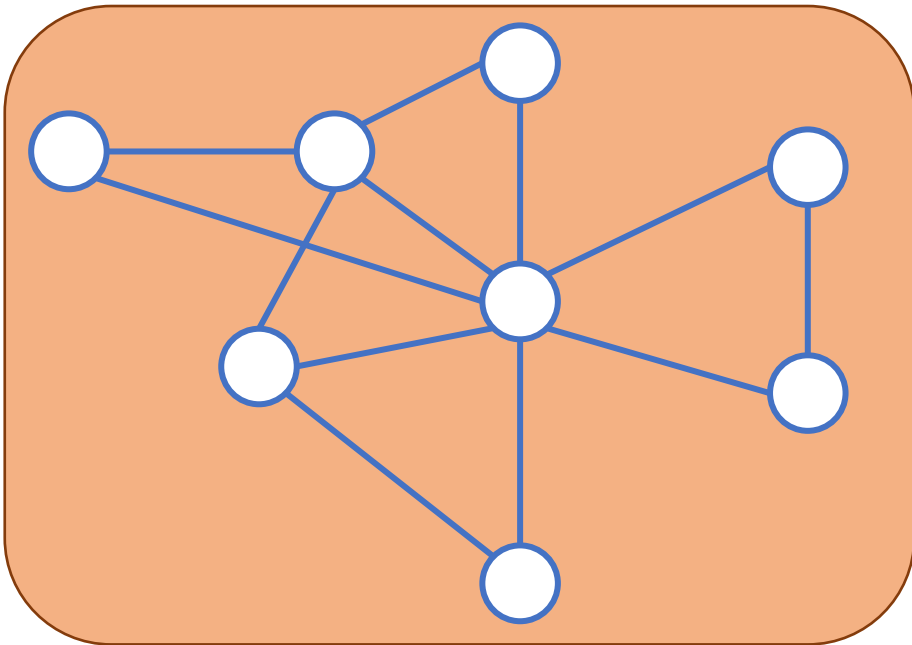


Relation prediction

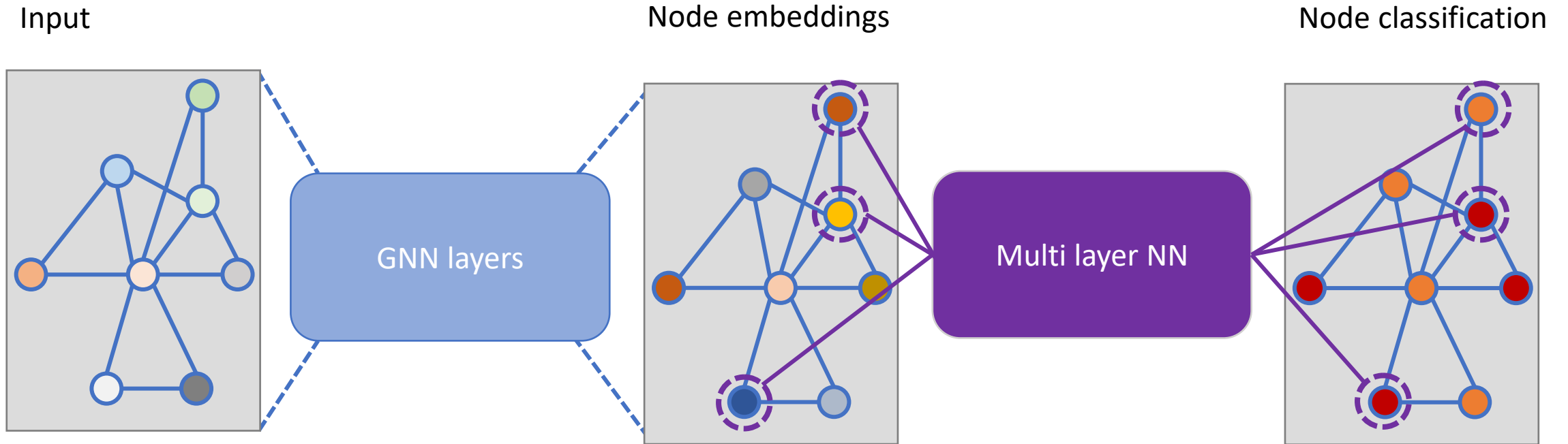


Learning problems

Graph classification



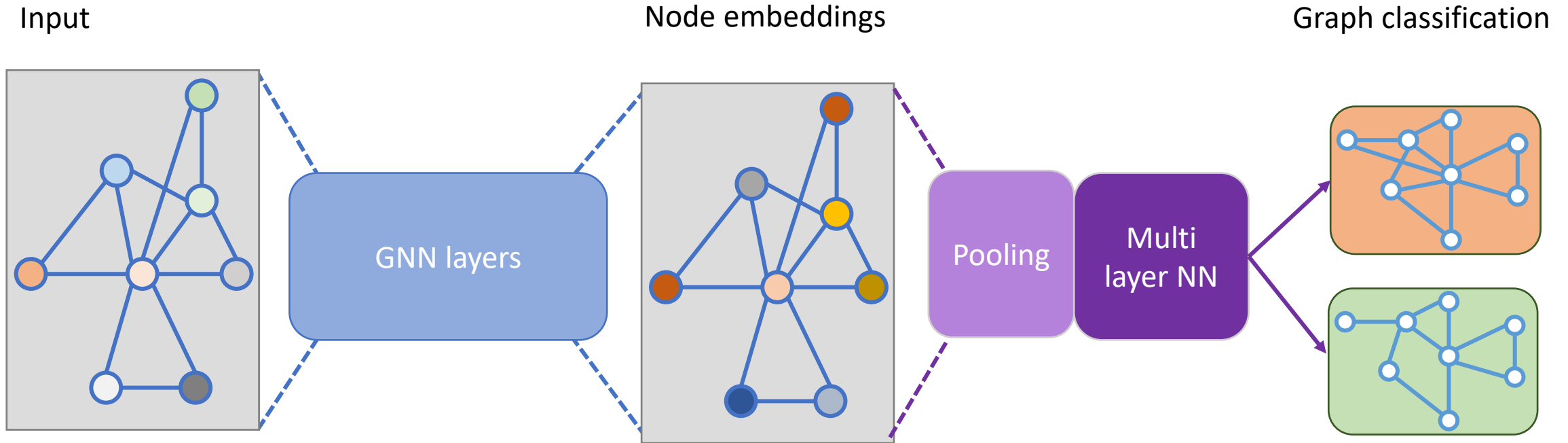
GNN architecture – node classification



A GNN is an optimizable transformation on all attributes of the graph (nodes, edges)

Loss: cross-entropy

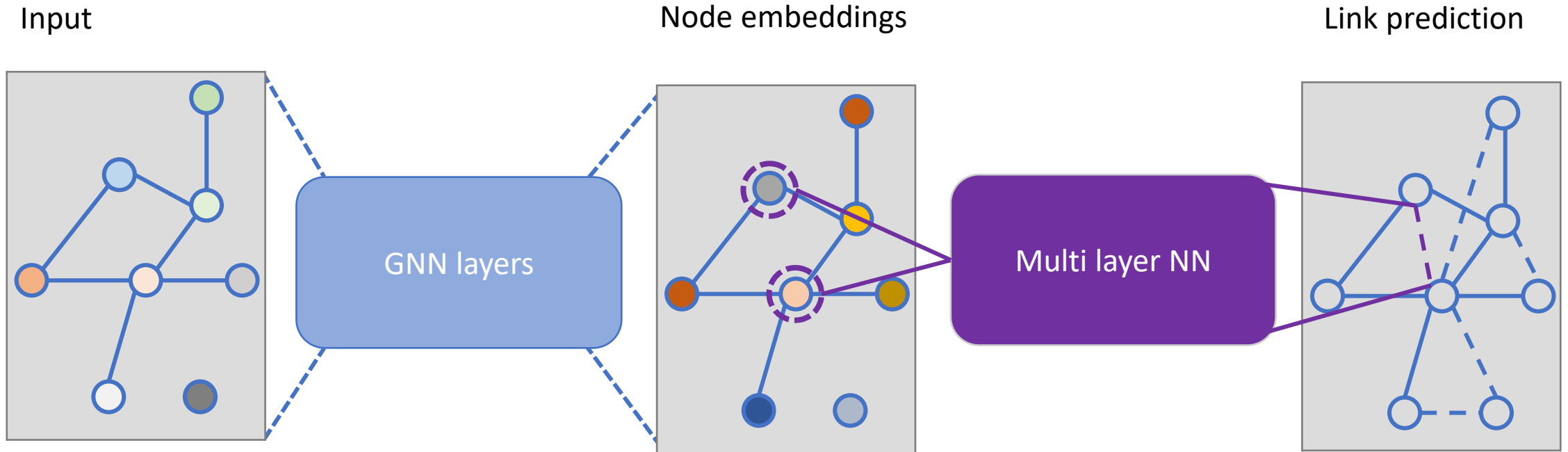
GNN architecture – graph classification



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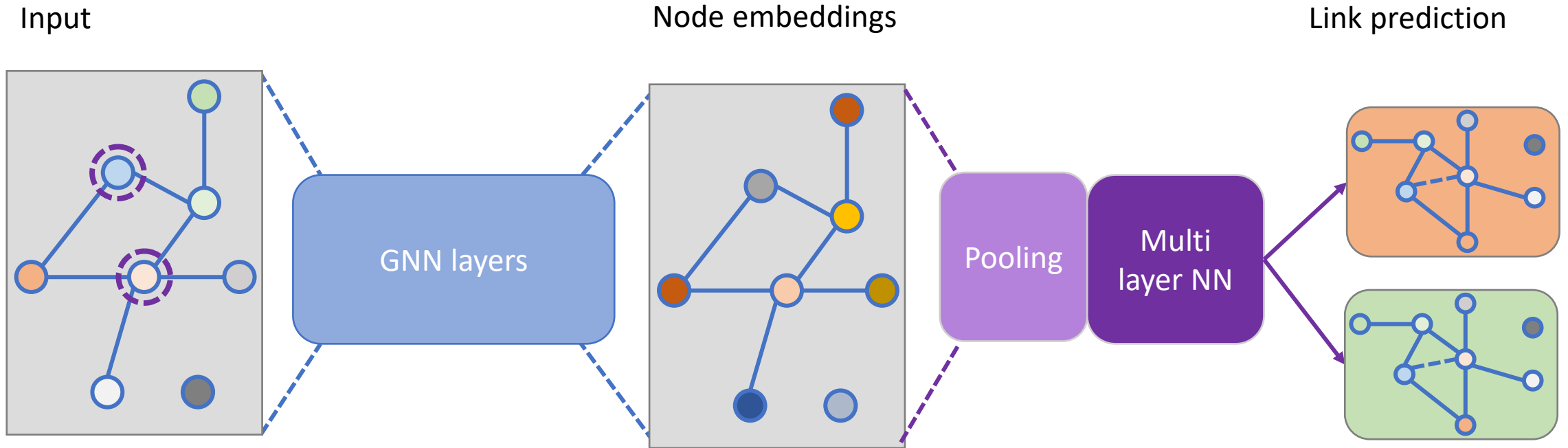
GNN architecture – link prediction



