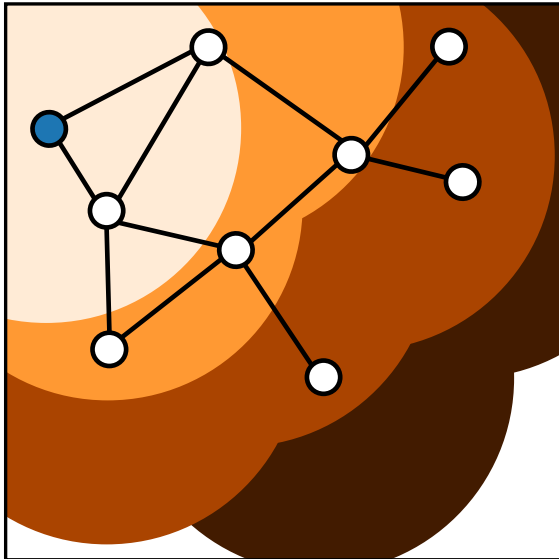


Discrete Event Systems

Verification of Finite Automata (Part 2)



Lana Josipović
Digital Systems and Design Automation Group
dynamo.ethz.ch

ETH Zurich (D-ITET)

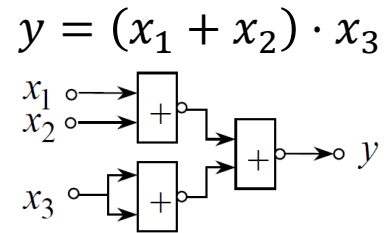
December 7, 2023

Most materials from Lothar Thiele and Romain Jacob

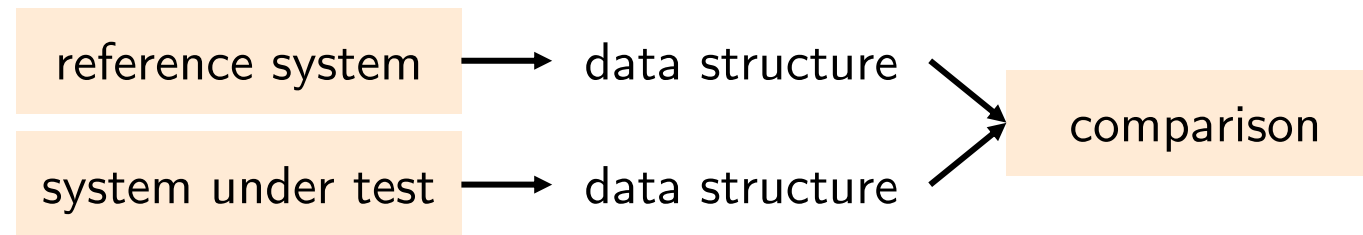
Last week in
Discrete Event Systems

Verification Scenarios

Example

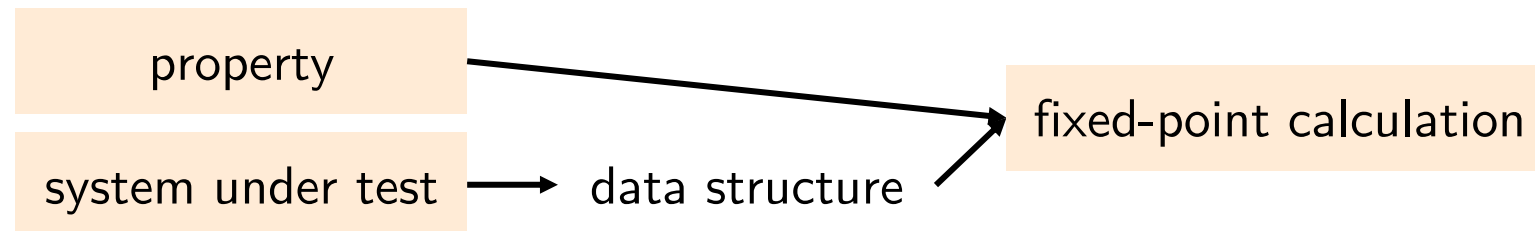


Comparison of specification and implementation



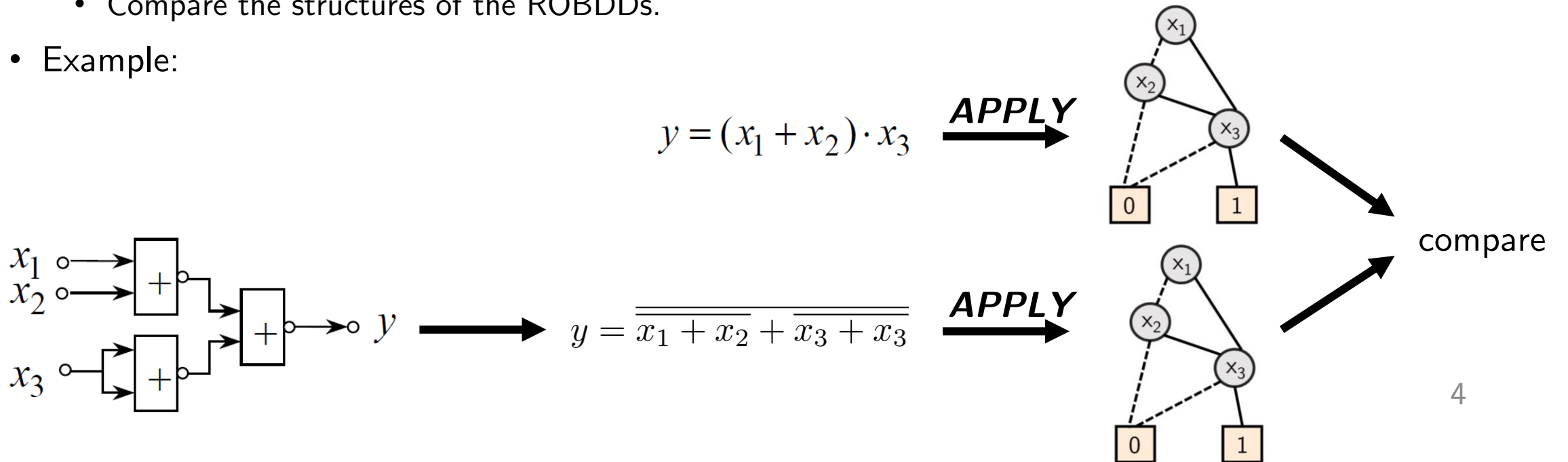
Proving properties

“The device can always be switched off.”



Comparison using BDDs

- Boolean (combinatorial) circuits: Compare specification and implementation, or compare two implementations.
- Method:
 - Representation of the two systems in ROBDDs, e.g., by applying the **APPLY** operator repeatedly.
 - Compare the structures of the ROBDDs.
- Example:



Sets and Relations

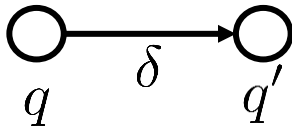
- Representation of a subset $A \subseteq E$:
 - Binary encoding $\sigma(e)$ of all elements $e \in E$
 - Subset A is represented by $a \in A \Leftrightarrow \psi_A(\sigma(a))$

characteristic function
of subset A



- Relation function: describe state transitions

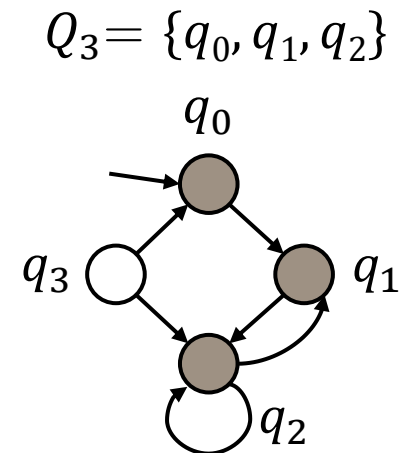
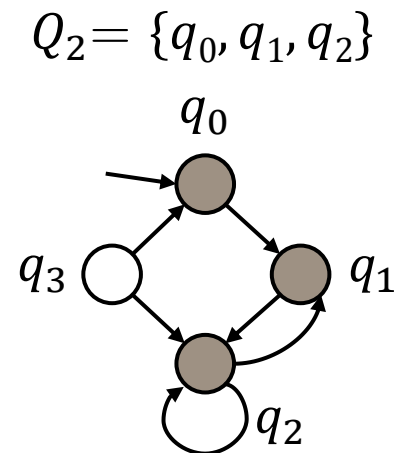
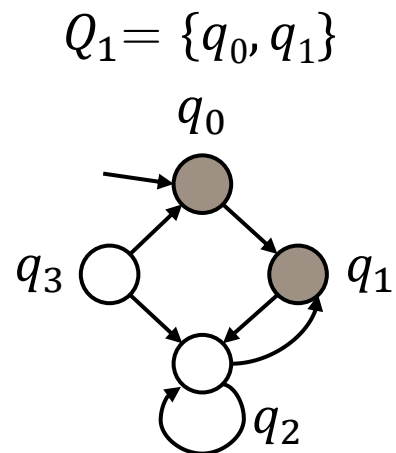
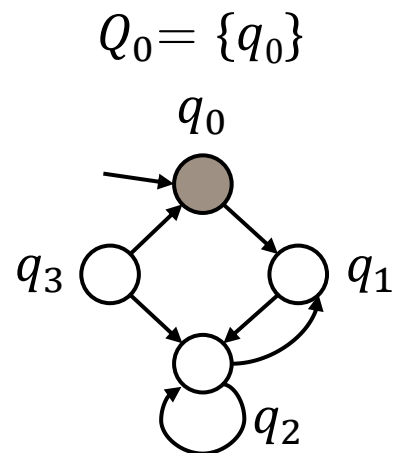
$$\psi_\delta(\sigma(q), \sigma(q')) = \psi_\delta(q, q')$$



$\sigma(e_1) = (0, 1, 0)$
 $\sigma(e_2) = (0, 0, 0)$
 $\psi_A(\sigma(e_1)) = 0$
 $\psi_A(\sigma(e_2)) = 1$

Reachability of States

- Problem: Is a state $q \in Q$ reachable by a sequence of state transitions?
- Method:
 - Represent set of states and the transformation relation as ROBDDs.
 - Use these representations to transform from one set of states to another. Set Q_i corresponds to the set of states reachable after i transitions.
 - Iterate the transformation until a fixed-point is reached, i.e., until the set of states does not change anymore (steady-state).
- Example:



Reachability of States

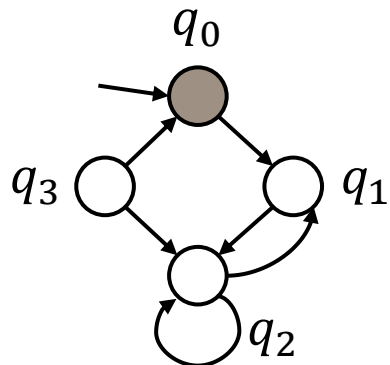
State encoding

Characteristic function: 1 if state in set, 0 otherwise

$\sigma(q)$	x_1	x_0	ψ_{Q_0}	ψ_{Q_1}	ψ_{Q_2}	ψ_{Q_3}
q_0	0	0	1	1	1	1
q_1	0	1	0	1	1	1
q_2	1	0	0	0	1	1
q_3	1	1	0	0	0	0

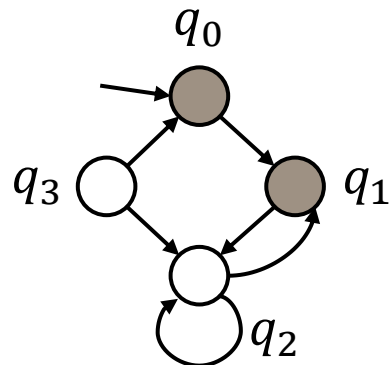
$$\psi_{Q_0}(q) = \overline{x_1} \cdot \overline{x_0}$$

$$Q_0 = \{q_0\}$$



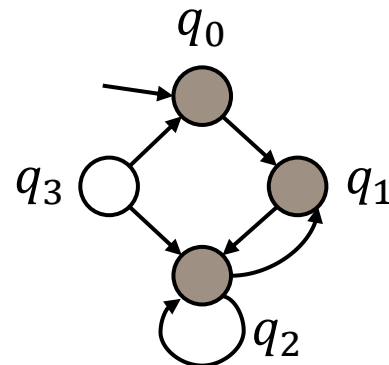
$$\psi_{Q_1}(q) = \overline{x_1}$$

$$Q_1 = \{q_0, q_1\}$$



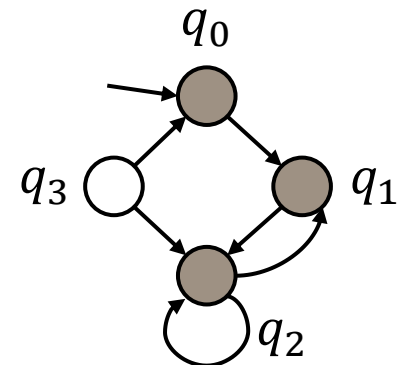
$$\psi_{Q_2}(q) = \overline{x_1} + \overline{x_0}$$

$$Q_2 = \{q_0, q_1, q_2\}$$



$$\psi_{Q_3}(q) = \overline{x_1} + \overline{x_0}$$

$$Q_3 = \{q_0, q_1, q_2\}$$



This week in
Discrete Event Systems

Efficient state representation

- Set of states as Boolean function
- Binary Decision Diagram representation

Computing reachability

- Leverage efficient state representation
- Explore successor sets of states

Today

Proving properties

- Temporal logic (CTL)
- Encoding as reachability problem

Temporal Logic

- Verify properties of a finite automaton, for example
 - Can we always reset the automaton?
 - Is every request followed by an acknowledgement?
 - Are both outputs always equivalent?

Formula	Examples
Atomic proposition	The printer is busy. The light is on.
Boolean logic	$\phi_1 + \phi_2 ; \neg\phi_1$

Temporal Logic

- Verify properties of a finite automaton, for example
 - Can we always reset the automaton?
 - Is every request followed by an acknowledgement?
 - Are both outputs always equivalent?
- Specification of the query in a formula of temporal logic.
- We use a simple form called Computation Tree Logic (CTL).
- Let us start with a minimal set of operators.
 - Any atomic proposition is a CTL formula.
 - CTL formula are constructed by composition of other CTL formula.

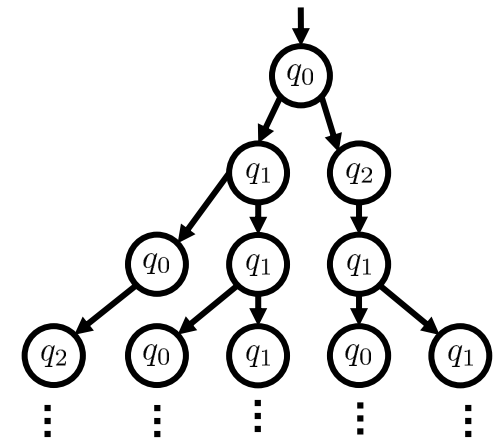
Formula	Examples
Atomic proposition	The printer is busy. The light is on.
Boolean logic	$\phi_1 + \phi_2 ; \neg\phi_1$
CTL logic	$EX \phi_1$

There exists
other logics
(e.g. LTL, CTL*)

Formulation of CTL properties

Based on atomic propositions (ϕ) and quantifiers

$A\phi$	\rightarrow « A ll ϕ »,	ϕ holds on all paths
$E\phi$	\rightarrow « E xists ϕ »,	ϕ holds on at least one path
$X\phi$	\rightarrow « N e X t ϕ »,	ϕ holds on the next state
$F\phi$	\rightarrow « F inally ϕ »,	ϕ holds at some state along the path
$G\phi$	\rightarrow « G lobally ϕ »,	ϕ holds on all states along the path
$\phi_1 U \phi_2$	\rightarrow « ϕ_1 U ntil ϕ_2 »,	ϕ_1 holds until ϕ_2 holds implies that ϕ_2 has to hold eventually



Quantifiers
over paths

Path-specific quantifiers

CTL quantifiers work in pairs: we need one of each! $\{A,E\} \{X,F,G,U\}\phi$

Formulation of CTL properties

Over paths:	Path-specific:
$A\phi \rightarrow \mathbf{A}ll \phi$	$X\phi \rightarrow \mathbf{NeX}t \phi$
$E\phi \rightarrow \mathbf{E}xists \phi$	$F\phi \rightarrow \mathbf{F}inally \phi$
	$G\phi \rightarrow \mathbf{G}lobally \phi$
	$\phi_1 U \phi_2 \rightarrow \phi_1 \mathbf{U}ntil \phi_2$

Based on atomic propositions (ϕ) and quantifiers

$A\phi$	$\rightarrow \ll \mathbf{A}ll \phi \gg,$	ϕ holds on all paths
$E\phi$	$\rightarrow \ll \mathbf{E}xists \phi \gg,$	ϕ holds on at least one path
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Quantifiers
over paths

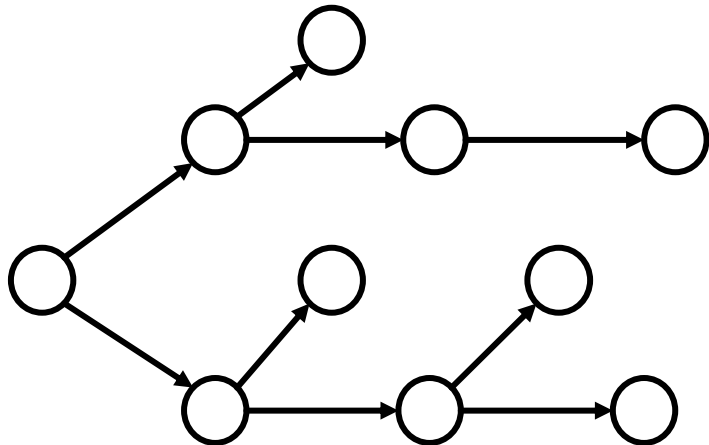
Path-specific quantifiers

CTL quantifiers work in pairs: we need one of each! $\{\mathbf{A}, \mathbf{E}\} \{\mathbf{X}, \mathbf{F}, \mathbf{G}, \mathbf{U}\} \phi$

