

Eidgenössische Technische Hochschule Zürich Swiss Federal Institute of Technology Zurich



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Prof. L. Thiele / R. Jacob

## Discrete Event Systems

Exercise Sheet 12

## 1 Comparison of Finite Automata

Here are two simple finite automata:

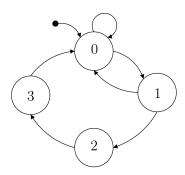


For each, we have a one bit encoding for the states  $(x_A \text{ and } x_B)$ , one binary output  $(y_A \text{ and } y_B)$ , and one common binary input (u). We want to verify whether or not these two automata are equivalent. This can be done through the following steps:

- a) Express the characteristic function of the transition relation for both automaton,  $\psi_r(x, x', u)$ .
- b) Express the joint transition function,  $\psi_f$ . Reminder:  $\psi_f(x_A, x_A', x_B, x_B') = (\exists u : \psi_A(x_A, x_A', u) \cdot \psi_B(x_B, x_B', u))$ .
- c) Express the characteristic function of the reachable states,  $\psi_X(x_A, x_B)$ .
- d) Express the characteristic function of the reachable output,  $\psi_Y(y_A, y_B)$ .
- e) Are the automata equivalent? Justify with a simple calculus.

## 2 Temporal Logic

a) We consider the following automaton. The property a is true on states 0 and 3.



For each of the following CTL formula, list all the states for which it holds true.

- (i) EF *a*
- (ii) EX AX a
- (iii) EF ( a AND EX NOT(a) )
- **b)** Given the transition function  $\psi_f(x, x')$  and the characteristic function  $\psi_Z(x)$  for a set Z, write a small pseudo-code which returns the characteristic function of  $\psi_{AFZ}(x)$ . It can be expressed as symbolic boolean functions, like  $\overline{x_A} x'_A \overline{x_B} x'_B + \overline{x_A} x'_A x_B x'_B$ .

expressed as symbolic boolean functions, like  $\overline{x_A}x'_A\overline{x_B}x'_B + \overline{x_A}x'_Ax_Bx'_B$ . **Hint:** To do this, simply use the classic boolean operators AND, OR, NOT and ! =. You can also use an existence selector EXISTS(a). For a given argument a, it returns the set  $\{x: \exists x', a(x,x') \text{ is true}\}$ .

**Hint:** It can be useful to reformulate AFZ as another CTL formula.