A GNN is an optimizable transformation on all attributes of the graph (nodes, edges)

Loss form: $\mathcal{L}(h_u, h_v, e_{uv})$

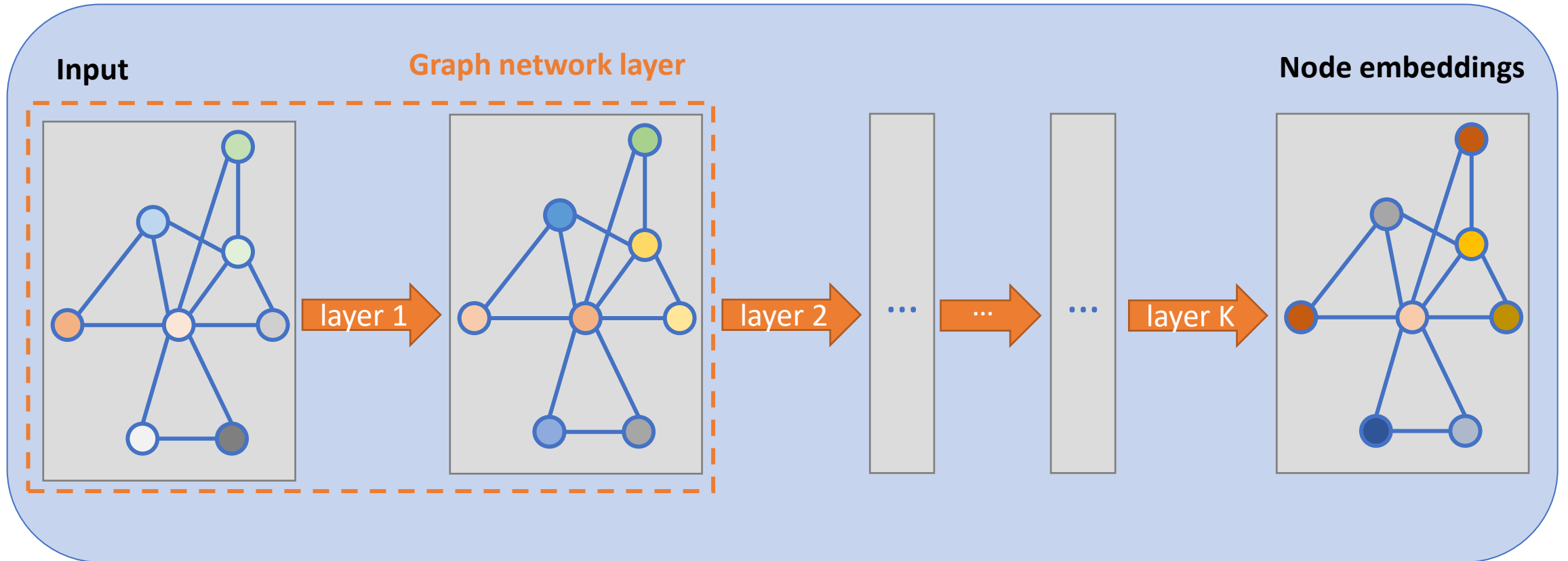
GNN architecture – link prediction



A GNN is an optimizable transformation on all attributes of the graph (nodes, edges)

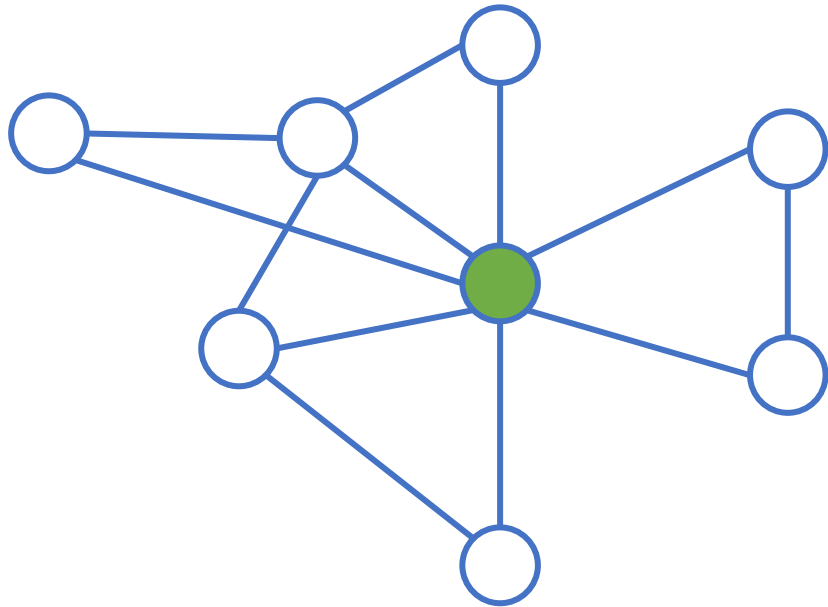
Loss form: $\mathcal{L}(h_u, h_v, e_{uv})$

GNN layers

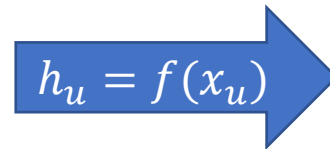


GNN layers

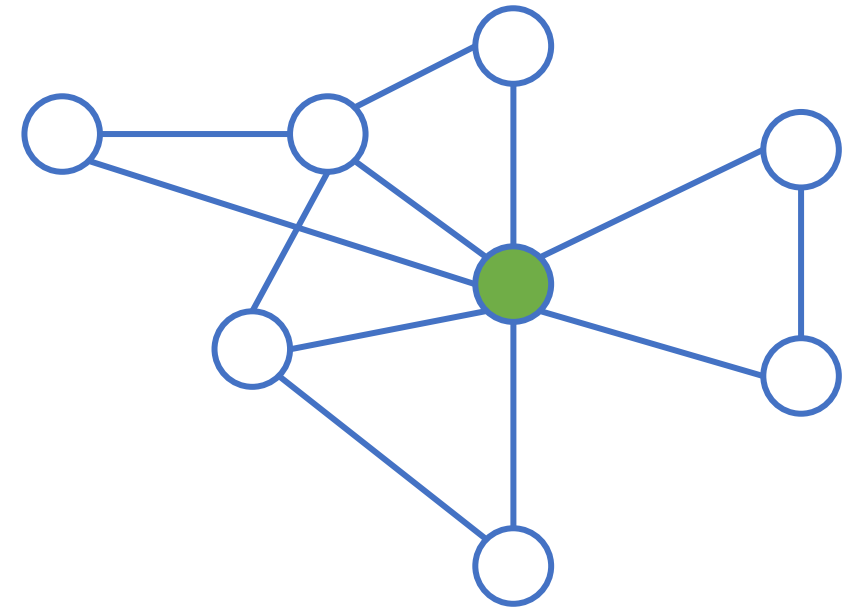
Input



Graph $G=(V,E)$
Feature vector $x_u \in \mathbb{R}^d$ for all $u \in V$



Node embeddings



Vector embedding $h_u \in \mathbb{R}^d$

Key ideas

Special class of graphs: image grids

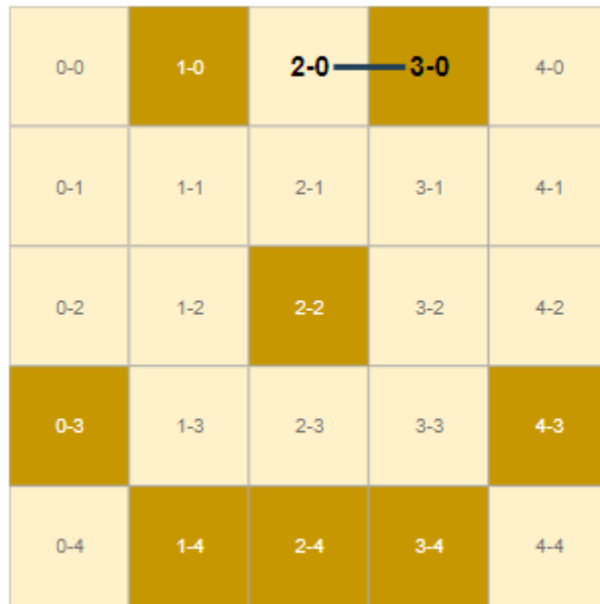
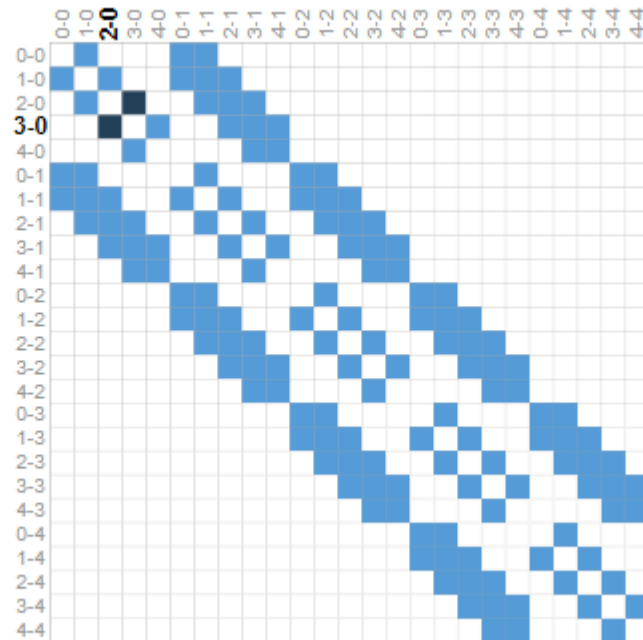
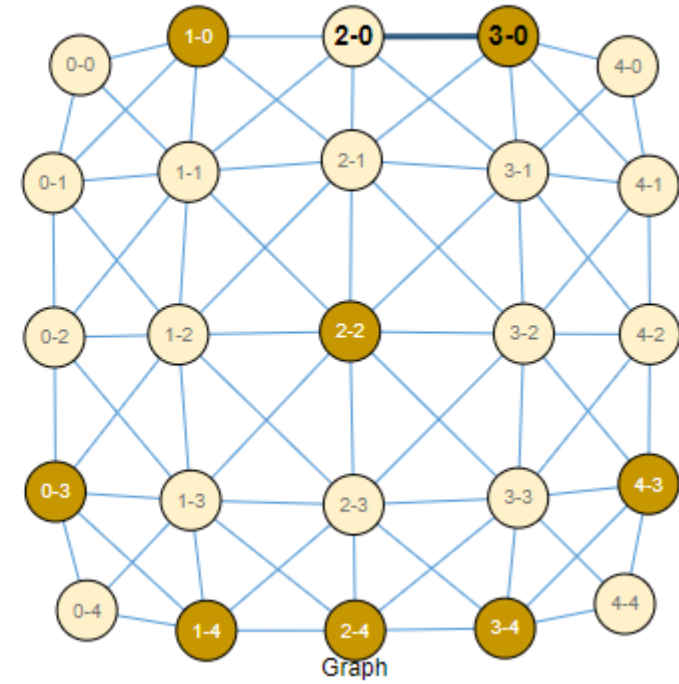