CTL works on computation trees

Over paths:	Path-specific:
$A\phi \rightarrow$ A ll ϕ	$X\phi \rightarrow$ Ne X t ϕ
$E\phi \rightarrow$ E xists ϕ	$F\phi \rightarrow$ F inally ϕ
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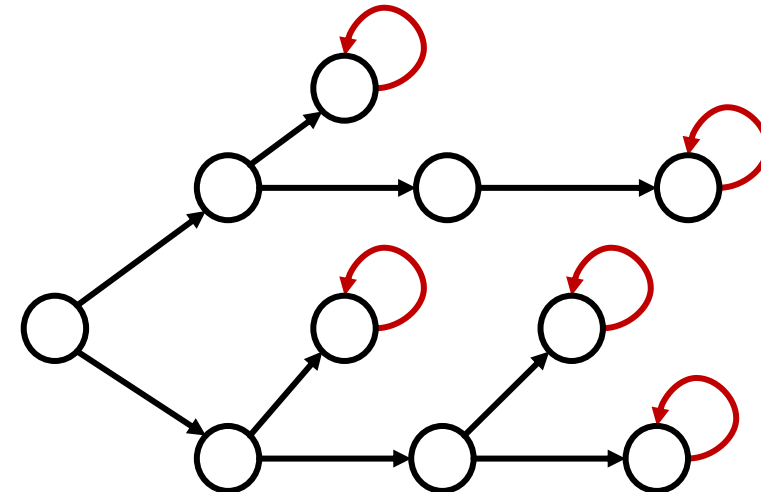
Automaton of interest



Requires fully-defined transition functions



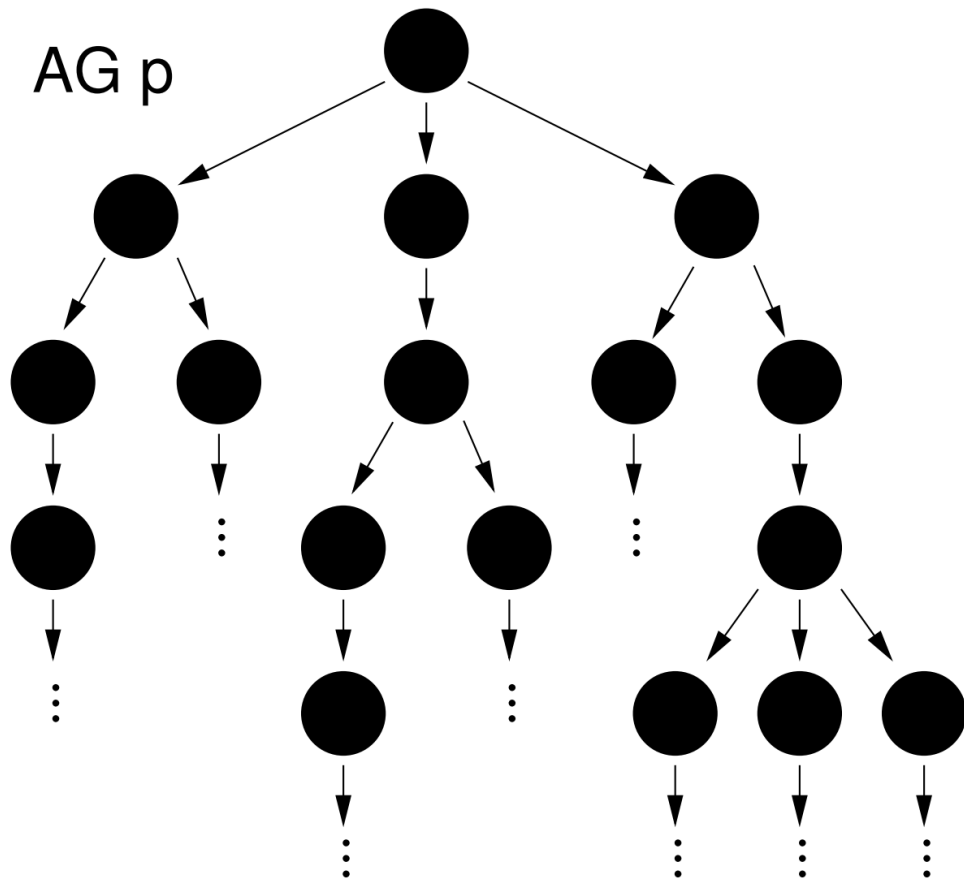
Automaton to work with



Each state has at least one successor (can be itself)

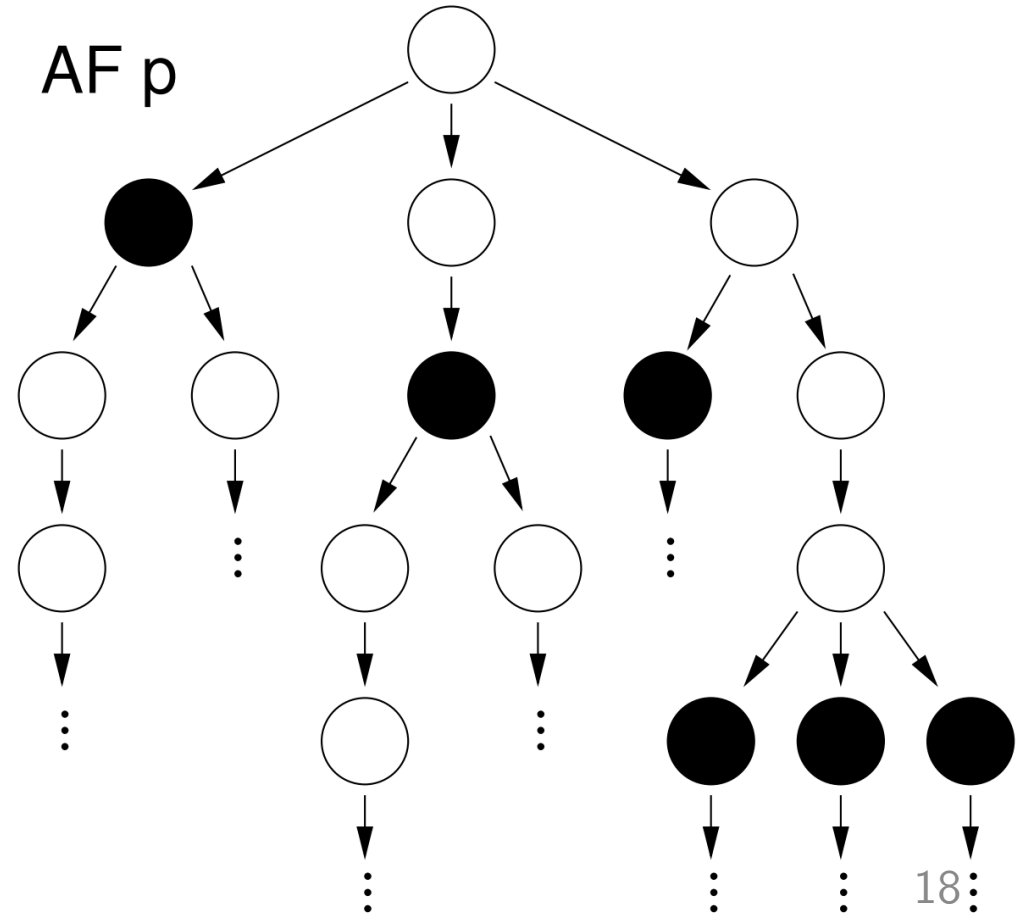
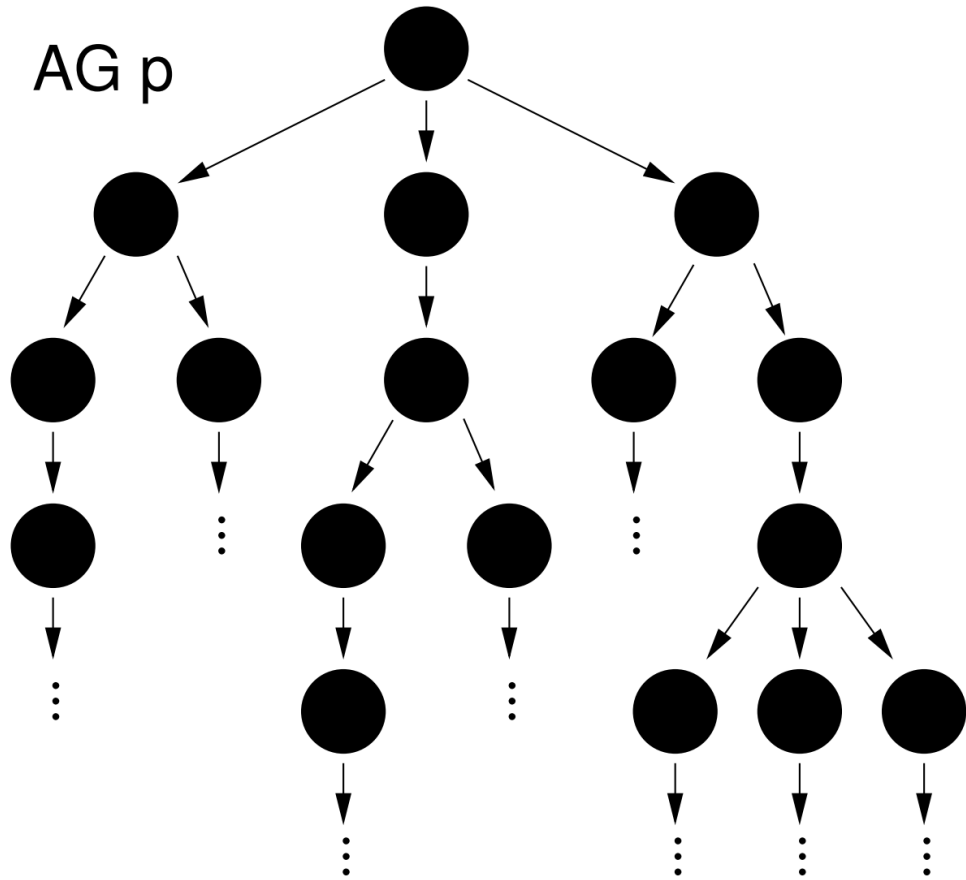
Visualizing CTL formula

Over paths:	Path-specific:
$A\phi \rightarrow$ A ll ϕ	$X\phi \rightarrow$ Ne X t ϕ
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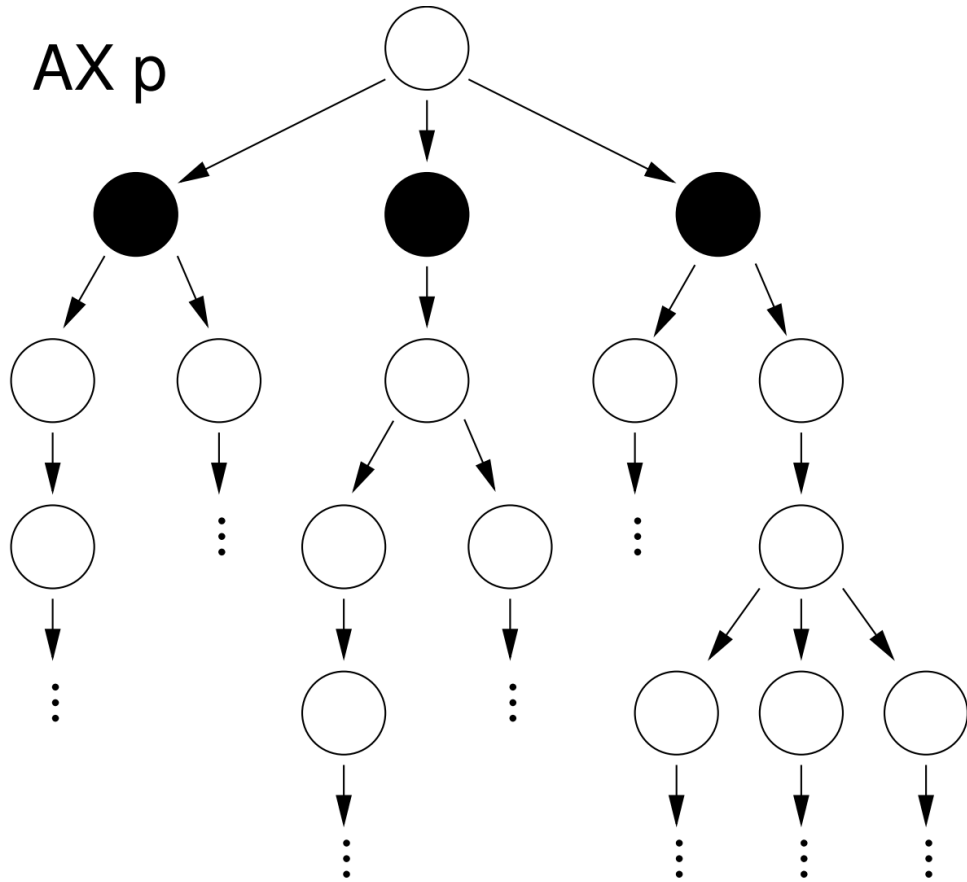
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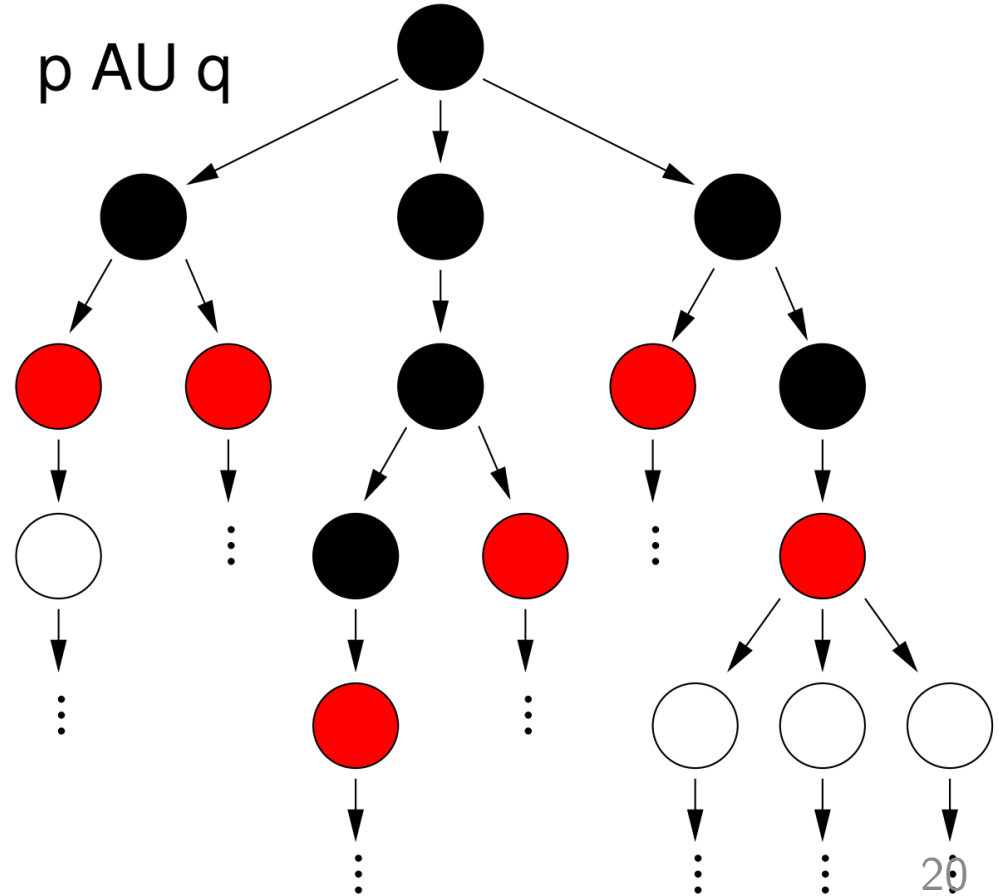
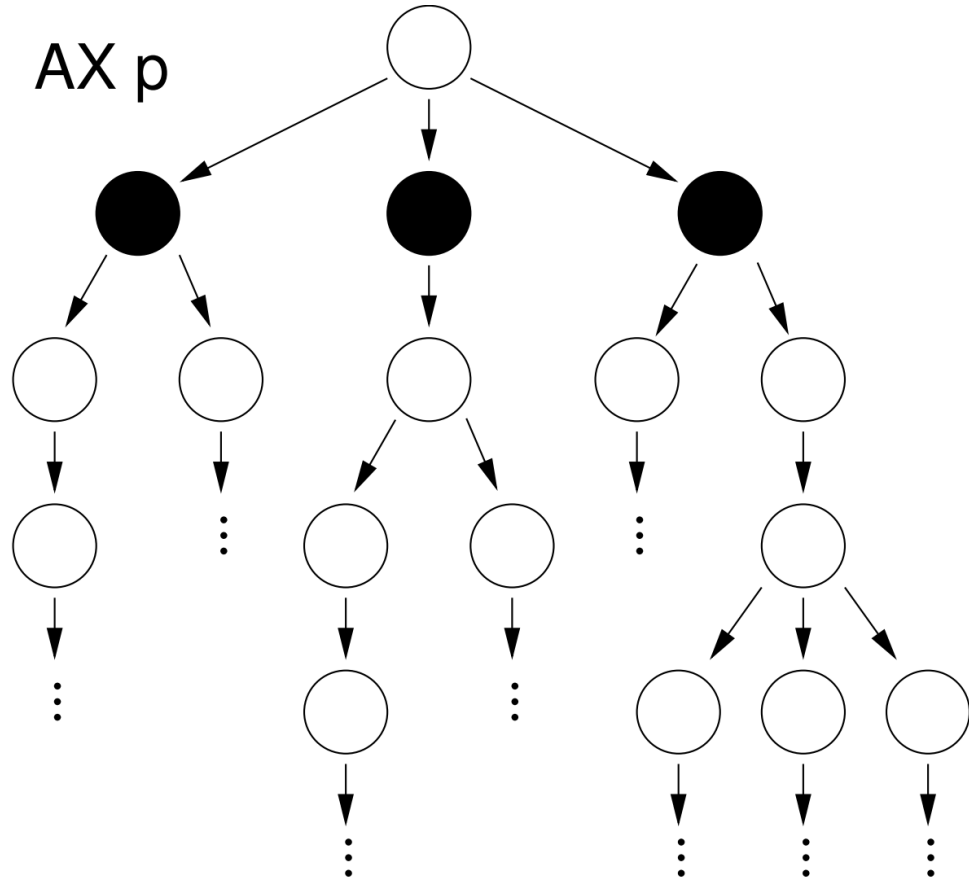
Visualizing CTL formula