Image Pixels



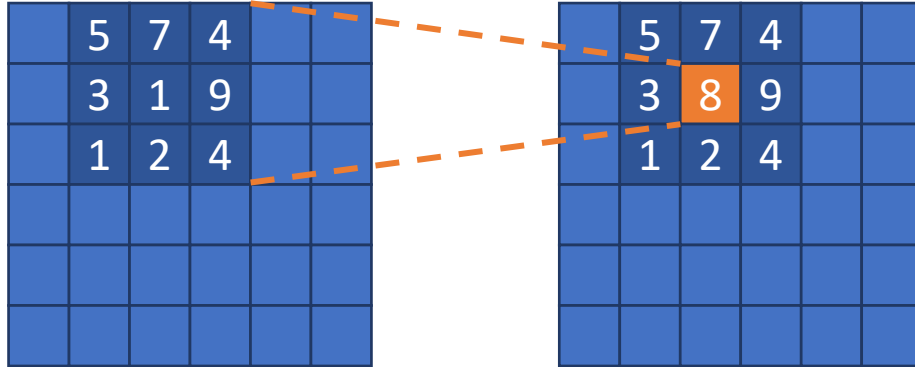
Adjacency Matrix



Key ideas

Images

Convolution on grid



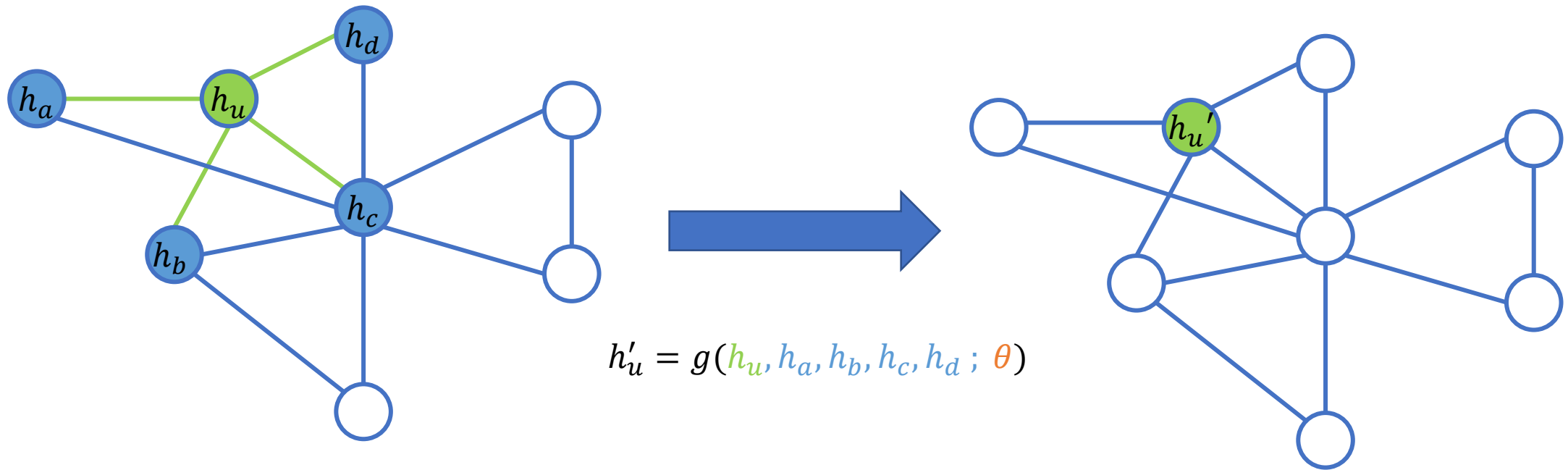
Graphs

Convolution on adjacent matrix ?



Sensitive to node reordering
& graph size

Key ideas



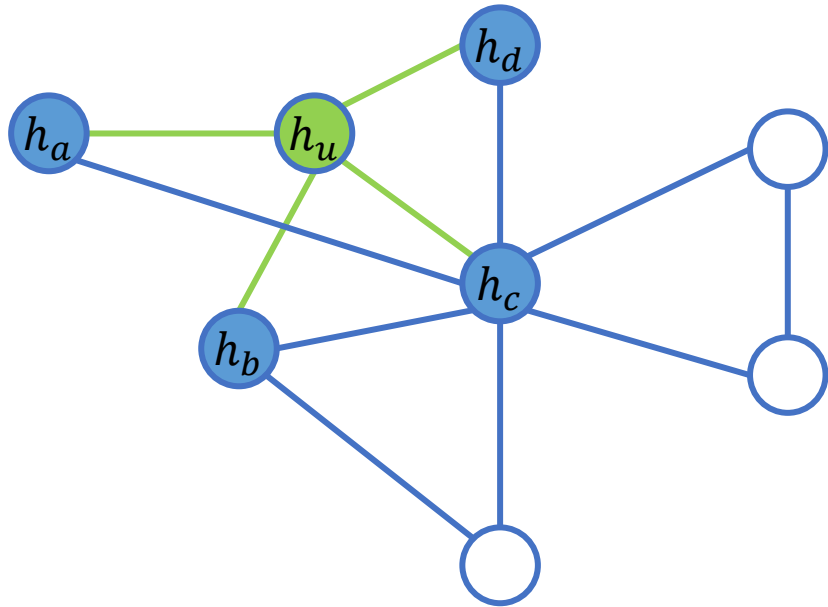
Key ideas

Desirable properties of g :

- Fixed number of parameters
- Leverage local information
- Permutation invariant

Message Passing Neural Network (MPNN)

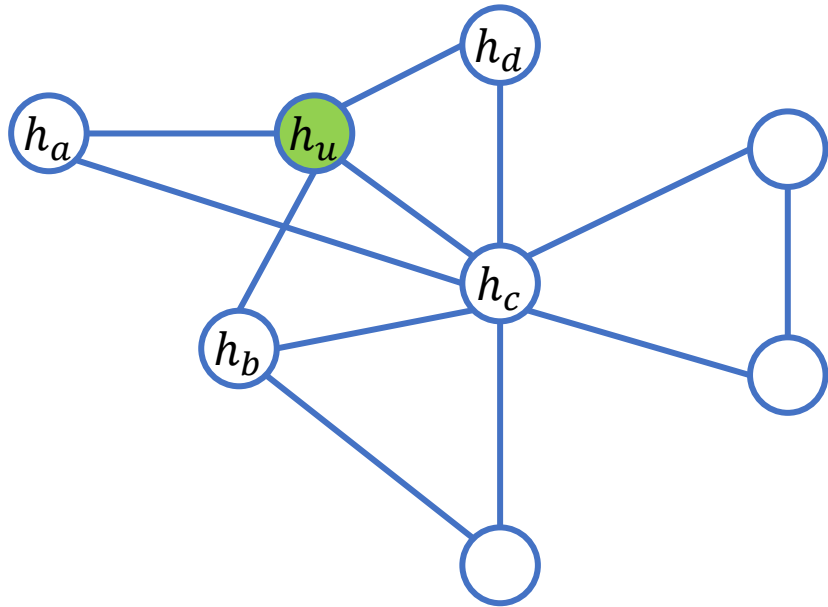
Message Passing Neural Network (MPNN)



$h_u^{(k)}$ = embedding of u at k^{th} – iteration

$$m_{N(u)}^{(k)} = \text{AGGREGATE}^{(k)} \left(\left\{ h_v^{(k)}, \forall v \in N(u) \right\} \right)$$

Message Passing Neural Network (MPNN)

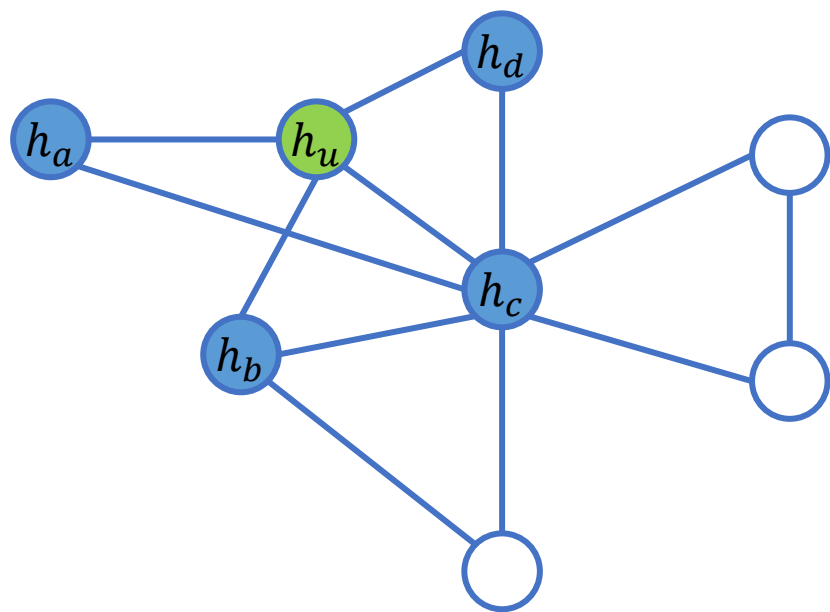


$h_u^{(k)}$ = embedding of u at k^{th} – iteration

$$m_{N(u)}^{(k)} = \text{AGGREGATE}^{(k)} \left(\left\{ h_v^{(k)}, \forall v \in N(u) \right\} \right)$$

$$h_u^{(k+1)} \leftarrow \text{UPDATE}^{(k)} \left(h_u^{(k)}, m_{N(u)}^{(k)} \right)$$

Basic GNN



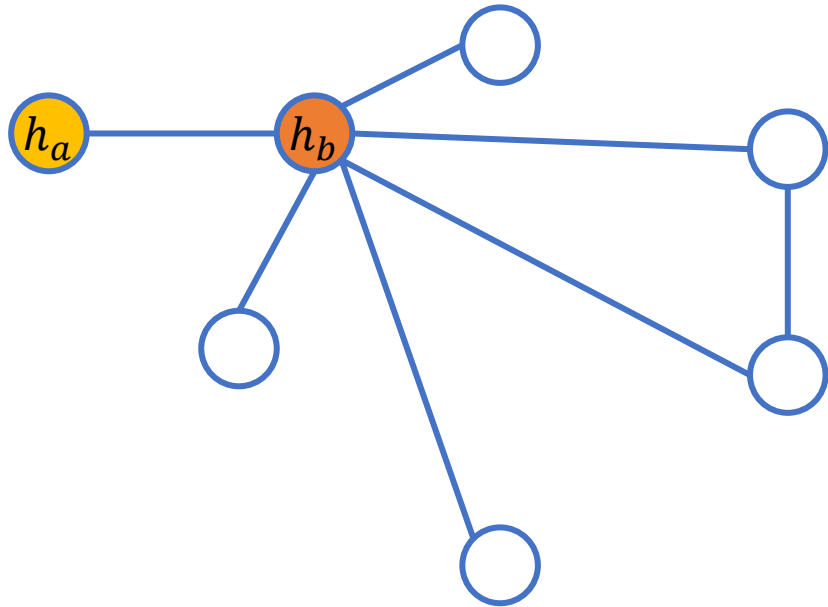
$$h_u \leftarrow \sigma(W_{self} h_u + W_{neigh}(h_a + h_b + h_c + h_d))$$

$$m_{N(u)} = \text{AGGREGATE}(\{h_v, \forall v \in N(u)\}) = \sum_{v \in N(u)} h_v$$

$$h_u \leftarrow \text{UPDATE}(h_u, m_{N(u)}) = \sigma(W_{self} h_u + W_{neigh} m_{N(u)})$$

$$\theta = \{W_{self}, W_{neigh}\}$$

Neighborhood normalization



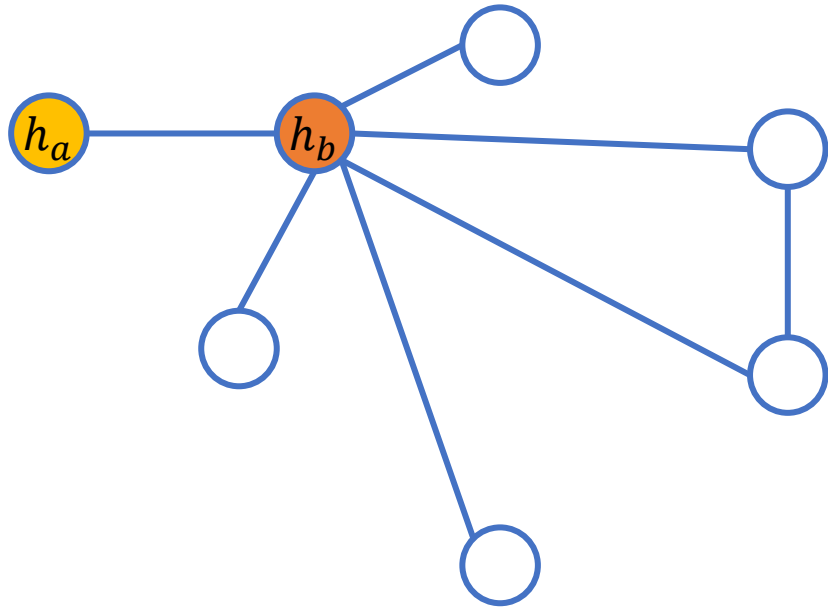
Assume

$$\left\| \sum_{v \in N(b)} h_v \right\| \gg \left\| \sum_{v \in N(a)} h_v \right\|$$



Numerical instabilities & difficulties for optimization

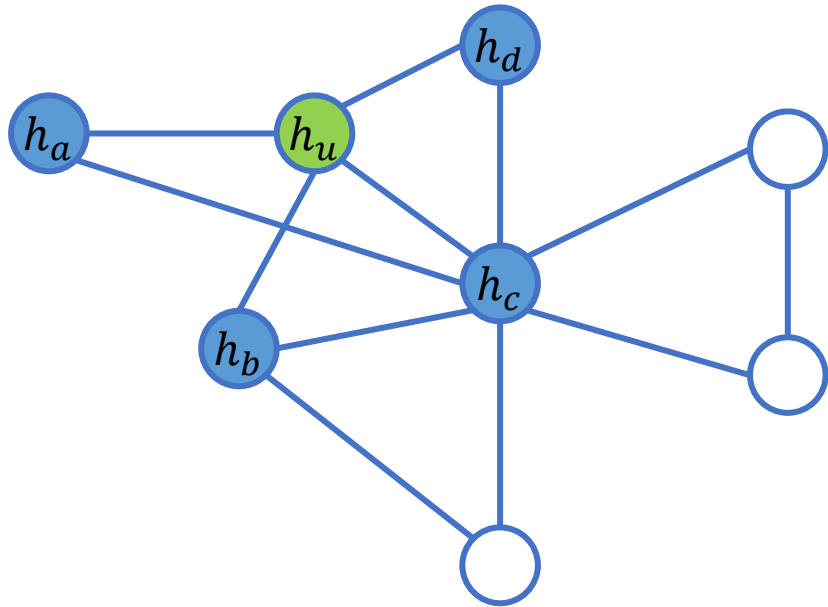
Neighborhood normalization



$$m_{N(u)} = \frac{1}{|N(u)|} \sum_{v \in N(u)} h_v$$

Downsides:
loss of information about structural info

Graph Convolution Network (GCN)



$$m_{N(u)} = \text{AGGREGATE} \left(\{h_v, \forall v \in N(u) \cup \{u\}\} \right)$$

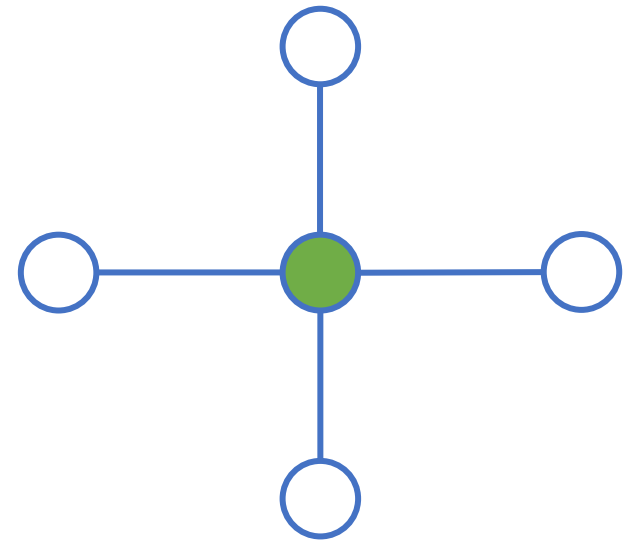
$$= \sum_{v \in N(u) \cup \{u\}} \frac{h_v}{\sqrt{|N(u)| |N(v)|}}$$

$$h_u \leftarrow \text{UPDATE}(h_u, m_{N(u)}) = \sigma(W m_{N(u)})$$

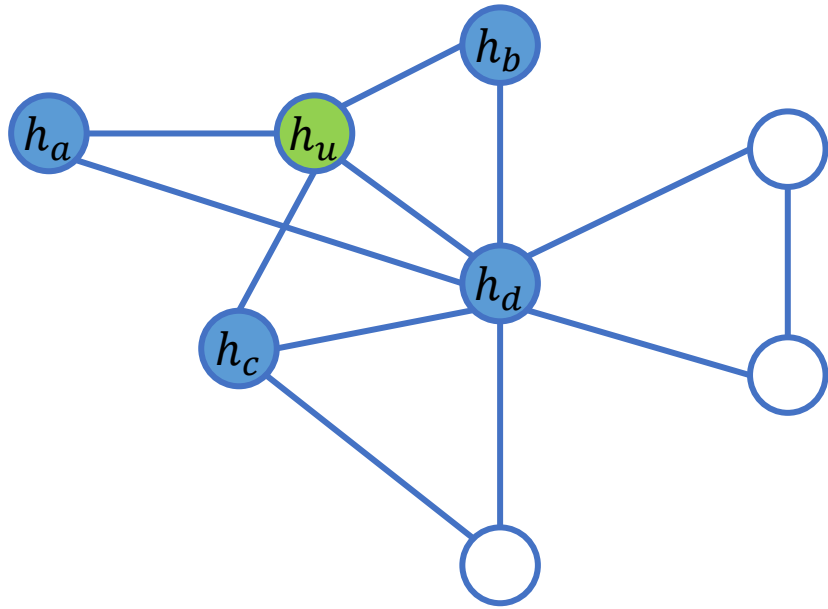
MPNN – limitations



Sum aggregate can distinguish,
mean cannot



Graph Isomorphism Network (GIN)