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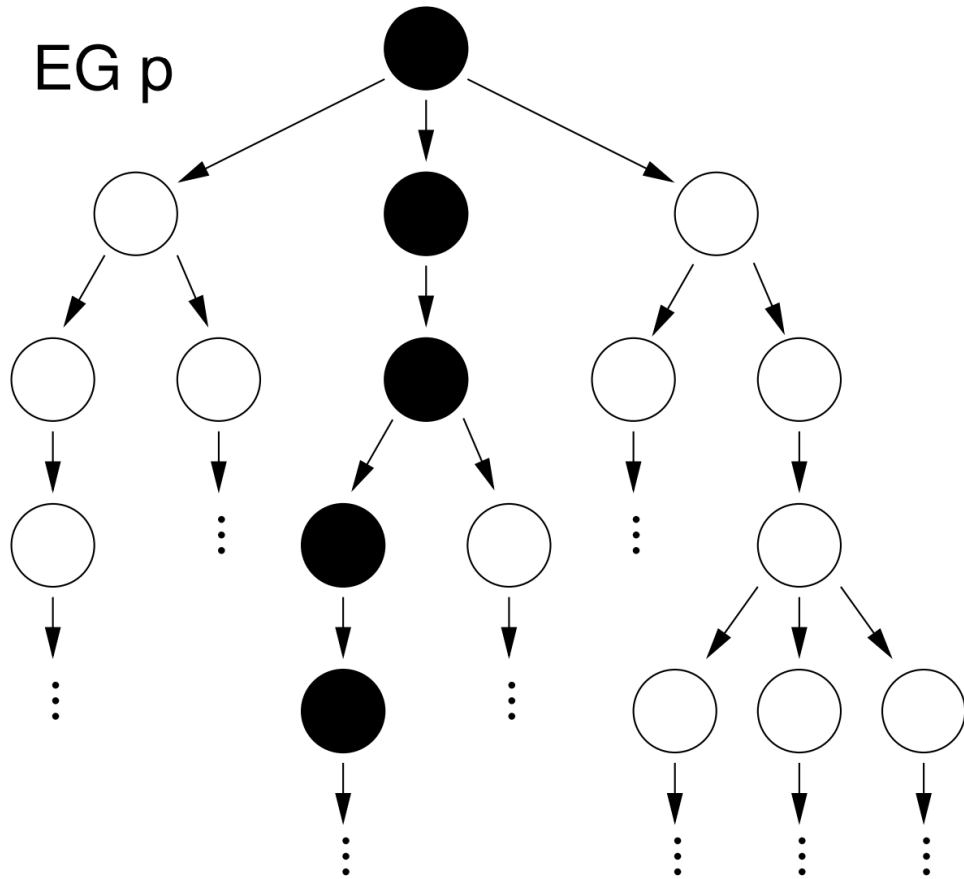
Visualizing CTL formula

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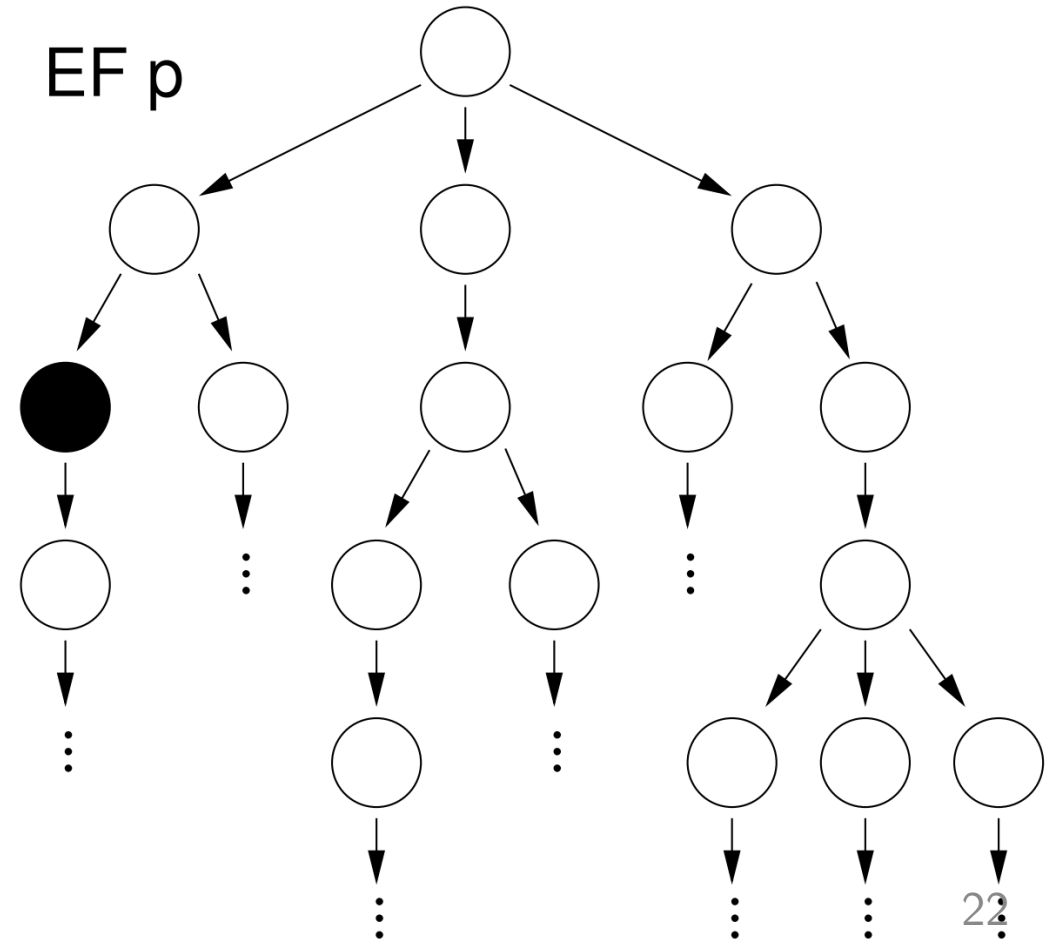
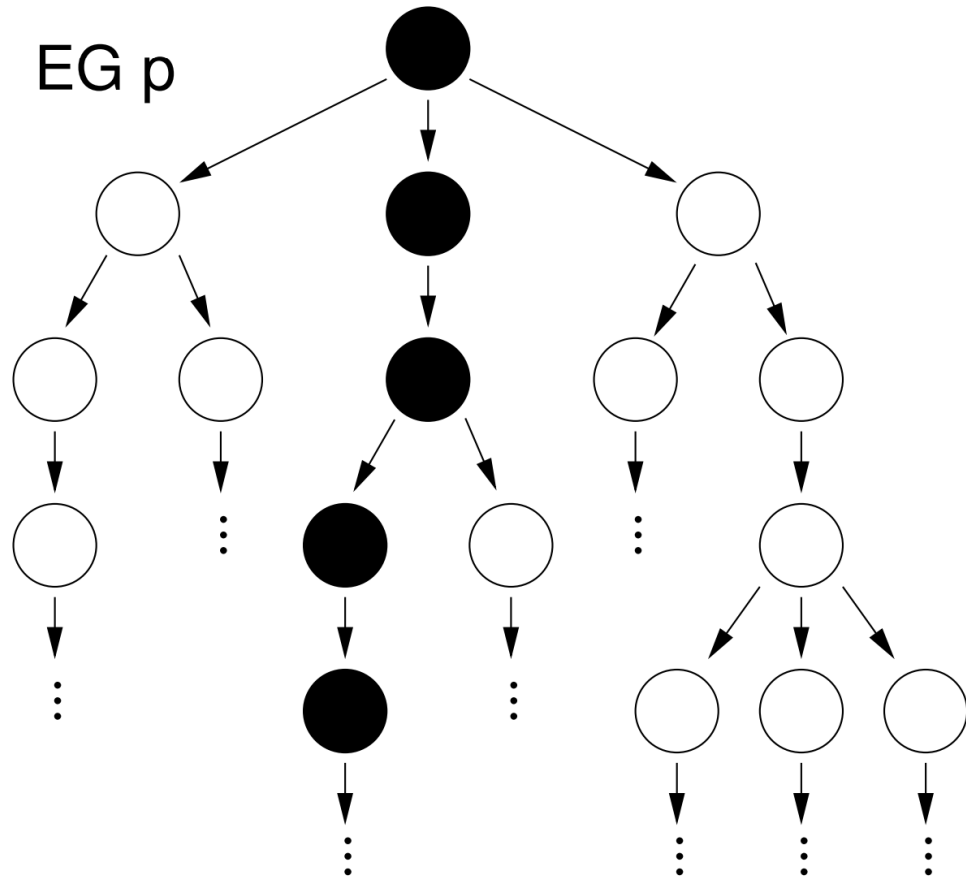
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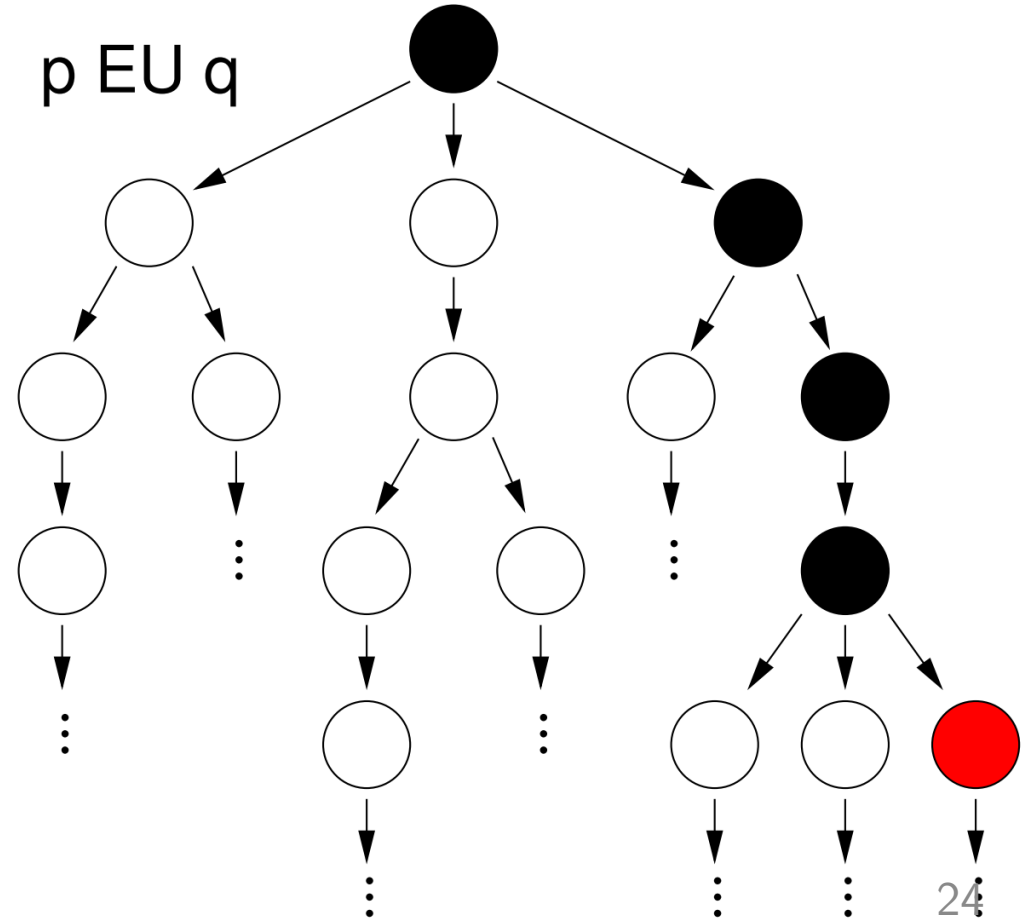
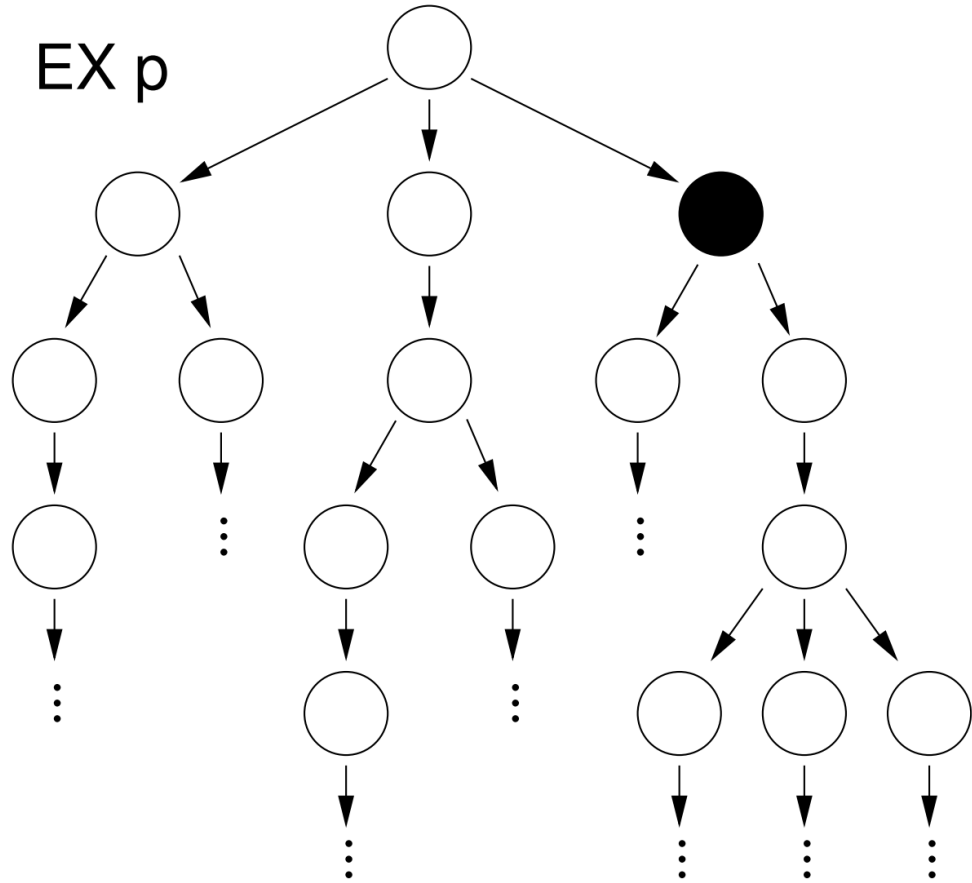
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Visualizing CTL formula

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Formulation of CTL properties

Over paths:	Path-specific:
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	$\phi_1 U \phi_2 \rightarrow \phi_1$ U ntil ϕ_2

Can be more than one pair

$$AG \phi_1 \text{ where } \phi_1 = EF \phi_2 \equiv AG EF \phi_2$$

A and F are convenient, but not necessary

E,G,X,U are sufficient to define the whole logic.

$$AF\phi \equiv \neg EG(\neg\phi)$$

$$AG\phi \equiv \neg EF(\neg\phi)$$

$$AX\phi \equiv \neg EX(\neg\phi)$$

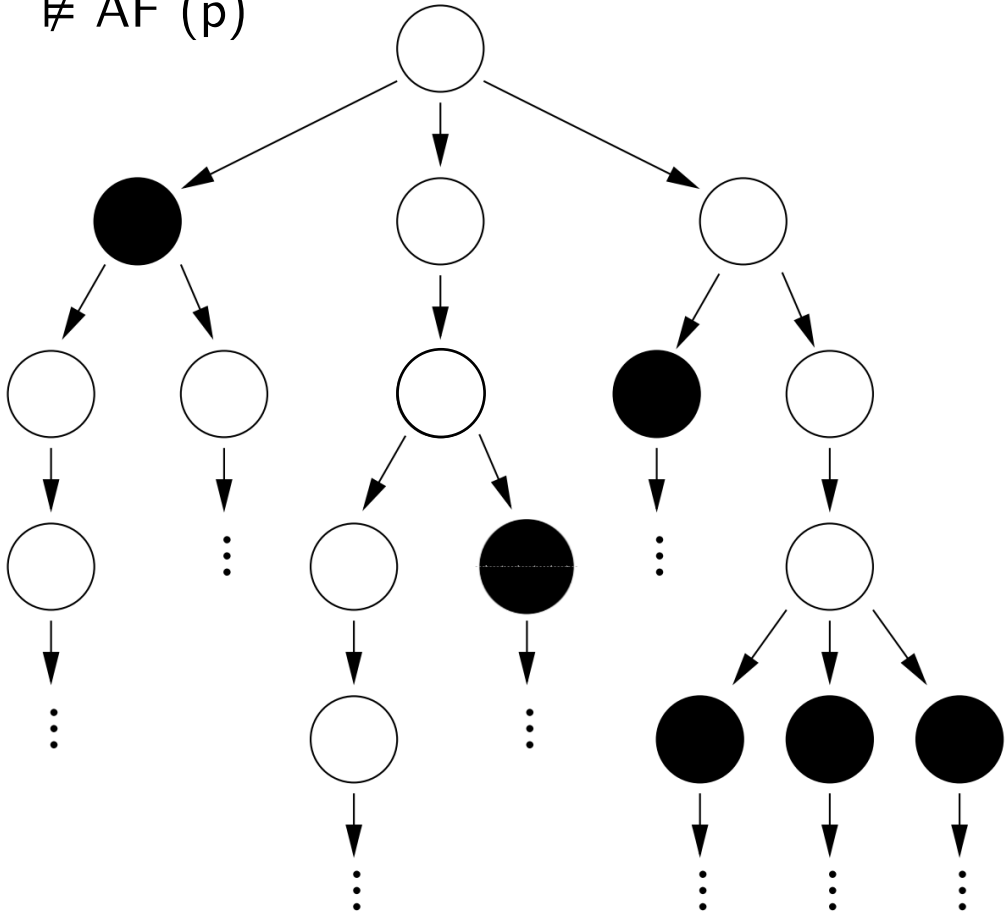
$$EF\phi \equiv \text{true} EU\phi$$

No need to know that one $\blacktriangleright \phi_1 AU \phi_2 \equiv \neg([(\neg\phi_1)EU\neg(\phi_1 + \phi_2)] + EG(\neg\phi_2))$