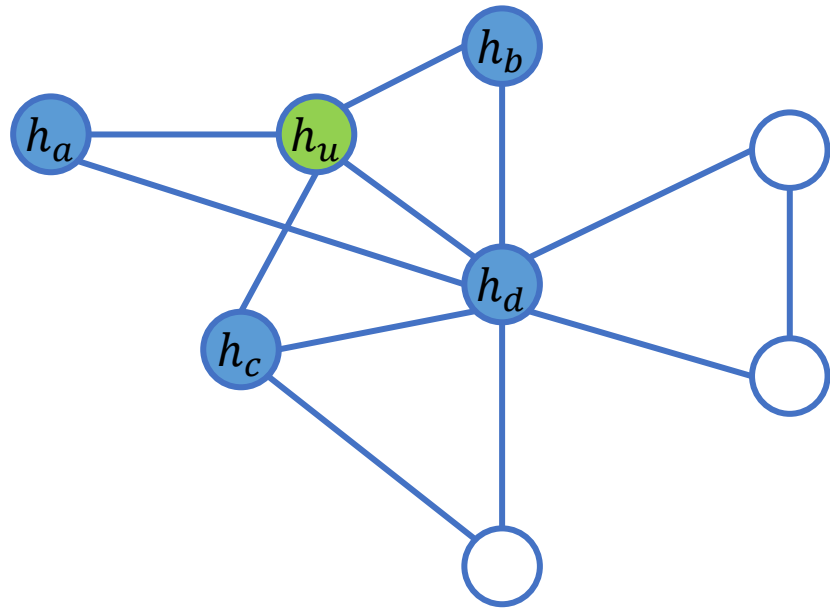
$$h_u \leftarrow \text{UPDATE}(h_u, \text{AGGREGATE}(\{h_v, \forall v \in N(u)\}))$$



How to learn any set function?

$$g(X) = \varphi\left(\sum_{x \in X} f(x)\right), \quad \text{s.t. } \sum_{x \in X} f(x) \text{ unique}$$

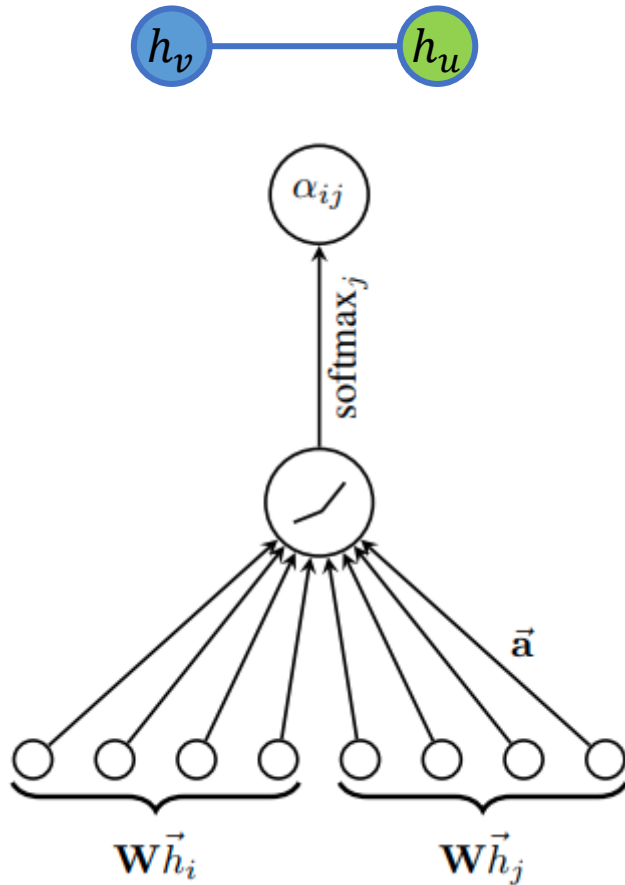
Graph Isomorphism Network (GIN)



$$h_u^{(k)} = MLP^{(k)} \left((1 + \epsilon)h_u^{(k-1)} + \sum_{v \in N(u)} h_v^{(k-1)} \right)$$

MLP=multi-layer perceptron NN

Graph Attention Network (GAT)



How relevant a neighboring node is in relation to the center node?

$$m_{N(u)} = \text{AGGREGATE}(\{h_v, \forall v \in N(u)\}) = \sum_{v \in N(u)} \alpha_{u,v} h_v$$

Bilinear attention model

$$\alpha_{u,v} = \frac{\exp(a^T [Wh_u \oplus Wh_v])}{\sum_{v' \in N(u)} \exp(a^T [Wh_u \oplus Wh_{v'}])}$$

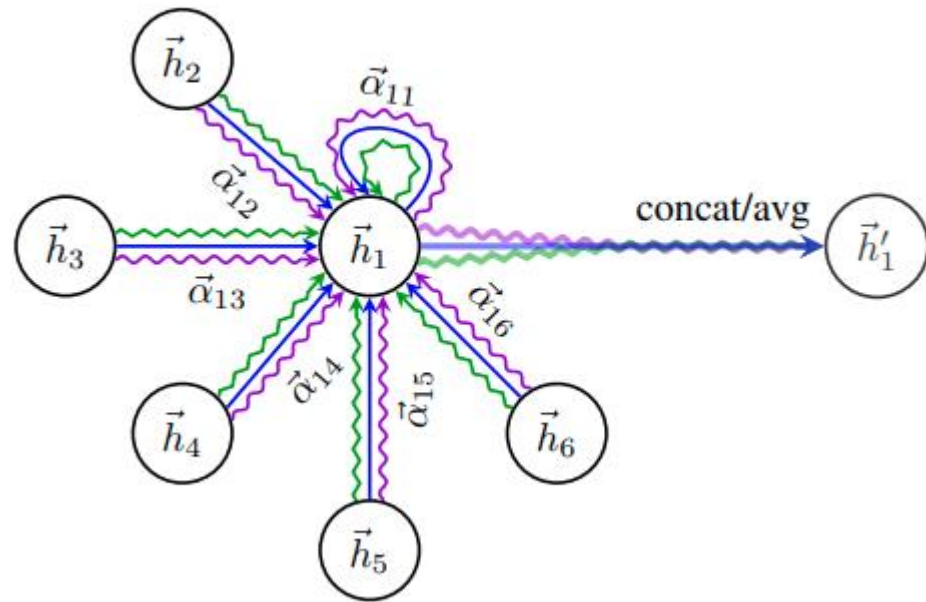
Attention via MLP

$$\alpha_{u,v} = \frac{\exp(\text{MLP}(h_u, h_v; \theta))}{\sum_{v' \in N(u)} \exp(\text{MLP}(h_u, h_{v'}; \theta))}$$

Graph Attention Network (GAT)



How relevant a neighboring node is in relation to the center node?



Multiple attention “heads”

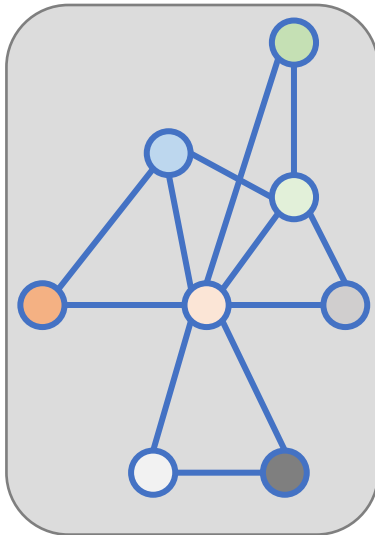
$$m_{N(u)} = \text{AGGREGATE}(\{h_v, \forall v \in N(u)\}) = [a_1 \oplus a_2 \oplus \dots \oplus a_K]$$

$$a_k = W_i \sum_{v \in N(u)} \alpha_{u,v,k} h_v$$

GAT - results

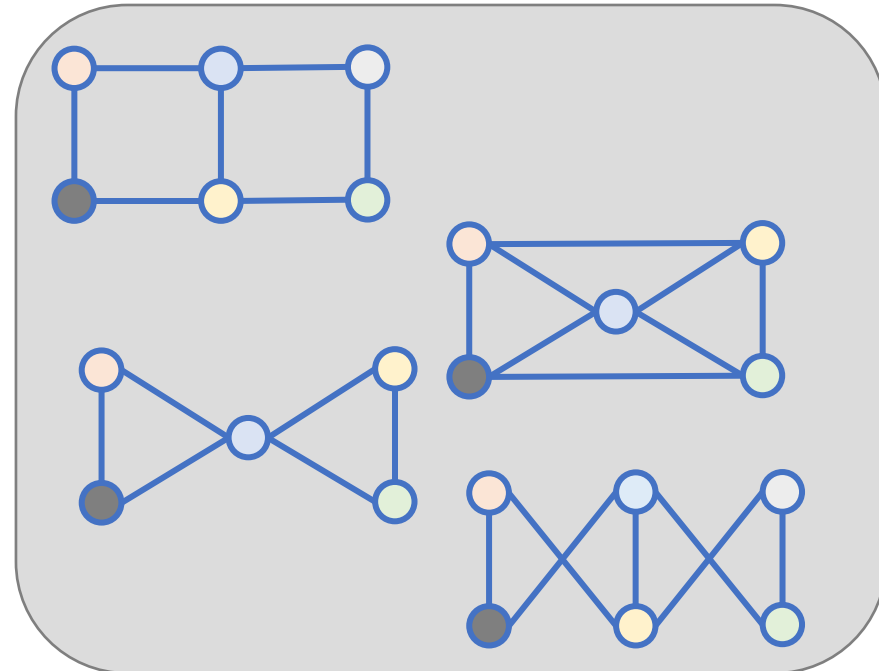
Transductive setting

1 graph, some labels are masked



Inductive setting

Multiple graphs, some for training, some for test



GAT - results

	Cora	Citeseer	Pubmed	PPI
Task	Transductive	Transductive	Transductive	Inductive
# Nodes	2708 (1 graph)	3327 (1 graph)	19717 (1 graph)	56944 (24 graphs)
# Edges	5429	4732	44338	818716
# Features/Node	1433	3703	500	50
# Classes	7	6	3	121 (multilabel)
# Training Nodes	140	120	60	44906 (20 graphs)
# Validation Nodes	500	500	500	6514 (2 graphs)
# Test Nodes	1000	1000	1000	5524 (2 graphs)

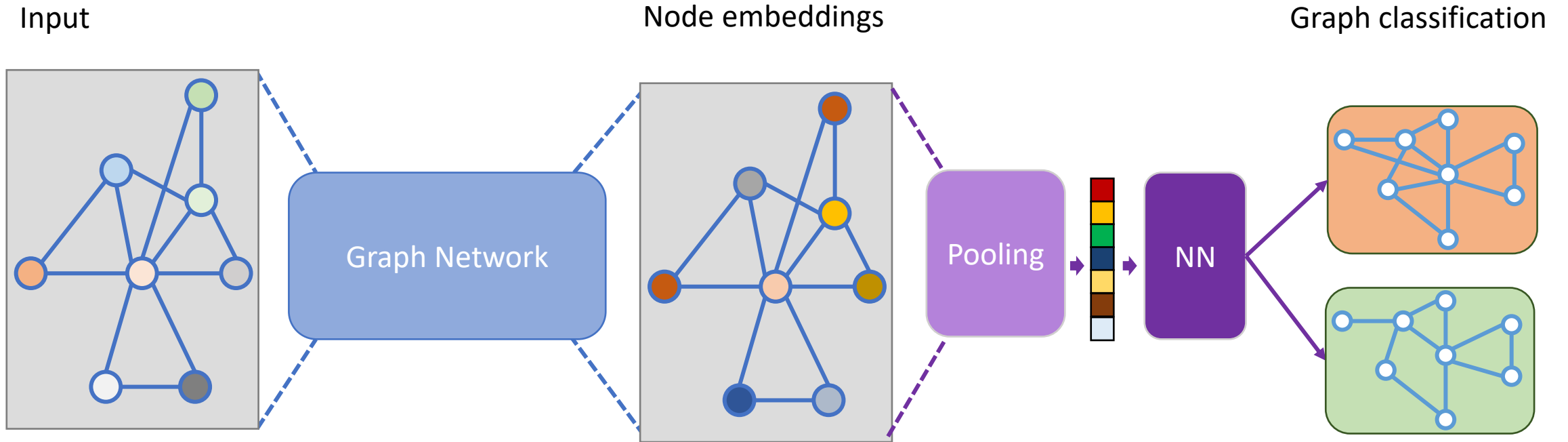
old

<i>Transductive</i>			
Method	Cora	Citeseer	Pubmed
MLP	55.1%	46.5%	71.4%
ManiReg (Belkin et al., 2006)	59.5%	60.1%	70.7%
SemiEmb (Weston et al., 2012)	59.0%	59.6%	71.7%
LP (Zhu et al., 2003)	68.0%	45.3%	63.0%
DeepWalk (Perozzi et al., 2014)	67.2%	43.2%	65.3%
ICA (Lu & Getoor, 2003)	75.1%	69.1%	73.9%
Planetoid (Yang et al., 2016)	75.7%	64.7%	77.2%
Chebyshev (Defferrard et al., 2016)	81.2%	69.8%	74.4%
GCN (Kipf & Welling, 2017)	81.5%	70.3%	79.0%
MoNet (Monti et al., 2016)	81.7 ± 0.5%	—	78.8 ± 0.3%
GCN-64*	81.4 ± 0.5%	70.9 ± 0.5%	79.0 ± 0.3%
GAT (ours)	83.0 ± 0.7%	72.5 ± 0.7%	79.0 ± 0.3%

old

<i>Inductive</i>	
Method	PPI
Random	0.396
MLP	0.422
GraphSAGE-GCN (Hamilton et al., 2017)	0.500
GraphSAGE-mean (Hamilton et al., 2017)	0.598
GraphSAGE-LSTM (Hamilton et al., 2017)	0.612
GraphSAGE-pool (Hamilton et al., 2017)	0.600
GraphSAGE*	0.768
Const-GAT (ours)	0.934 ± 0.006
GAT (ours)	0.973 ± 0.002

Graph pooling

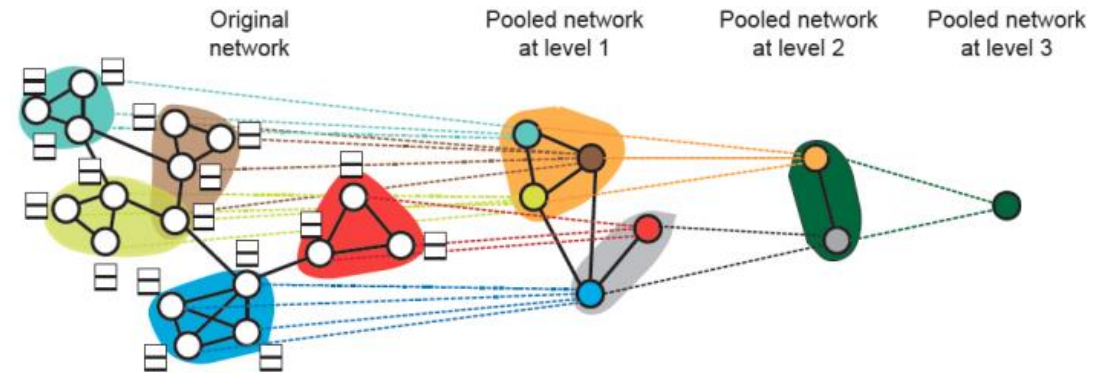


Graph pooling

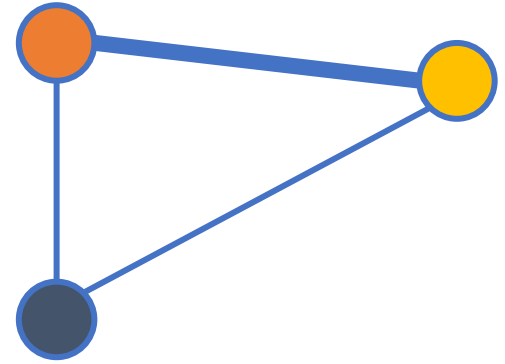
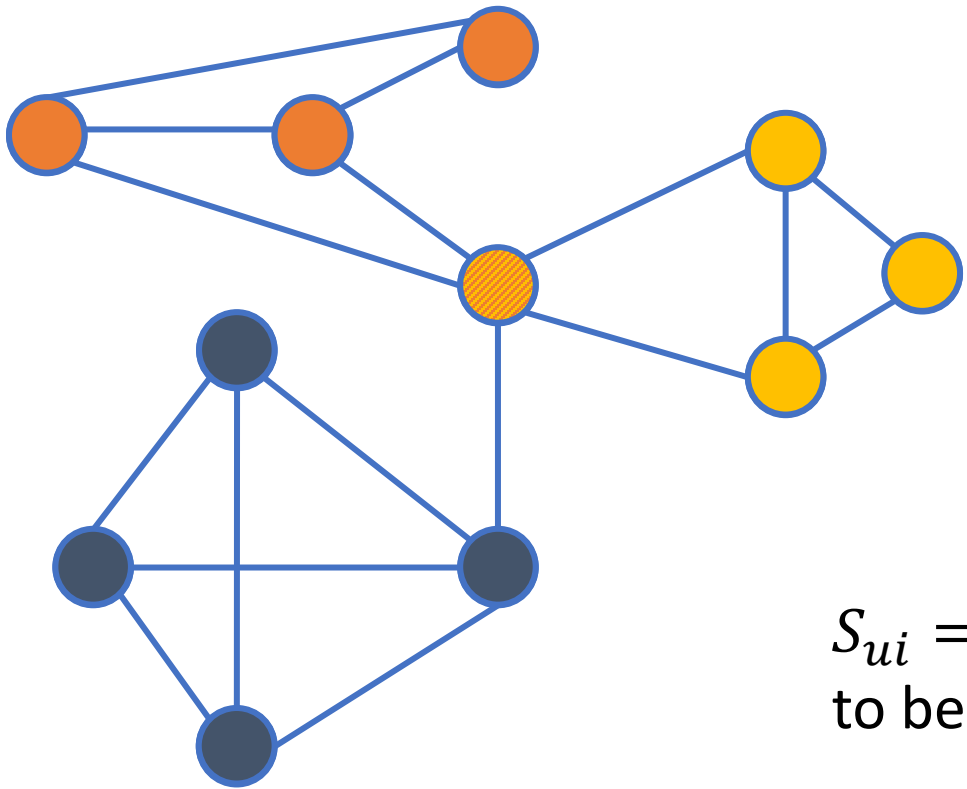
Set pooling approaches