Intuition for “ $AF p = \neg EG (\neg p)$ ”

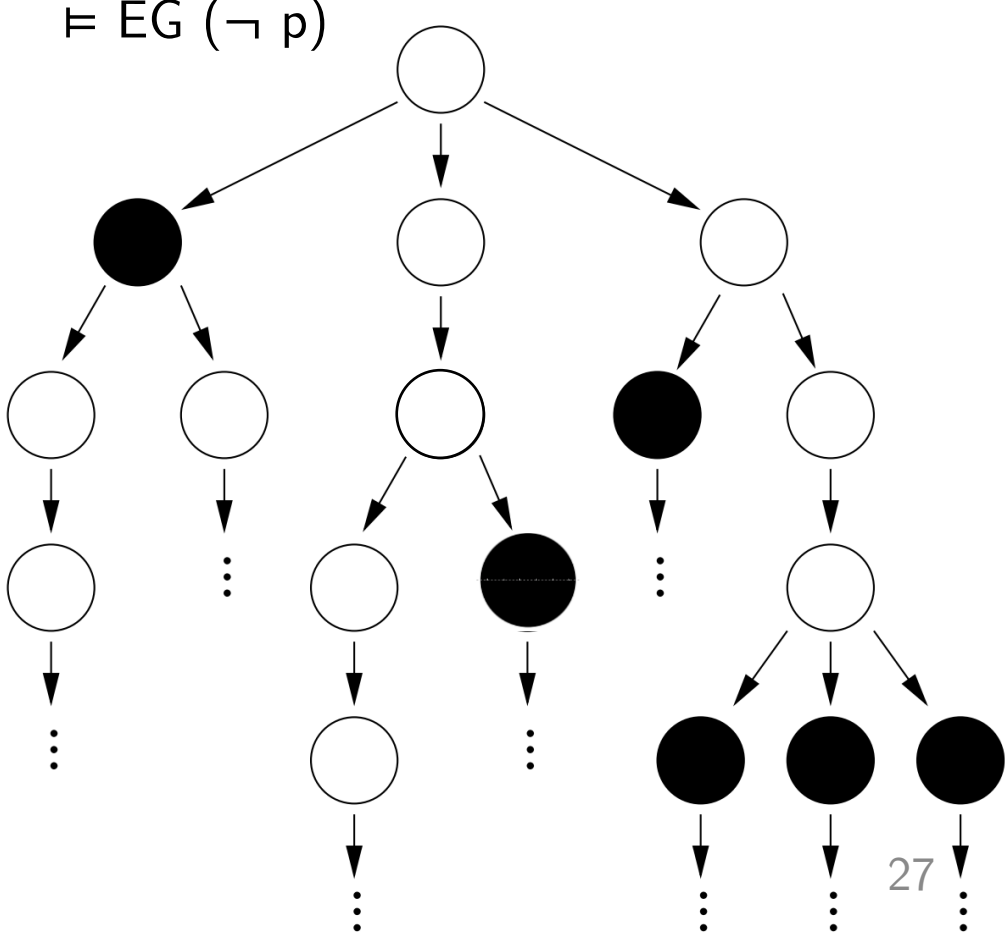
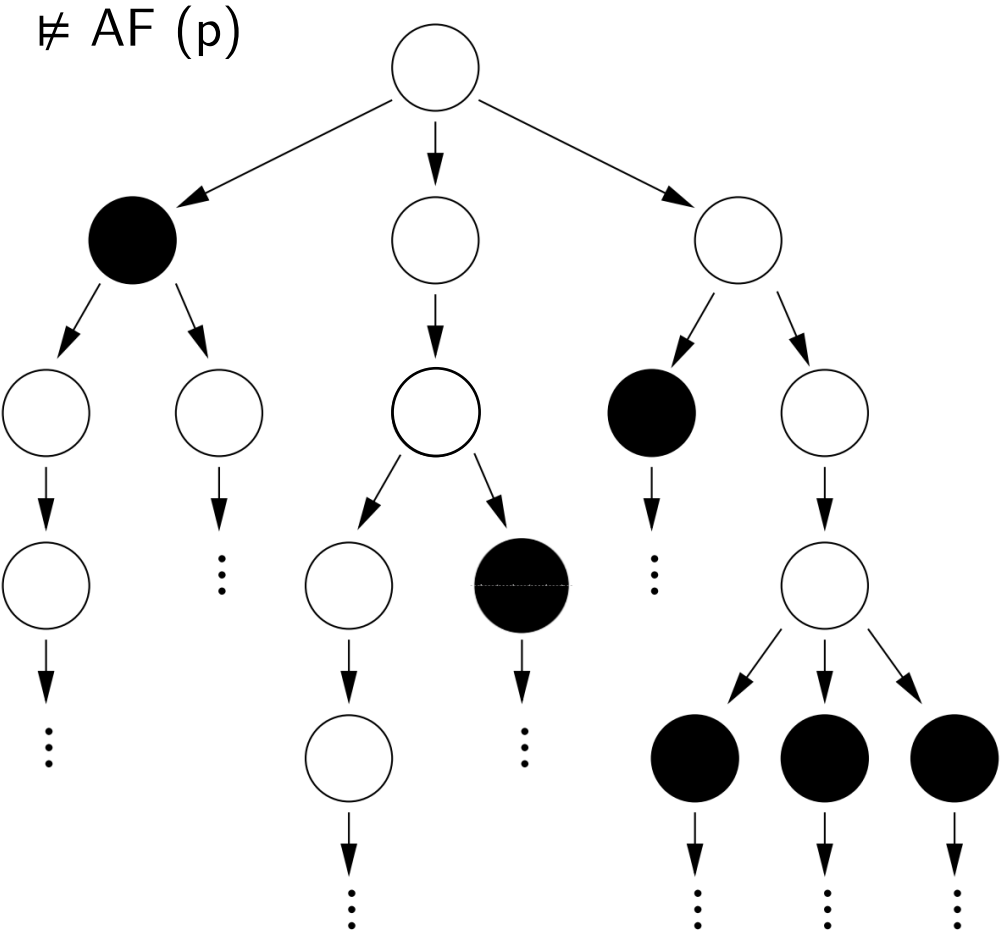
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$\neq AF(p)$



Over paths:	Path-specific:
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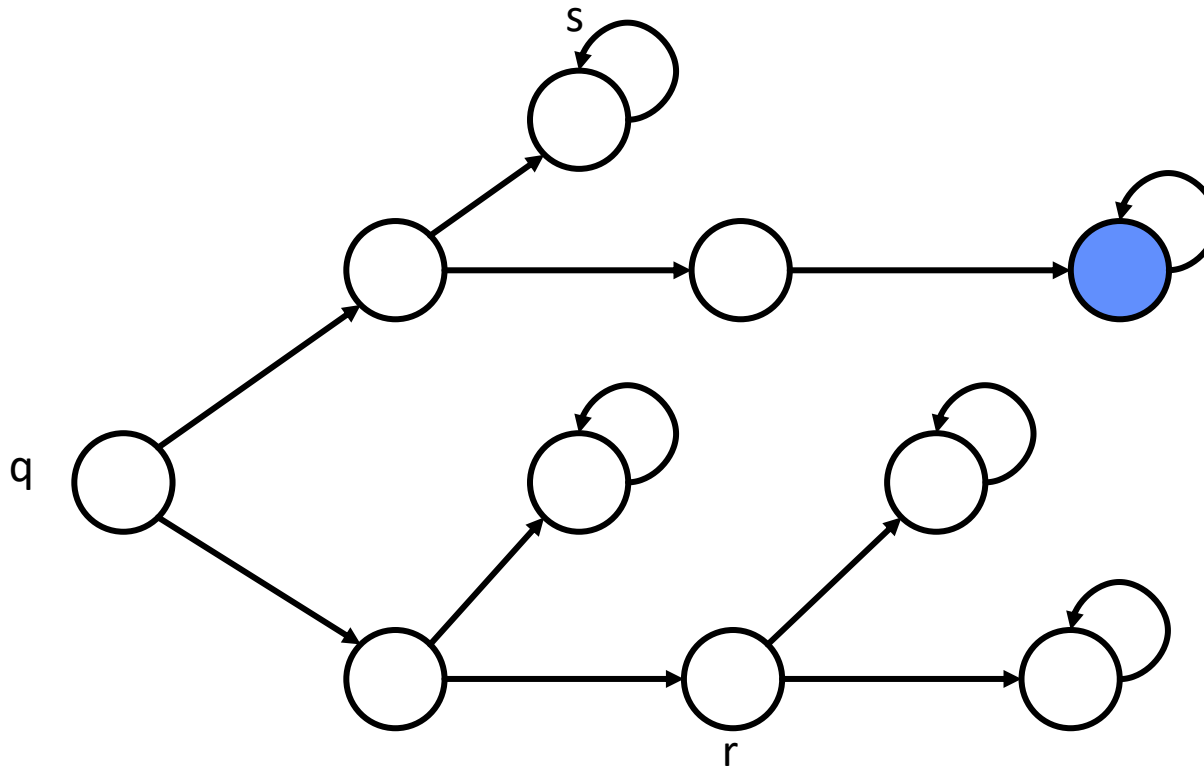
Intuition for “ $AF p = \neg EG (\neg p)$ ”



Evaluating a CTL formula

$EF \phi$: “There exists a path along which at some state ϕ holds.”

Over paths:	Path-specific:
$A\phi \rightarrow$ All ϕ	$X\phi \rightarrow$ NeXt ϕ
$E\phi \rightarrow$ Exists ϕ	$F\phi \rightarrow$ Finally ϕ
	$G\phi \rightarrow$ Globally ϕ
	$\phi_1 U \phi_2 \rightarrow \phi_1$ Until ϕ_2



$\bullet \models \phi$

$q \models EF \phi$

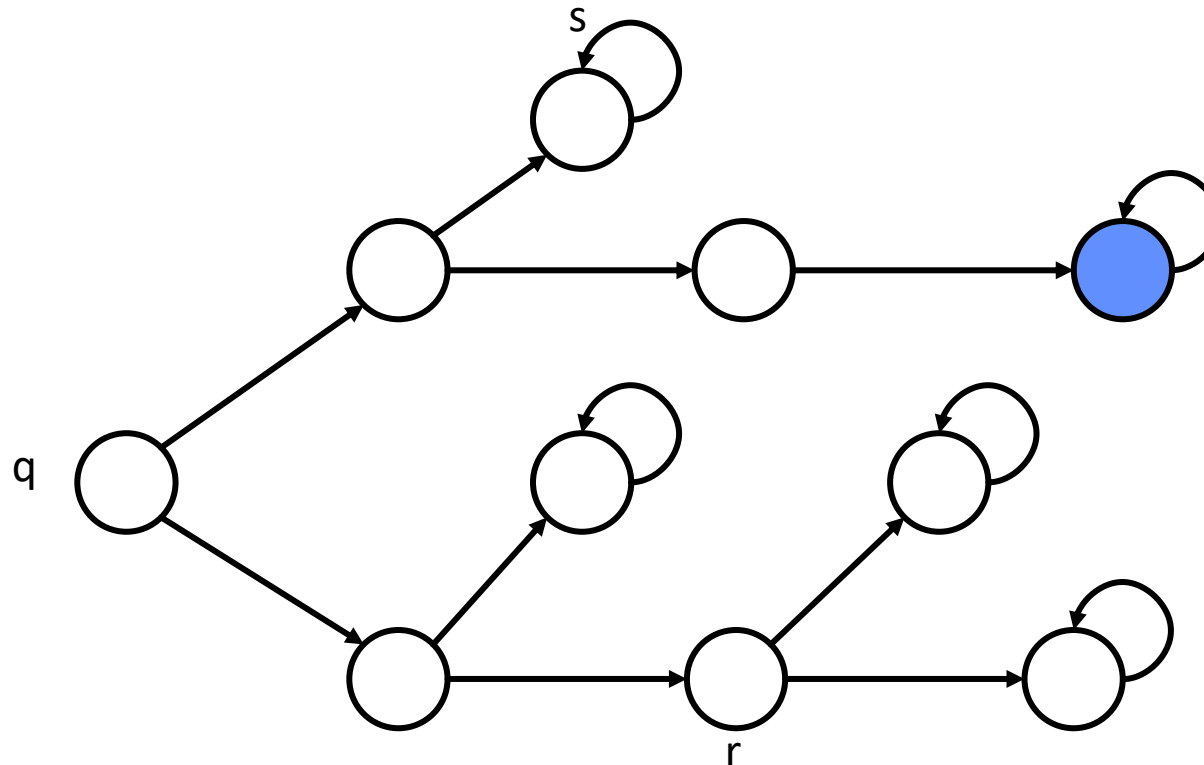
$r \models ?$

$s \models ?$

Evaluating a CTL formula

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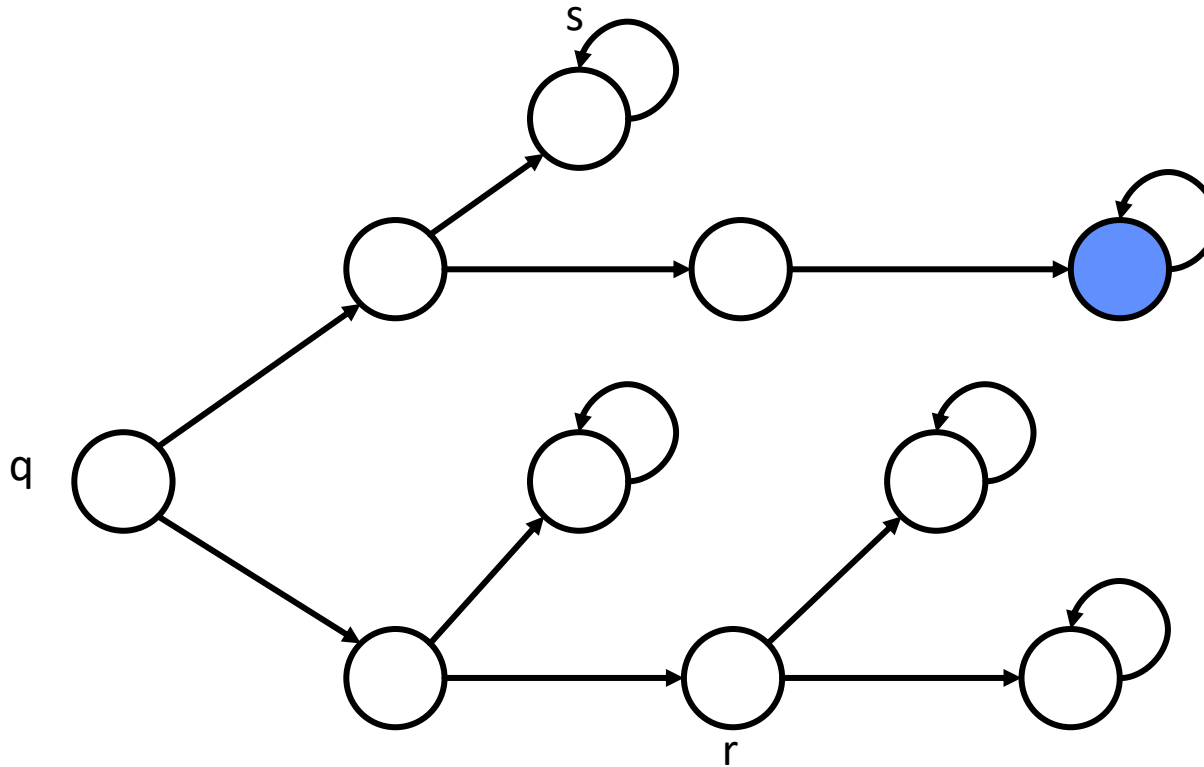
$r \not\models EF \phi$

$s \models ?$

Evaluating a CTL formula

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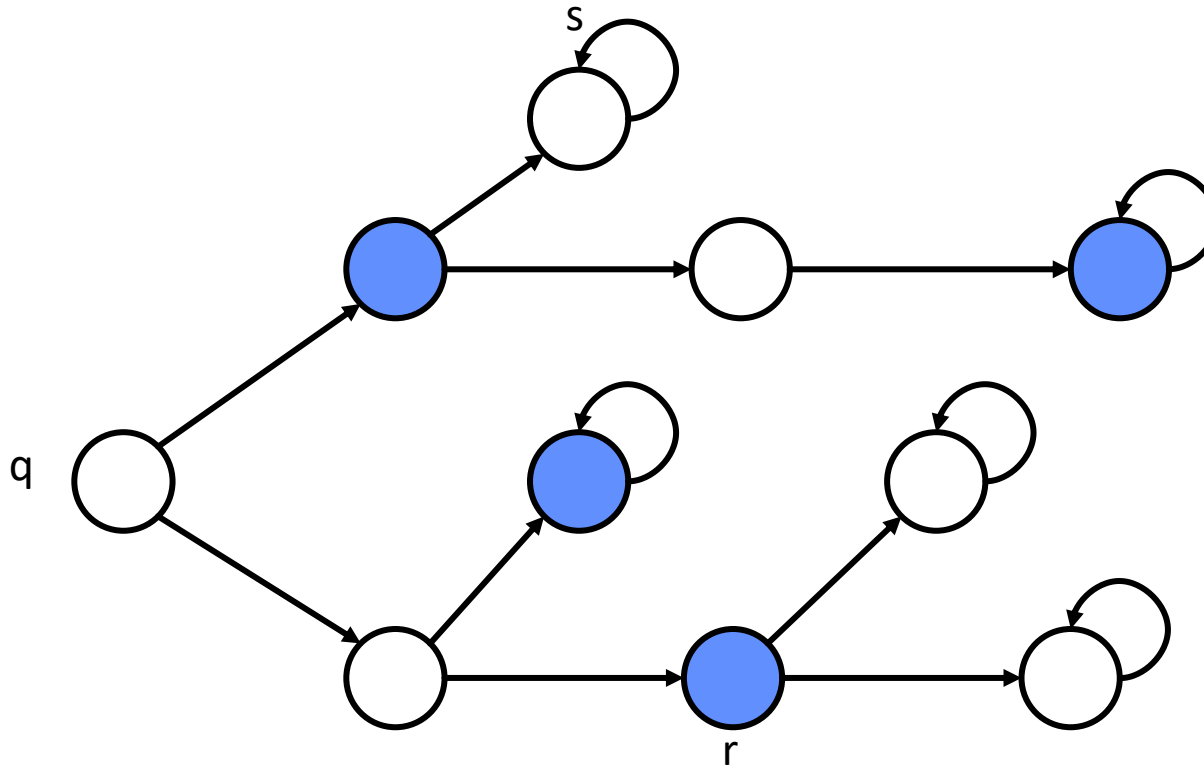
$r \not\models EF \phi$

$s \not\models EF \phi$

Evaluating a CTL formula

$AF \phi$: “On all paths,
at some state ϕ holds.”