- $Z_G = \frac{\sum_{v \in V} z_v}{|V|}$
- $Z_G = \sum_{v \in V} z_v$

Graph coarsening approaches



Graph coarsening

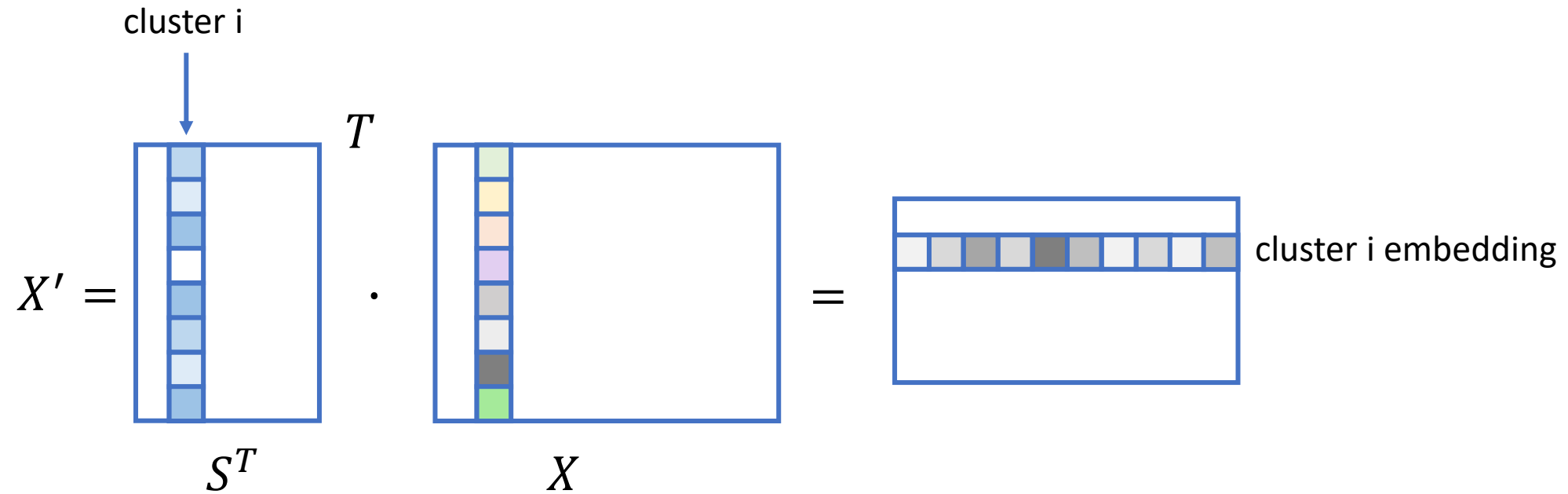


S_{ui} = prob. of node u
to belong to cluster i

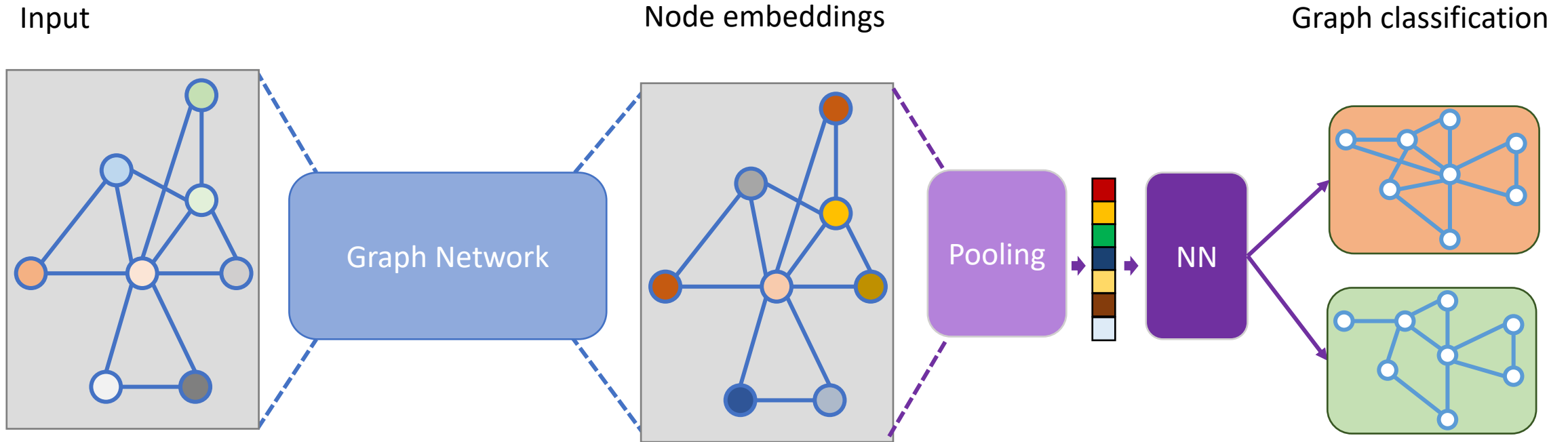
$$G': A', X'$$
$$A' = S^T A S \in \mathbb{R}^{c \times c}$$
$$X' = S^T X \in \mathbb{R}^{c \times d}$$

$G: A, X$

Graph coarsening

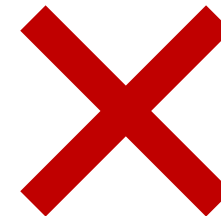
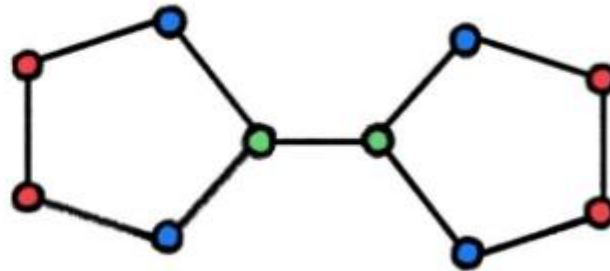
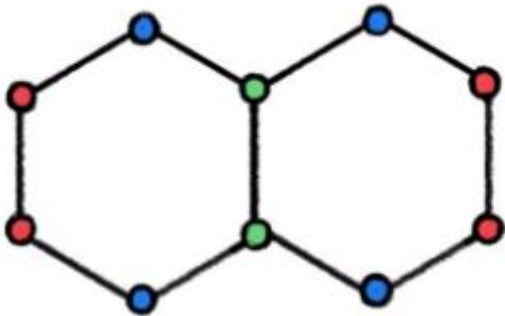
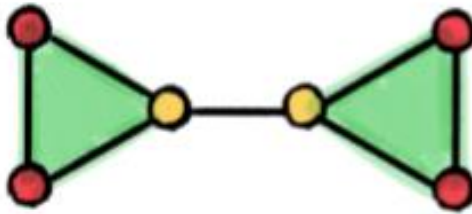
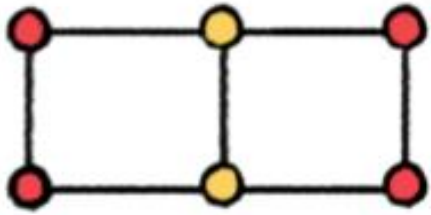


Graph pooling

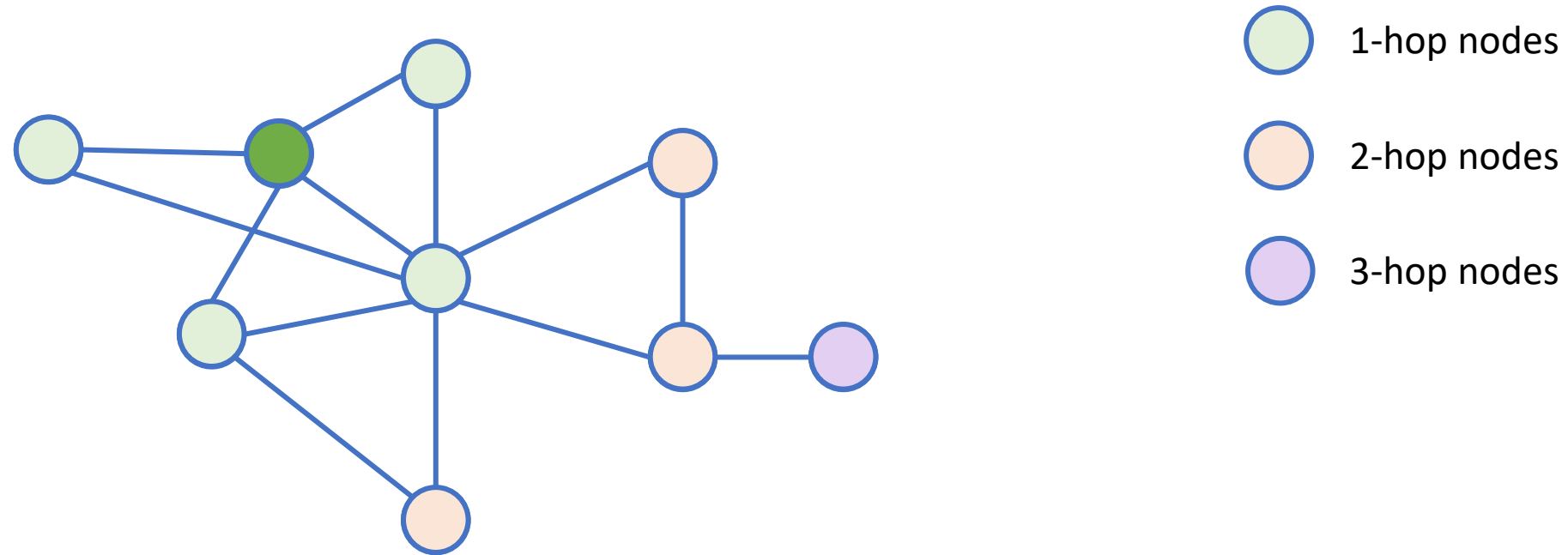


Outlook: problems

Problems – Graph isomorphism (WL-test)

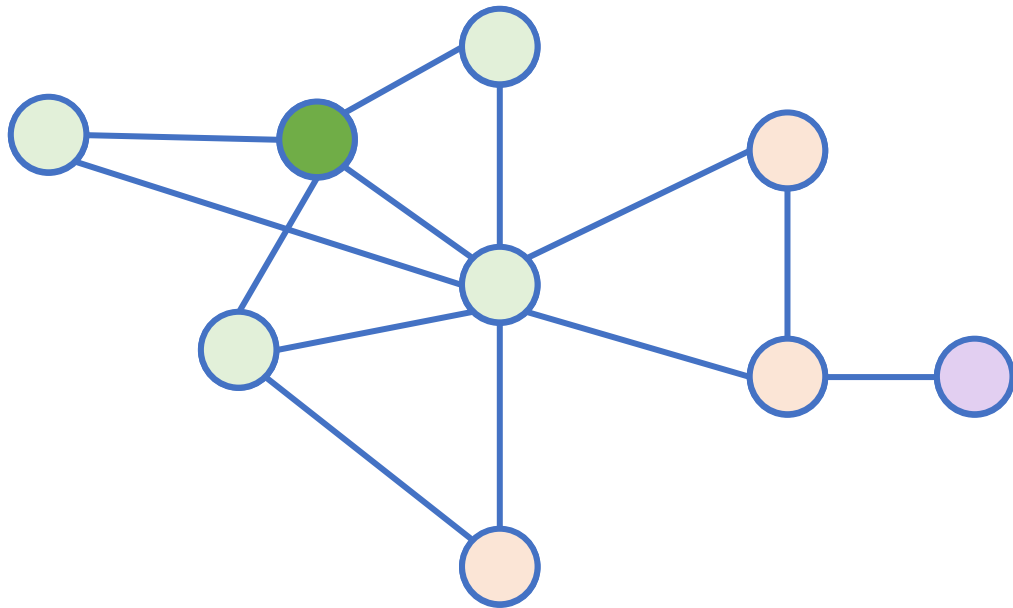


Problems – Underreaching



Problems – Underreaching

Issue

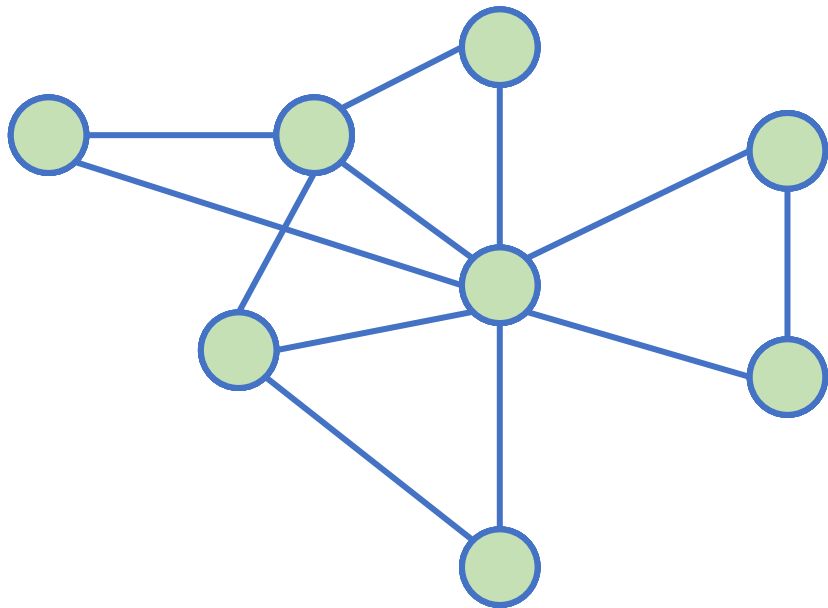



Possible solution

- Aggregate further away
- Add edges
 - Changes topology
 - May lead to oversmoothing

Problems – Oversmoothing

Issue



Averaging  same embedding for all nodes

Possible solution

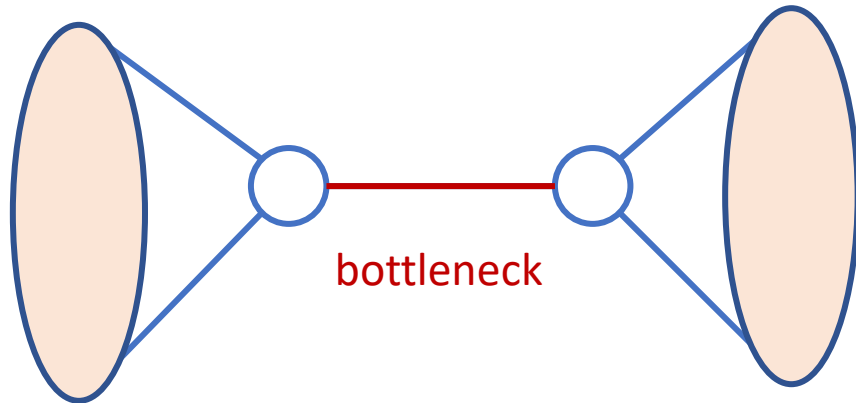
- Skip connections

$$m_{N(u)}^{(k)} = \text{AGGREGATE}^{(k)} \left(\{h_v^{(k)}, \forall v \in N(u)\} \right)$$

$$h_u^{(k+1)} \leftarrow \left[h_u^{(k)} \oplus \text{UPDATE}^{(k)} \left(h_u^{(k)}, m_{N(u)}^{(k)} \right) \right]$$

Problems – Oversquashing

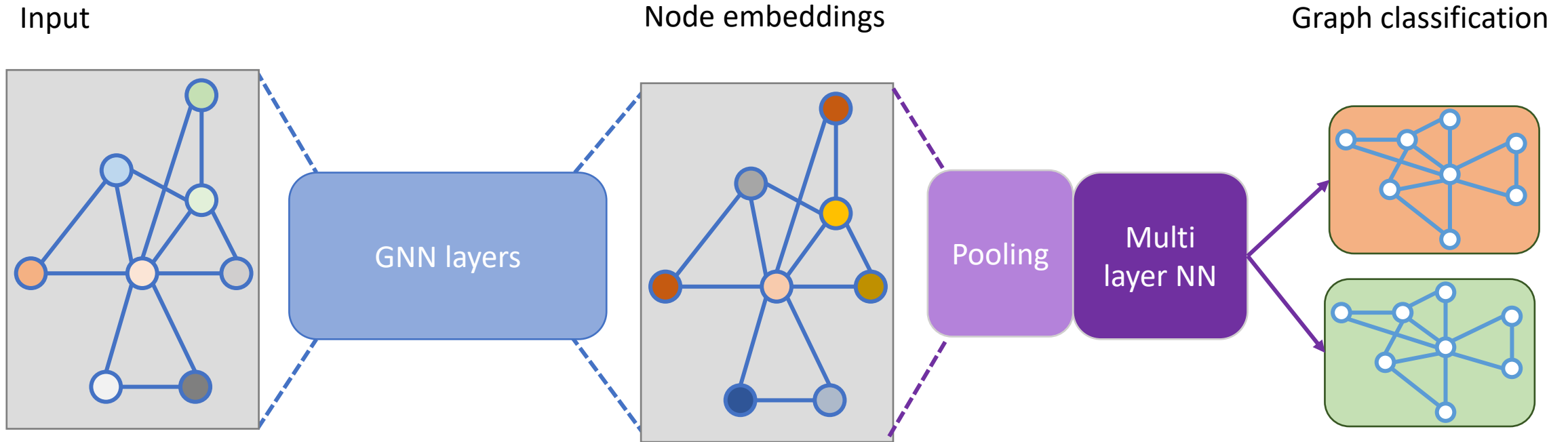
Issue



Possible solution

- Add edges
 - Changes topology
 - May lead to oversmoothing

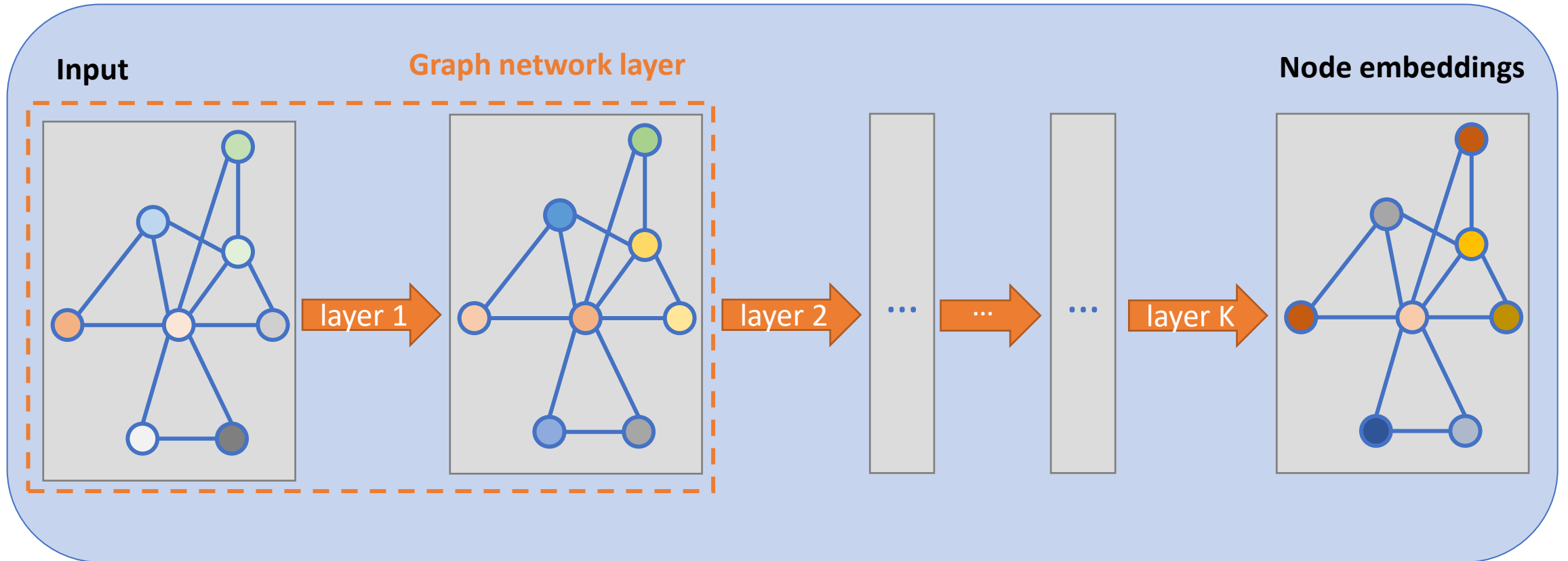
Summary



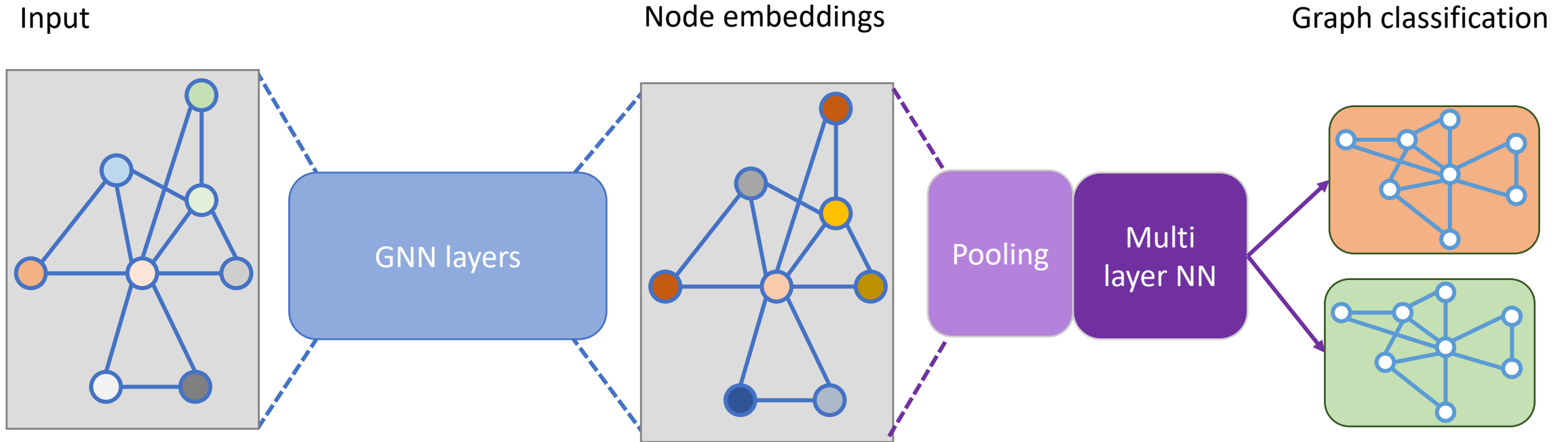
A GNN is an optimizable transformation on all attributes of the graph (nodes, edges)

Loss: cross-entropy

Summary



Summary



A GNN is an optimizable transformation on all attributes of the graph (nodes, edges)

Loss: cross-entropy