Over paths:	Path-specific:
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$\bullet \models \phi$

$q \models AF \phi$

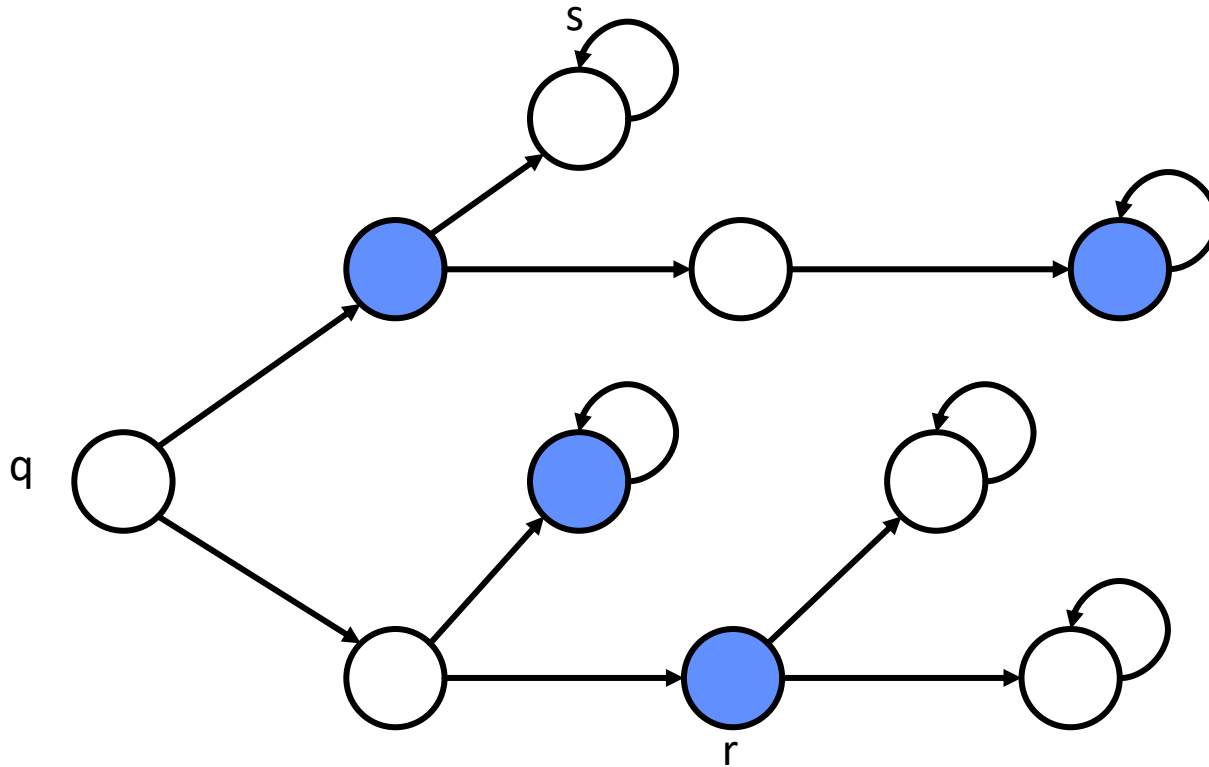
$r \models ?$

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Evaluating a CTL formula

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$q \models AF \phi$

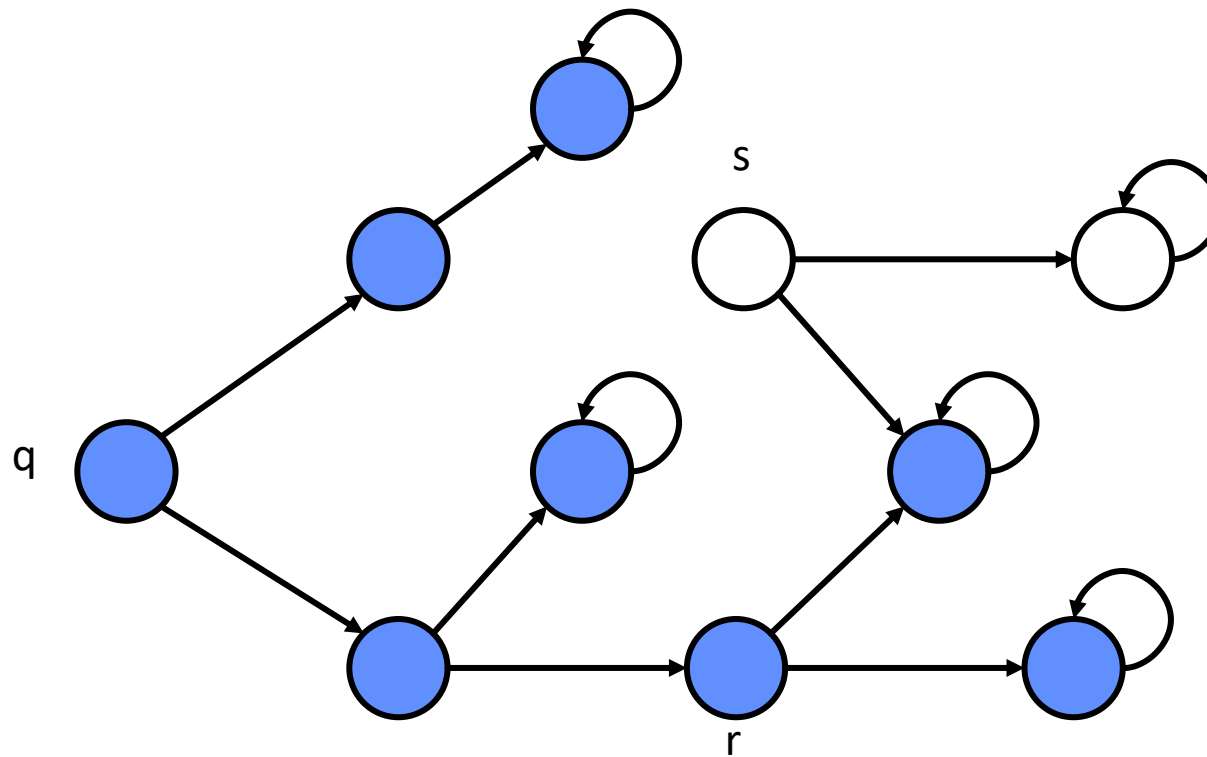
$r \models AF \phi$

$s \models ?$

Evaluating a CTL formula

$AG \phi$: “On all paths, for all states ϕ holds.”

Over paths:	Path-specific:
$A\phi \rightarrow$ All ϕ	$X\phi \rightarrow$ NeXt ϕ
$E\phi \rightarrow$ Exists ϕ	$F\phi \rightarrow$ Finally ϕ
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	$\phi_1 U \phi_2 \rightarrow \phi_1$ Until ϕ_2



$\bullet \models \phi$

$q \models AG \phi$

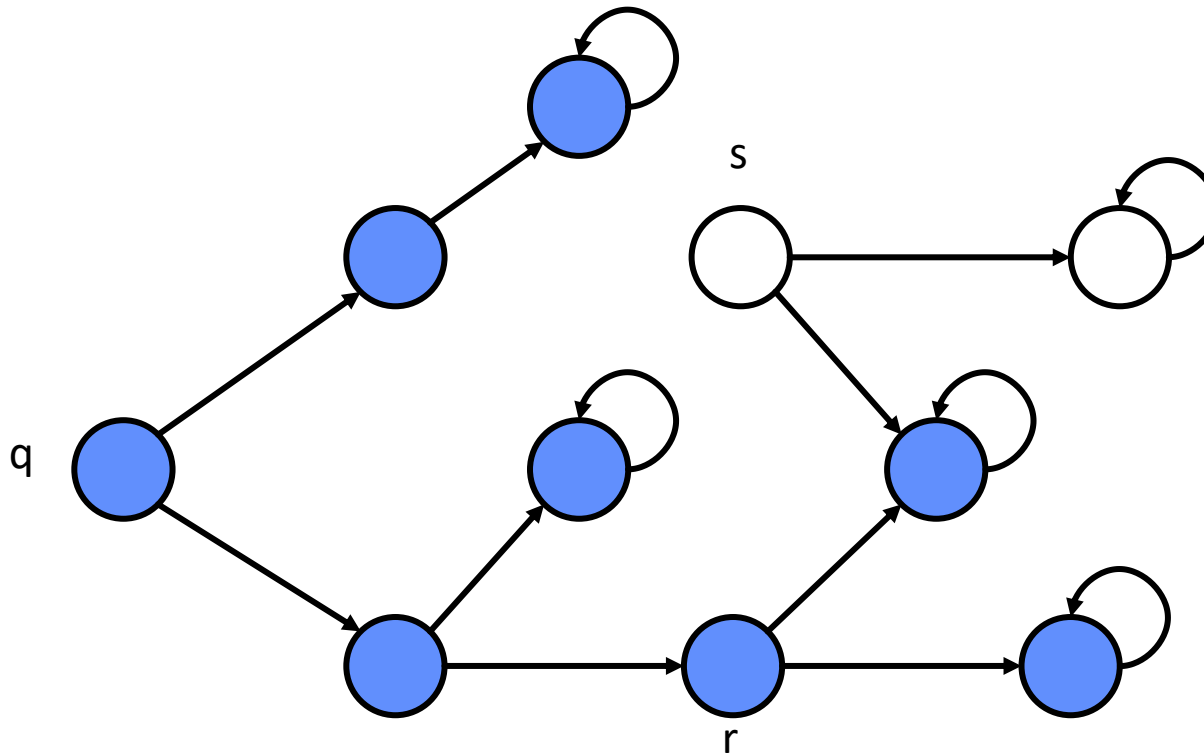
$r \models ?$

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Evaluating a CTL formula

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$\bullet \models \phi$

$q \models AG \phi$

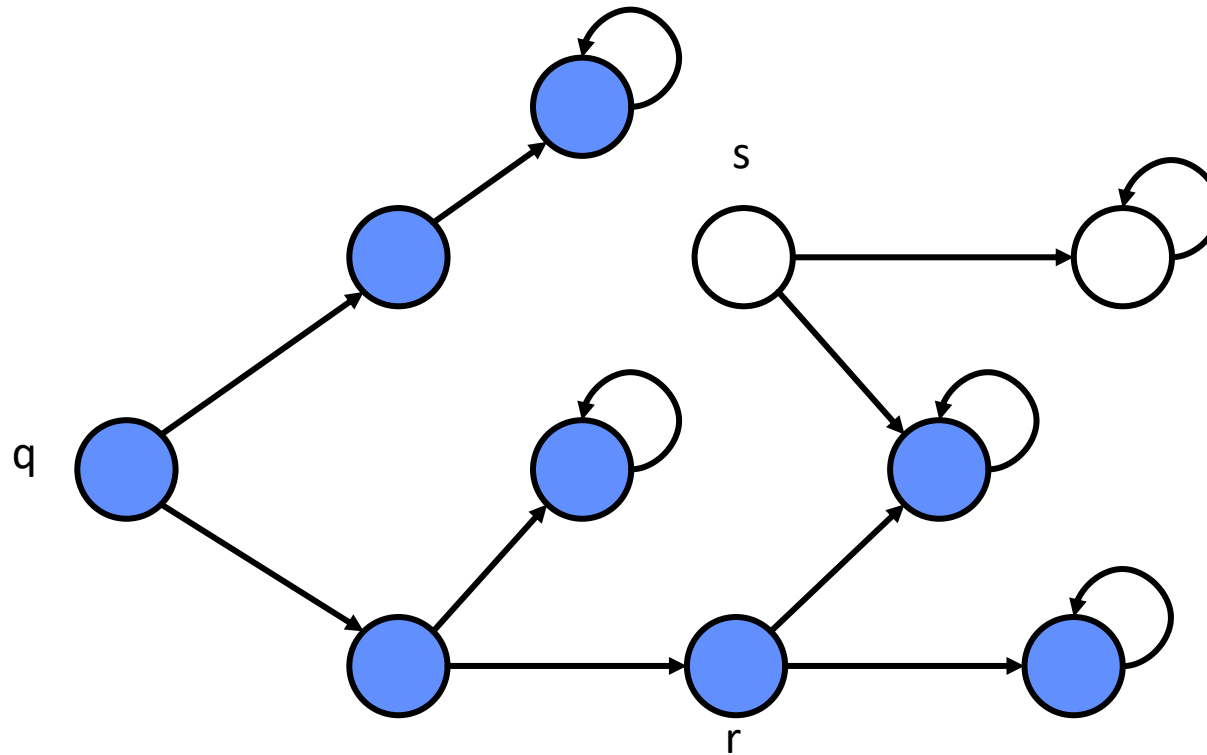
$r \models AG \phi$

$s \models ?$

Evaluating a CTL formula

$AG \phi$: “On all paths, for all states ϕ holds.”

Over paths:	Path-specific:
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$\bullet \models \phi$

$q \models AG \phi$

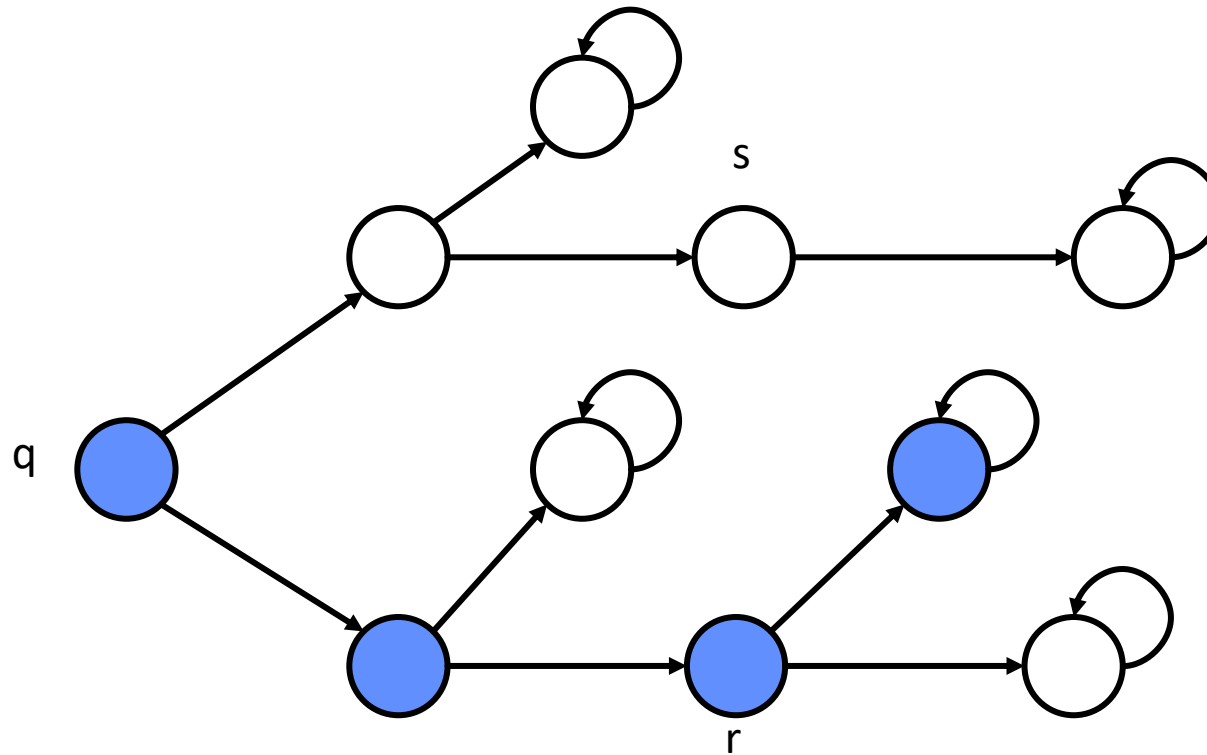
$r \models AG \phi$

$s \not\models AG \phi$

Evaluating a CTL formula

EG ϕ : “There exists a path along which for all states ϕ holds.”

Over paths:	Path-specific:
$A\phi \rightarrow$ All ϕ	$X\phi \rightarrow$ Ne X t ϕ
$E\phi \rightarrow$ E xists ϕ	$F\phi \rightarrow$ F inally ϕ
	$G\phi \rightarrow$ G lobally ϕ
	$\phi_1 U \phi_2 \rightarrow \phi_1$ U ntil ϕ_2



● $\models \phi$

$q \models EG \phi$

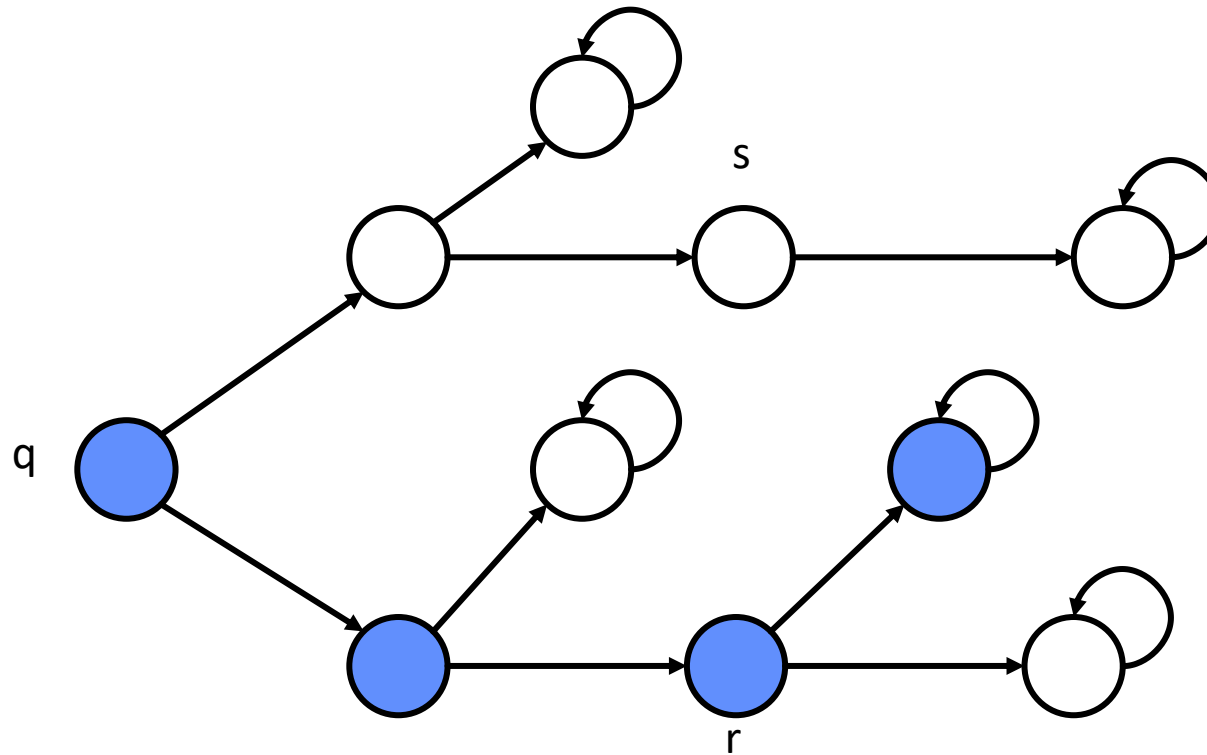
$r \models ?$

$s \models ?$

Evaluating a CTL formula

EG ϕ : “**T**here exists a path along which **f**or all states ϕ holds.”

Over paths:	Path-specific:
$A\phi \rightarrow$ A ll ϕ	$X\phi \rightarrow$ Ne X t ϕ
$E\phi \rightarrow$ E xists ϕ	$F\phi \rightarrow$ F inally ϕ
	$G\phi \rightarrow$ G lobally ϕ
	$\phi_1 U \phi_2 \rightarrow \phi_1$ U ntil ϕ_2



● $\models \phi$

q $\models EG \phi$

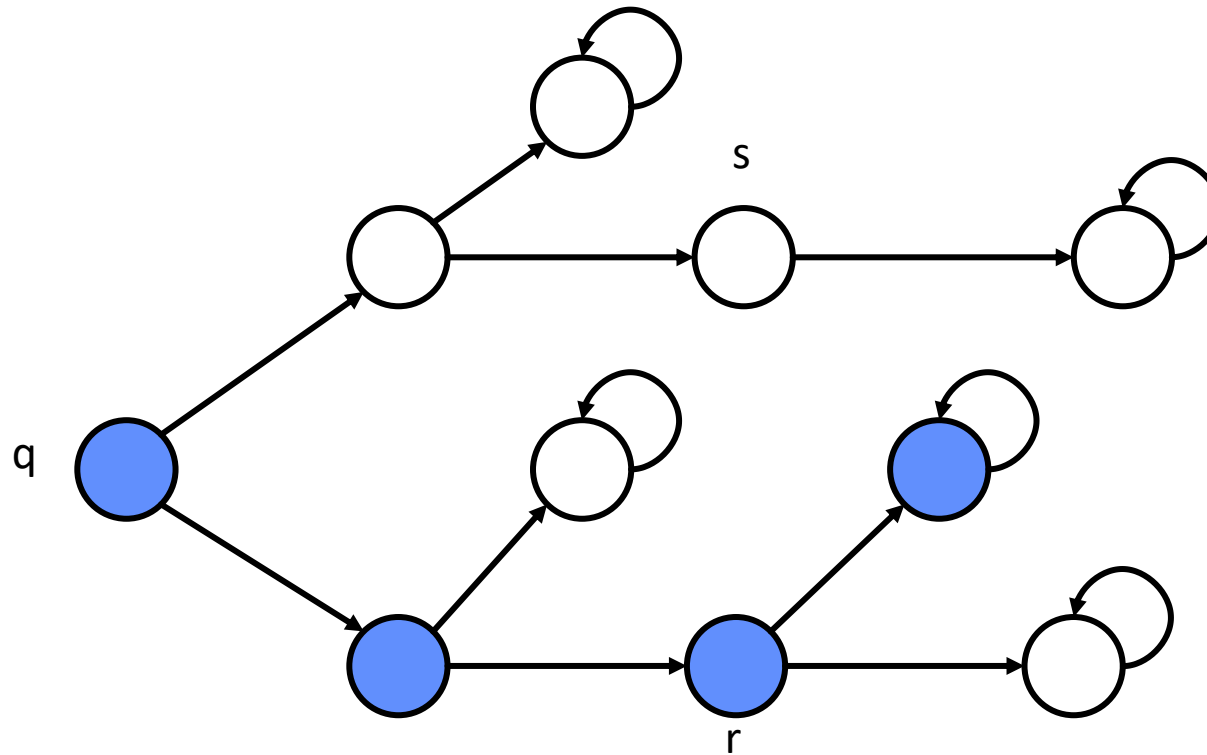
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Evaluating a CTL formula

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Over paths:	Path-specific:
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	$\phi_1 U \phi_2 \rightarrow \phi_1$ U ntil ϕ_2



$\bullet \models \phi$

$q \models EG \phi$

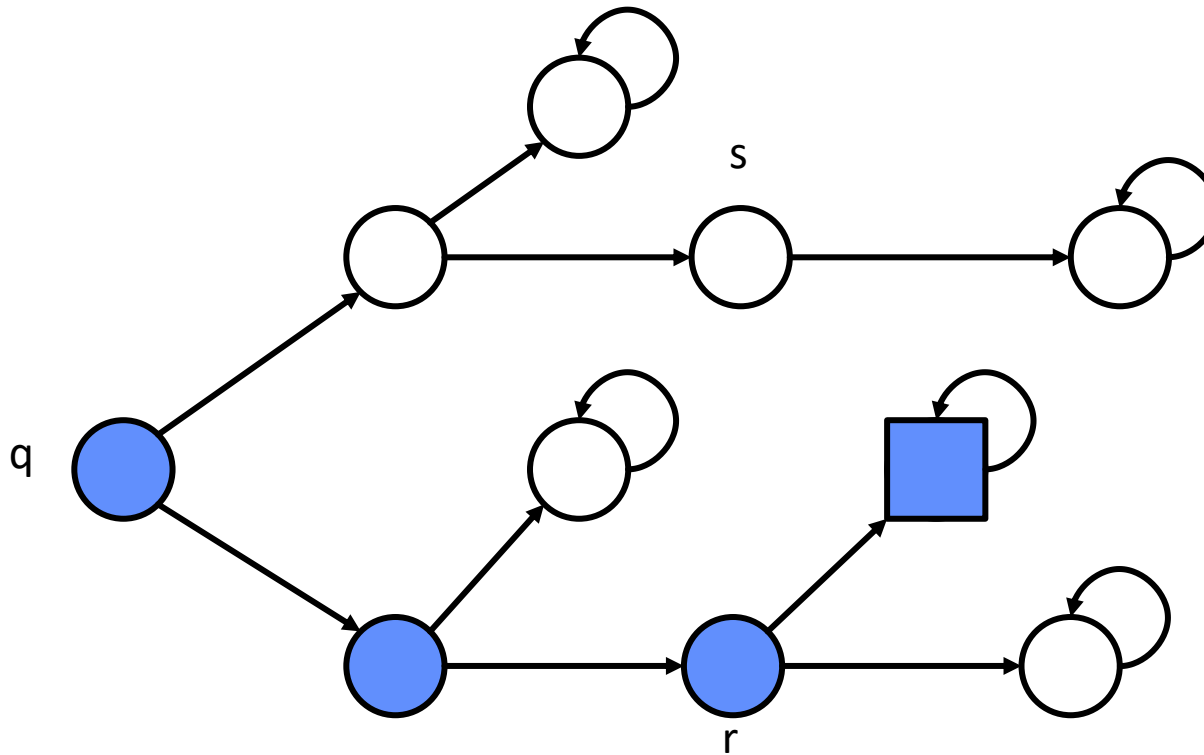
$r \models EG \phi$

$s \not\models EG \phi$

Evaluating a CTL formula

$\phi EU \Psi$: “There exists a path along which ϕ holds until Ψ holds.”

Over paths:	Path-specific:
$A\phi \rightarrow$ All ϕ	$X\phi \rightarrow$ NeXt ϕ
$E\phi \rightarrow$ Exists ϕ	$F\phi \rightarrow$ Finally ϕ
	$G\phi \rightarrow$ Globally ϕ
	$\phi_1 U \phi_2 \rightarrow \phi_1$ Until ϕ_2



■ $\models \Psi$

● $\models \phi$

q $\models \phi EU \Psi$

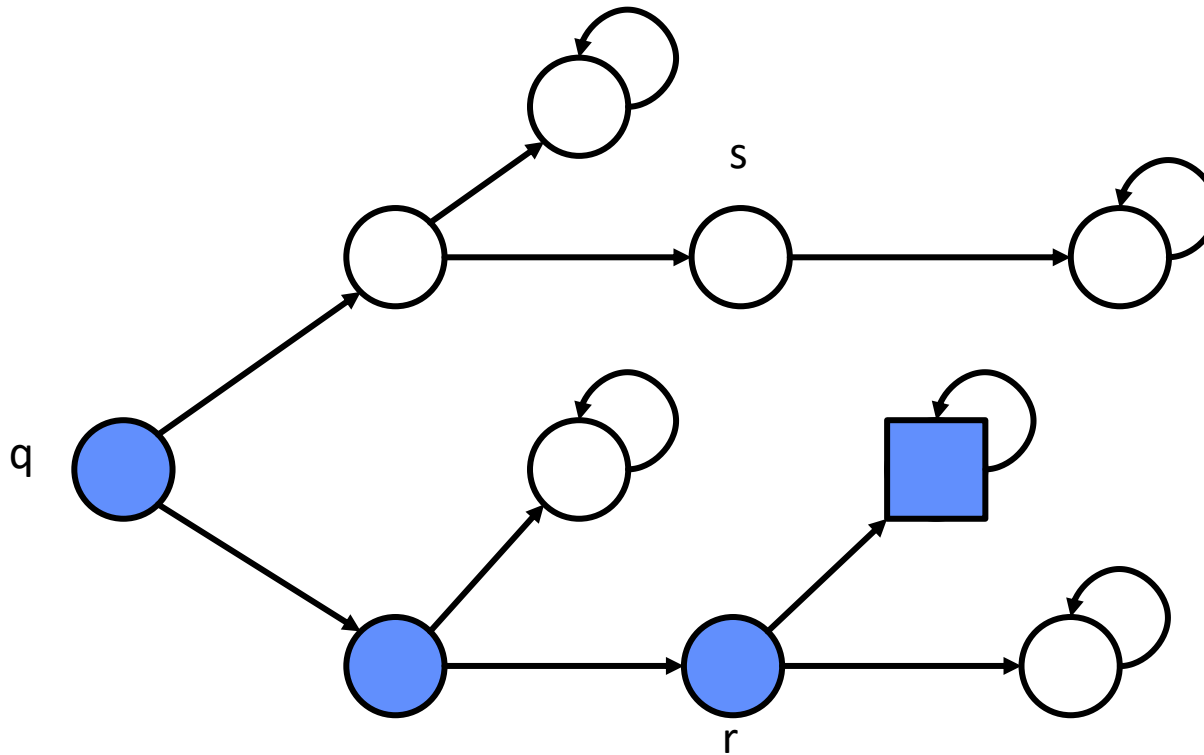
r $\models ?$

s $\models ?$

Evaluating a CTL formula

$\phi EU \Psi$: “There exists a path along which ϕ holds until Ψ holds.”

Over paths:	Path-specific:
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$E\phi \rightarrow$ Exists ϕ	$F\phi \rightarrow$ Finally ϕ
	$G\phi \rightarrow$ Globally ϕ
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■ $\models \Psi$

● $\models \phi$

q $\models \phi EU \Psi$

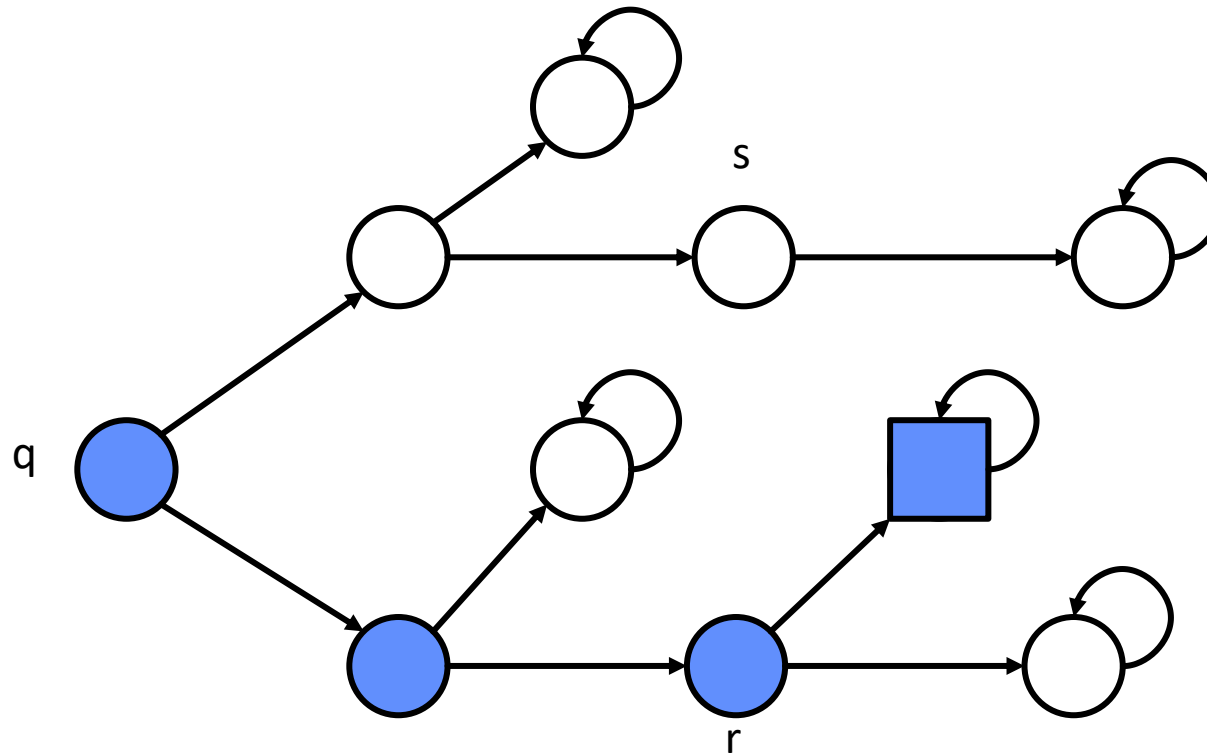
r $\models \phi EU \Psi$

s $\models ?$

Evaluating a CTL formula

$\phi EU \Psi$: “There exists a path along which ϕ holds until Ψ holds.”

Over paths:	Path-specific:
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	$\phi_1 U \phi_2 \rightarrow \phi_1$ Until ϕ_2



■ $\models \Psi$

● $\models \phi$

q $\models \phi EU \Psi$

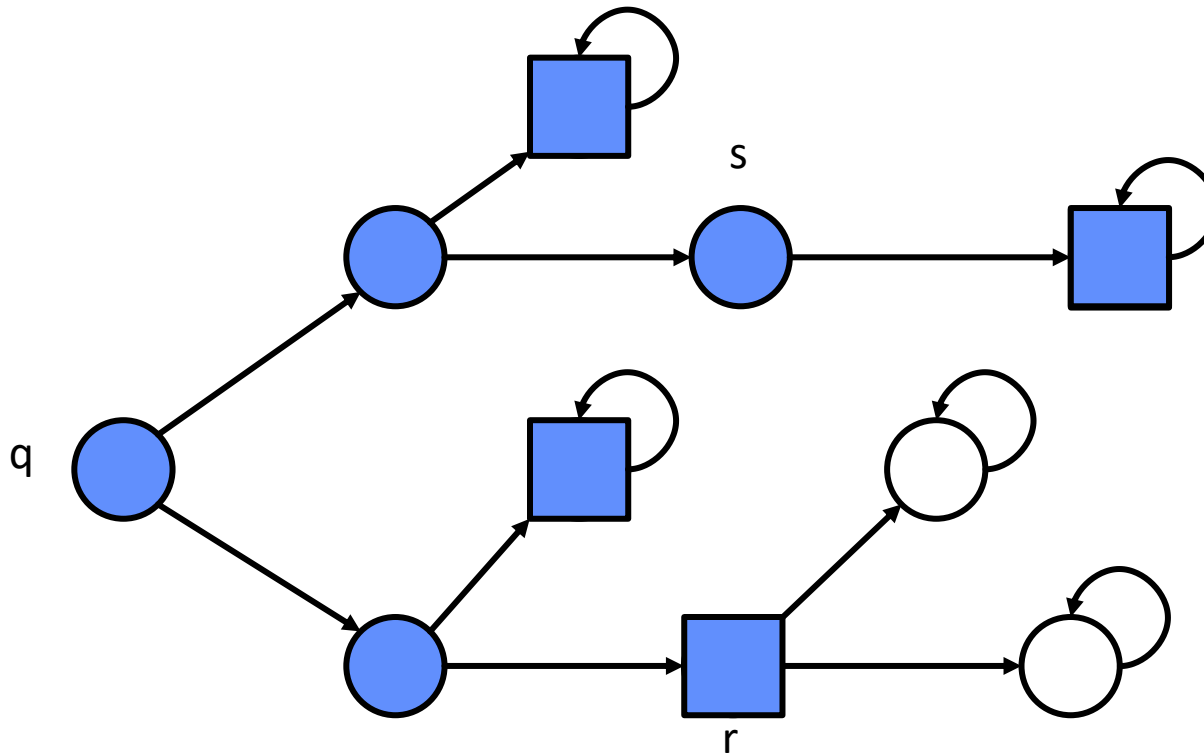
r $\models \phi EU \Psi$

s $\not\models \phi EU \Psi$

Evaluating a CTL formula

$\phi AU \Psi$: “On all paths,
 ϕ holds until Ψ holds.”

Over paths:	Path-specific:
$A\phi \rightarrow$ All ϕ	$X\phi \rightarrow$ NeXt ϕ
$E\phi \rightarrow$ Exists ϕ	$F\phi \rightarrow$ Finally ϕ
	$G\phi \rightarrow$ Globally ϕ
	$\phi_1 U \phi_2 \rightarrow \phi_1$ Until ϕ_2



$\blacksquare \models \Psi$

$\bullet \models \phi$

$q \models \phi AU \Psi$

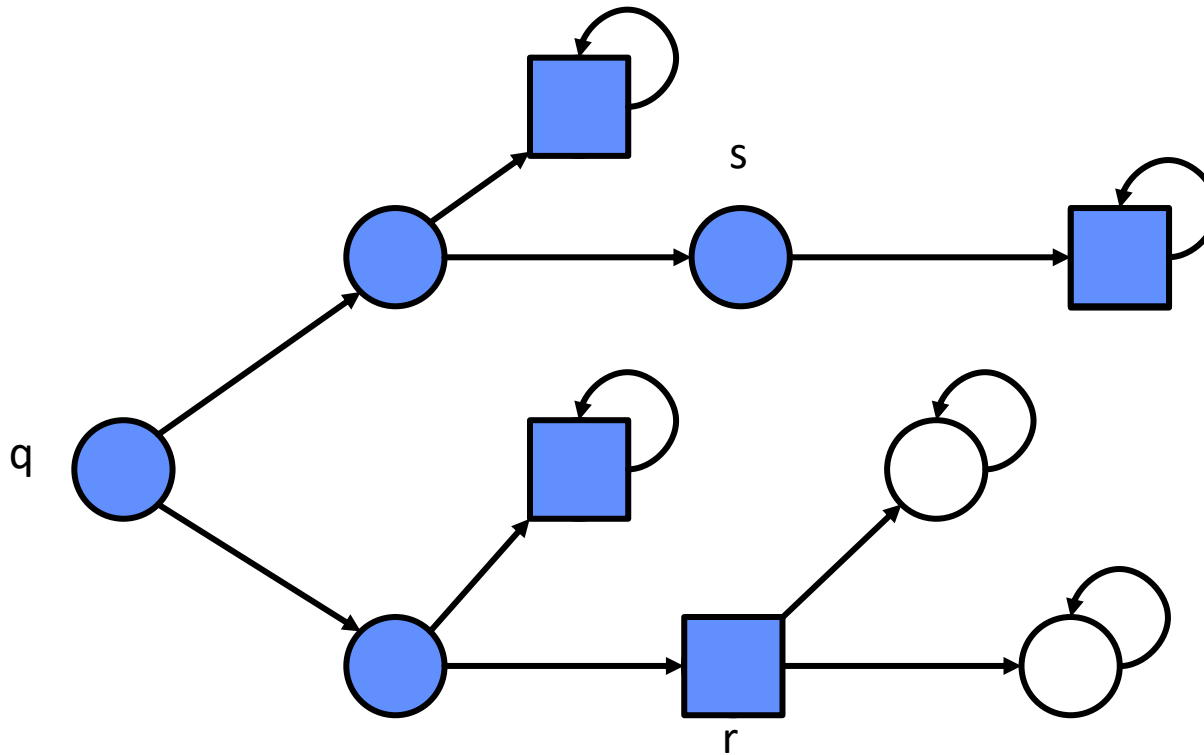
$r \models ?$

$s \models ?$

Evaluating a CTL formula

$\phi AU \Psi$: “On all paths, ϕ holds until Ψ holds.”

Over paths:	Path-specific:
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	$\phi_1 U \phi_2 \rightarrow \phi_1$ Until ϕ_2



■ $\models \Psi$

● $\models \phi$

q $\models \phi AU \Psi$

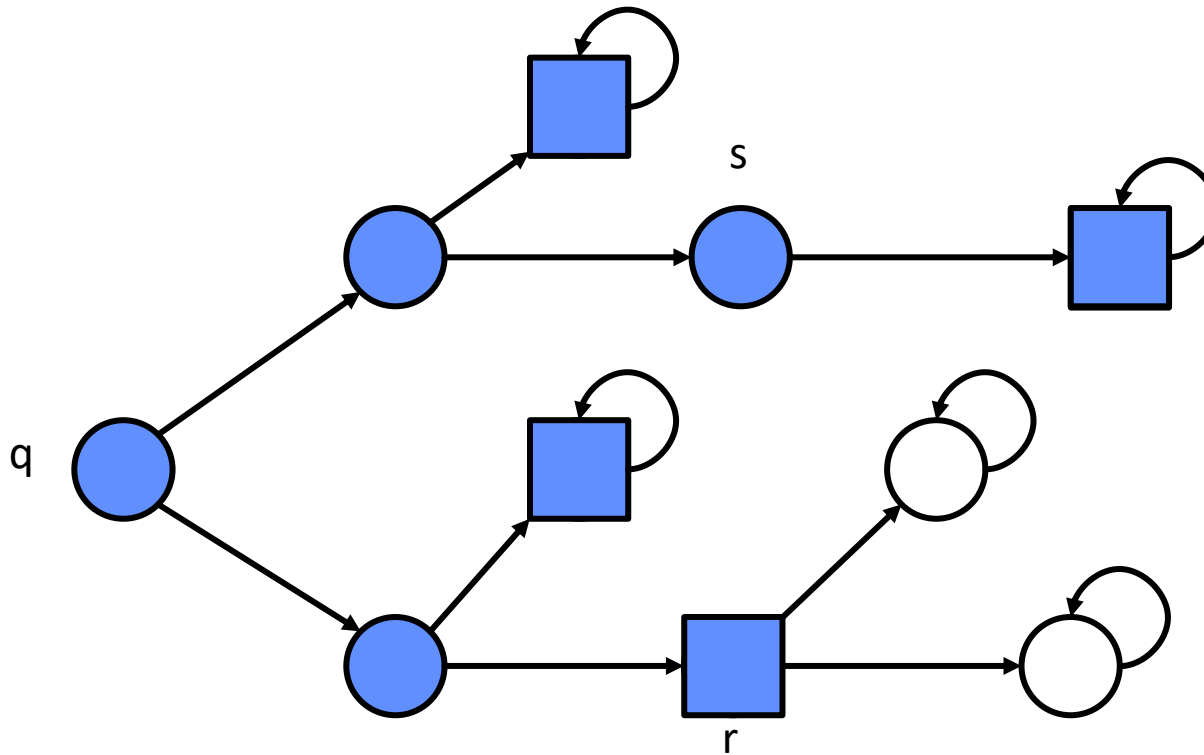
r $\models \phi AU \Psi$

s $\models ?$

Evaluating a CTL formula

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■ $\models \Psi$

● $\models \phi$

q $\models \phi AU \Psi$

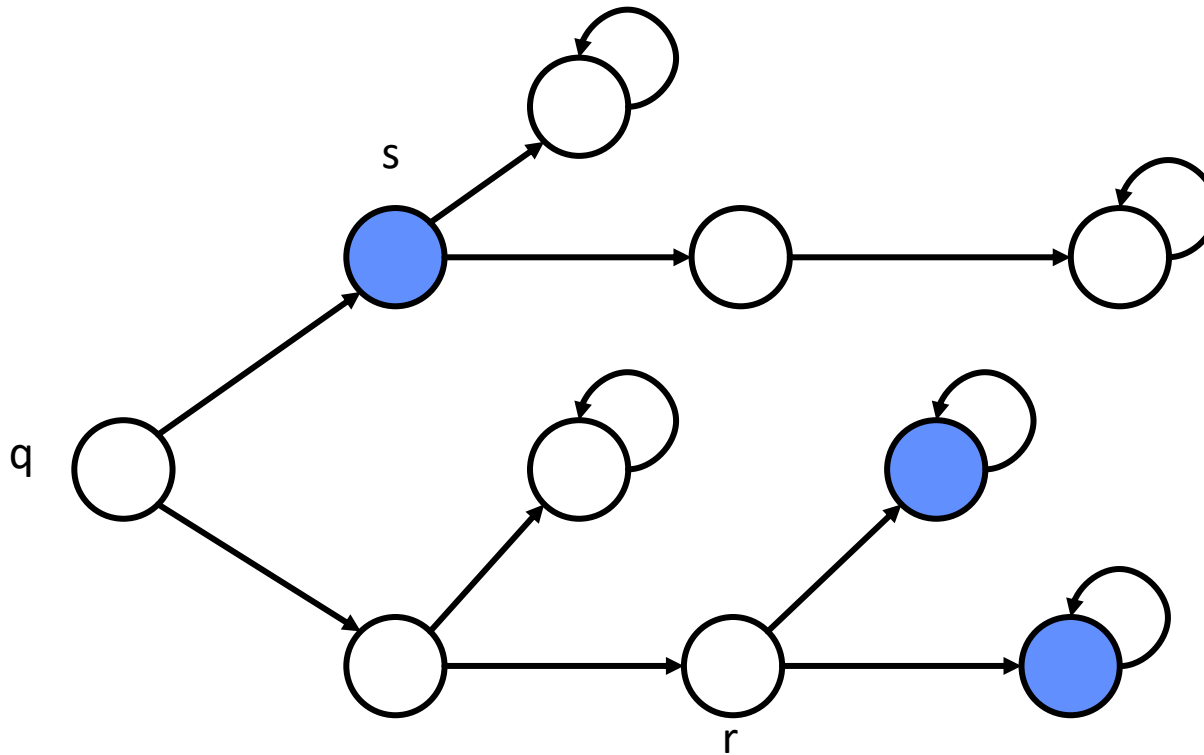
r $\models \phi AU \Psi$

s $\models \phi AU \Psi$

Evaluating a CTL formula

$EX\phi$: “There exists a path along which the next state satisfies ϕ .”

Over paths:	Path-specific:
$A\phi \rightarrow$ All ϕ	$X\phi \rightarrow$ NeXt ϕ
$E\phi \rightarrow$ Exists ϕ	$F\phi \rightarrow$ Finally ϕ
	$G\phi \rightarrow$ Globally ϕ
	$\phi_1 U \phi_2 \rightarrow \phi_1$ Until ϕ_2

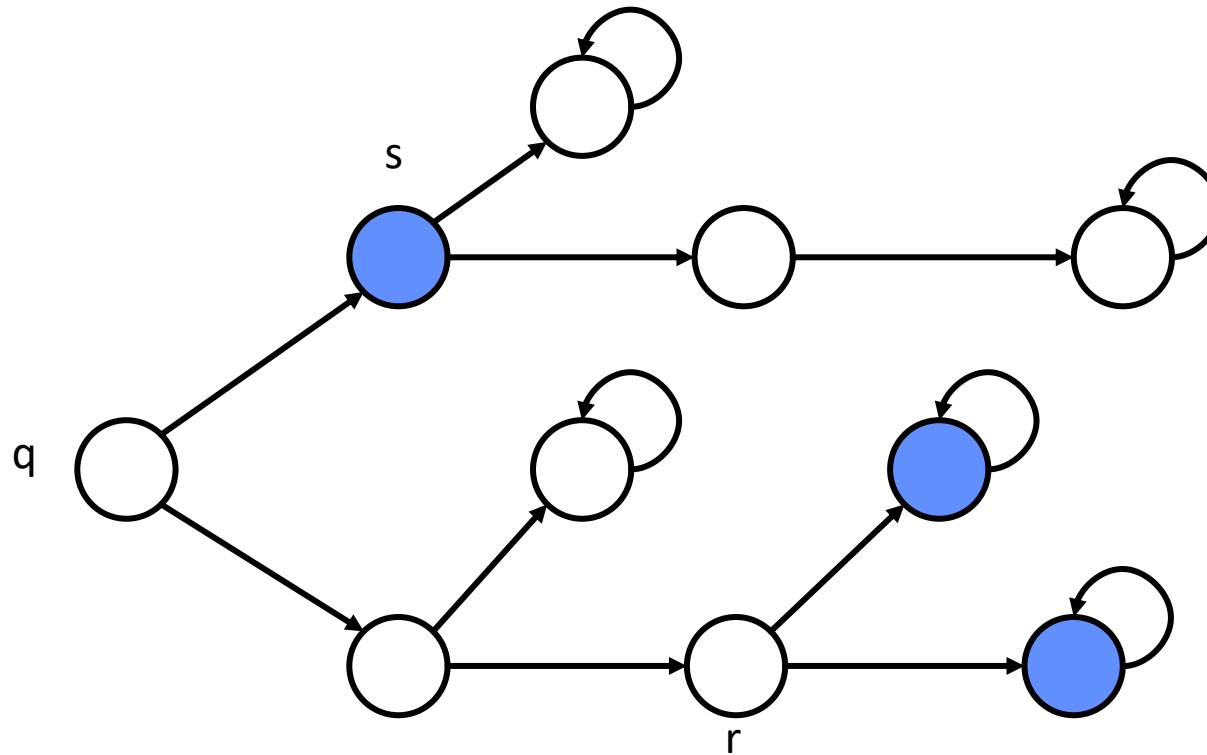


- $\bullet \models \phi$
- $q \models EX\phi$
- $r \models ?$
- $s \models ?$

Evaluating a CTL formula

$EX\phi$: “There exists a path along which the next state satisfies ϕ .”

Over paths:	Path-specific:
$A\phi \rightarrow$ All ϕ	$X\phi \rightarrow$ NeXt ϕ
$E\phi \rightarrow$ Exists ϕ	$F\phi \rightarrow$ Finally ϕ
	$G\phi \rightarrow$ Globally ϕ
	$\phi_1 U \phi_2 \rightarrow \phi_1$ Until ϕ_2

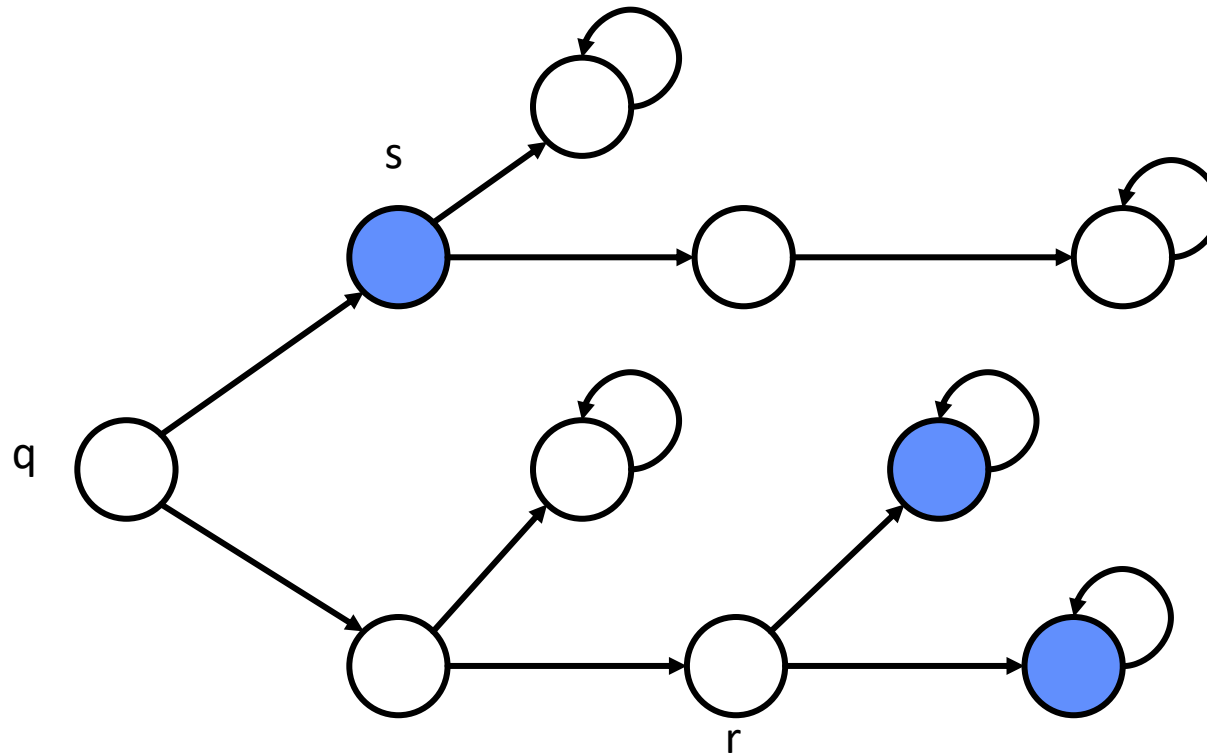


- $\bullet \models \phi$
- $q \models EX\phi$
- $r \models EX\phi$
- $s \models ?$

Evaluating a CTL formula

$EX\phi$: “There exists a path along which the next state satisfies ϕ .”

Over paths:	Path-specific:
$A\phi \rightarrow$ All ϕ	$X\phi \rightarrow$ NeXt ϕ
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	$\phi_1 U \phi_2 \rightarrow \phi_1$ Until ϕ_2

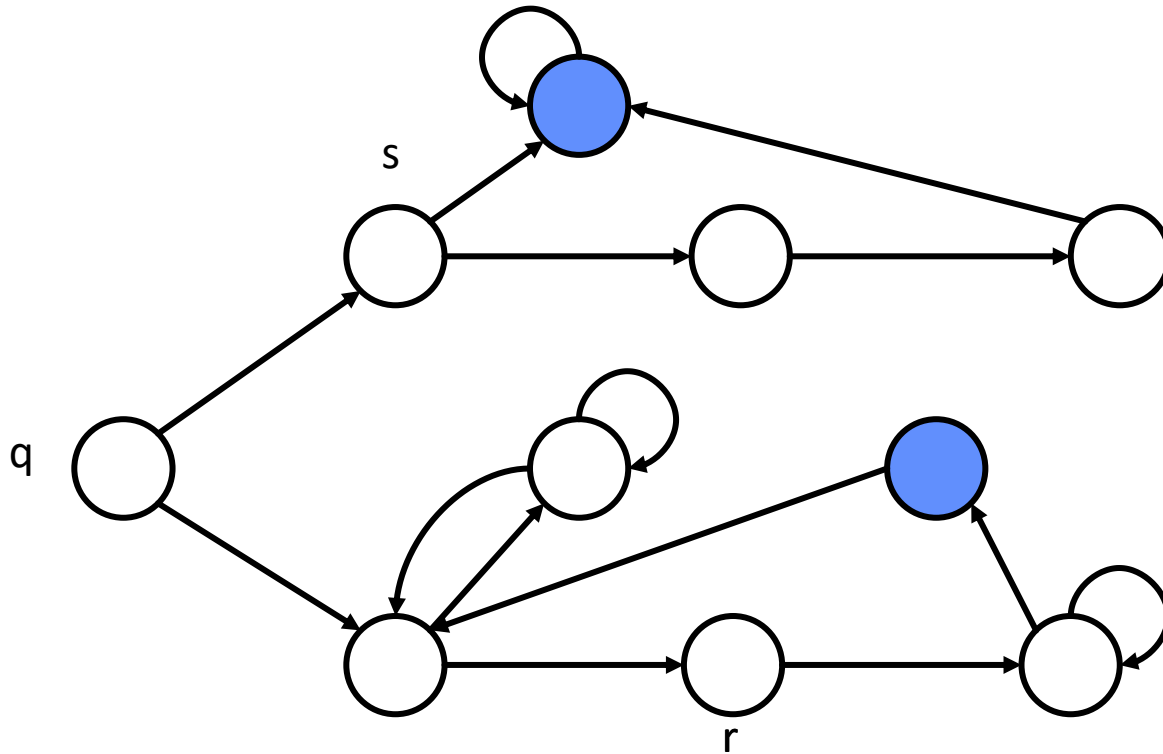


- $\bullet \models \phi$
- $q \models EX\phi$
- $r \models EX\phi$
- $s \not\models EX\phi$

Evaluating a CTL formula

AG EF ϕ : “On all paths and for all states, there exists a path along which at some state ϕ holds.”

Over paths:	Path-specific:
$A\phi \rightarrow$ A ll ϕ	$X\phi \rightarrow$ Ne X t ϕ
$E\phi \rightarrow$ E xists ϕ	$F\phi \rightarrow$ F inally ϕ
	$G\phi \rightarrow$ G lobally ϕ
	$\phi_1 U \phi_2 \rightarrow \phi_1$ U ntil ϕ_2



● $\models \phi$

$q \models AG EF \phi$

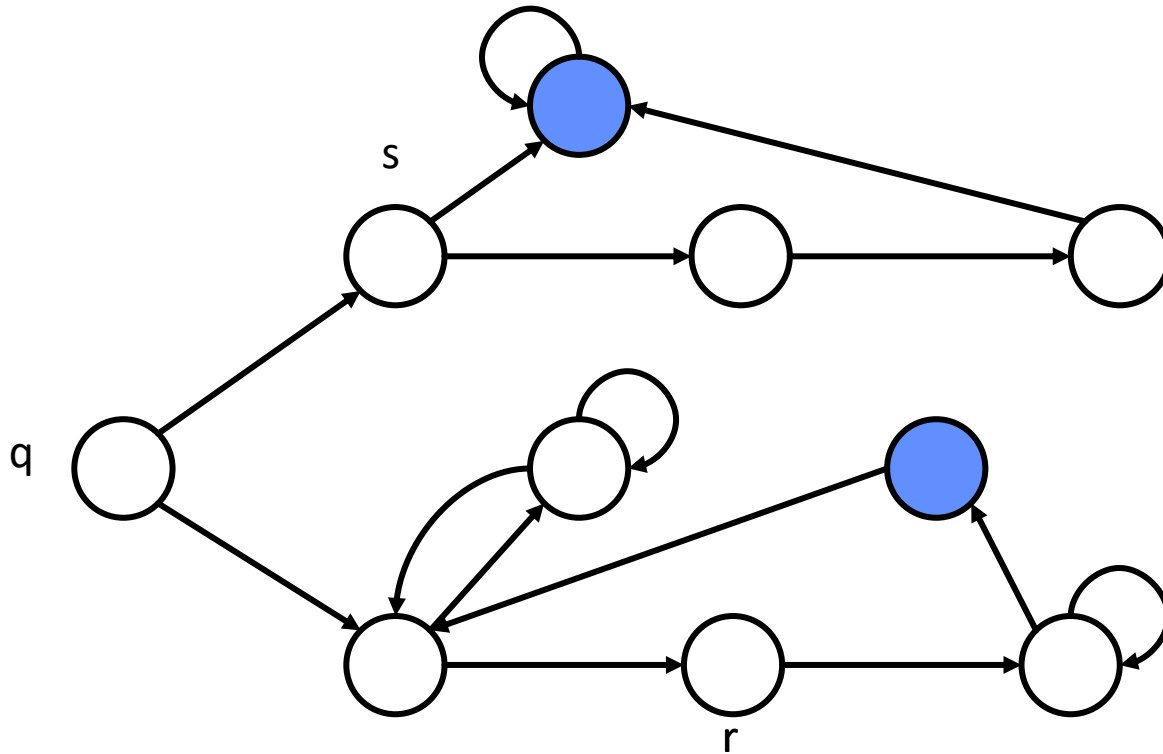
$r \models ?$

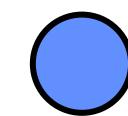
$s \models ?$

Evaluating a CTL formula

AG EF ϕ : “On all paths and for all states, there exists a path along which at some state ϕ holds.”

Over paths:	Path-specific:
$A\phi \rightarrow$ A ll ϕ	$X\phi \rightarrow$ Ne X t ϕ
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	$G\phi \rightarrow$ G lobally ϕ
	$\phi_1 U \phi_2 \rightarrow \phi_1$ U ntil ϕ_2



 $\models \phi$

$q \models AG EF \phi$

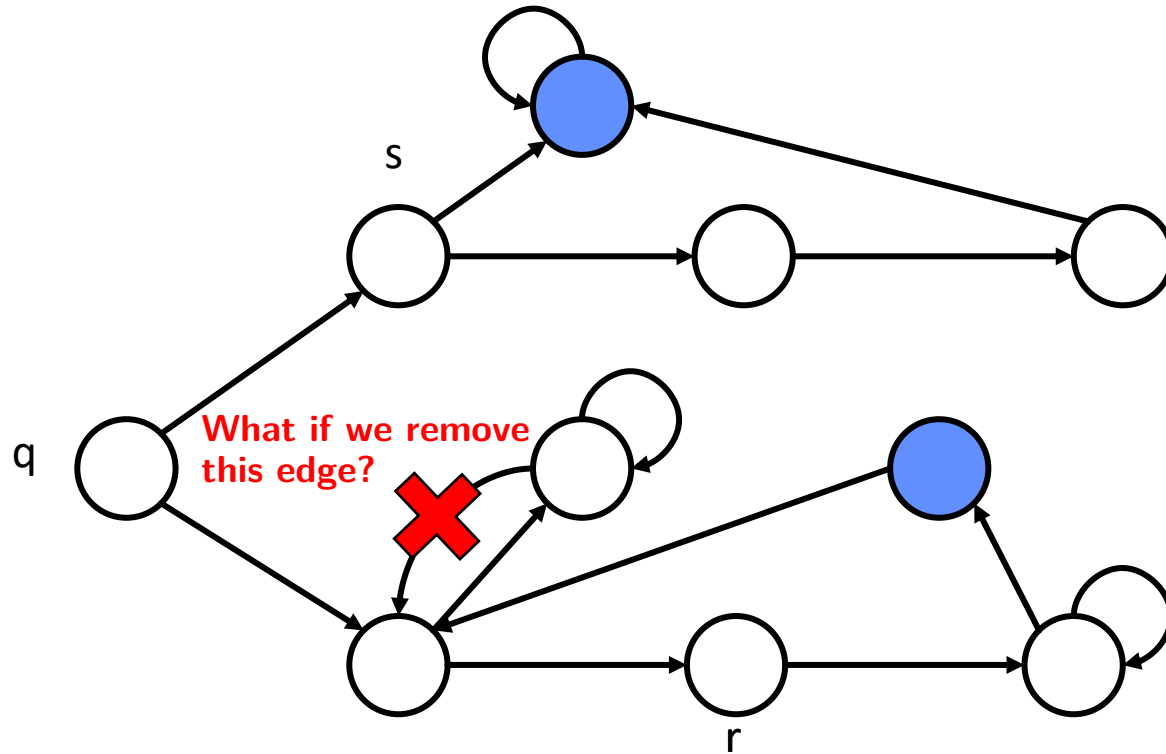
$r \models AG EF \phi$

$s \models ?$

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Over paths:	Path-specific:
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● $\models \phi$

q $\models ?$

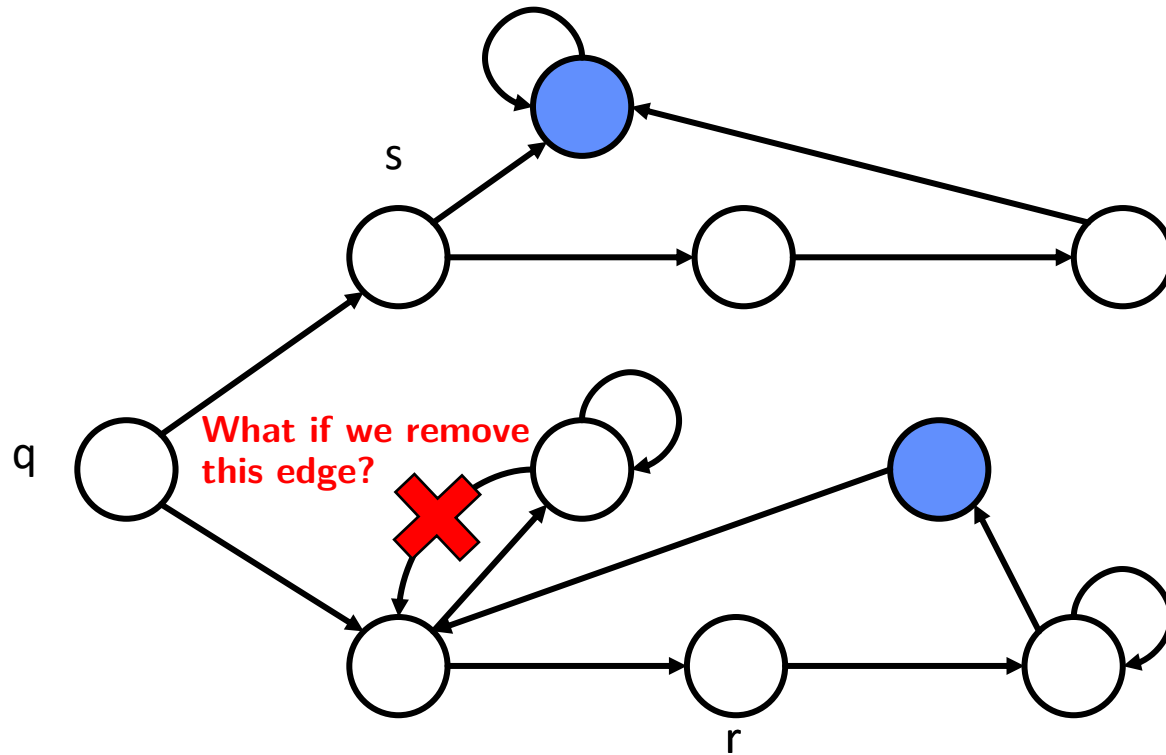
r $\models ?$

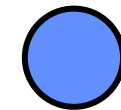
s $\models ?$

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	$\phi_1 U \phi_2 \rightarrow \phi_1$ U ntil ϕ_2



 $\models \phi$

$q \not\models AG EF \phi$

$r \not\models AG EF \phi$

$s \models AG EF \phi$

Interpreting a CTL formula

Encoding	Proposition
p	I like chocolate
q	It's warm outside

Over paths:	Path-specific:
$A\phi \rightarrow \mathbf{A}ll \phi$	$X\phi \rightarrow \mathbf{NeX}t \phi$
$E\phi \rightarrow \mathbf{E}xists \phi$	$F\phi \rightarrow \mathbf{F}inally \phi$
	$G\phi \rightarrow \mathbf{G}lobally \phi$
	$\phi_1 U \phi_2 \rightarrow \phi_1 \mathbf{U}ntil \phi_2$

Interpreting a CTL formula

Encoding	Proposition
p	I like chocolate
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- AG p

Over paths:	Path-specific:
$A\phi \rightarrow \mathbf{A}ll \phi$	$X\phi \rightarrow \mathbf{NeX}t \phi$
$E\phi \rightarrow \mathbf{E}xists \phi$	$F\phi \rightarrow \mathbf{F}inally \phi$
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$A\phi \rightarrow \mathbf{A}ll \phi$	$X\phi \rightarrow \mathbf{NeX}t \phi$
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	$\phi_1 U \phi_2 \rightarrow \phi_1 \mathbf{U}ntil \phi_2$

Encoding	Proposition
p	I like chocolate
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- AG p I will like chocolate from now on, no matter what happens.

Interpreting a CTL formula

Over paths:	Path-specific:
$A\phi \rightarrow \mathbf{A}ll \phi$	$X\phi \rightarrow \mathbf{NeX}t \phi$
$E\phi \rightarrow \mathbf{E}xists \phi$	$F\phi \rightarrow \mathbf{F}inally \phi$
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	$\phi_1 U \phi_2 \rightarrow \phi_1 \mathbf{U}ntil \phi_2$

Encoding	Proposition
p	I like chocolate
q	It's warm outside

- $AG p$ I will like chocolate from now on, no matter what happens.
- $EF p$

Interpreting a CTL formula

Over paths:	Path-specific:
$A\phi \rightarrow$ A ll ϕ	$X\phi \rightarrow$ Ne X t ϕ
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Encoding	Proposition
p	I like chocolate
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- $AG\ p$ I will like chocolate from now on, no matter what happens.
- $EF\ p$ It's possible I may like chocolate someday, at least for one day.

Interpreting a CTL formula

Over paths:	Path-specific:
$A\phi \rightarrow$ A ll ϕ	$X\phi \rightarrow$ Ne X t ϕ
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Encoding	Proposition
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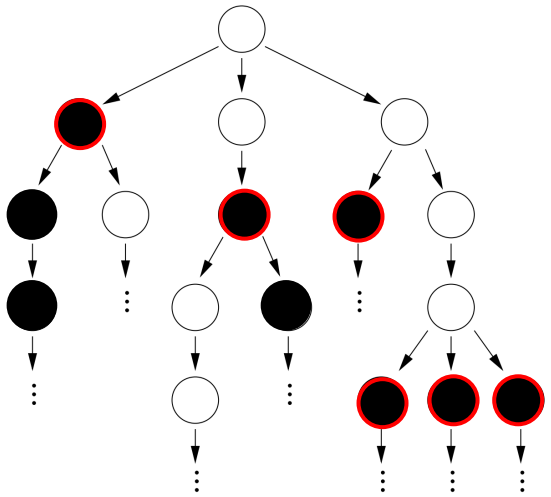
- $AG\ p$ I will like chocolate from now on, no matter what happens.
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- $AF\ EG\ p$

Interpreting a CTL formula

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$A\phi \rightarrow$ A ll ϕ	$X\phi \rightarrow$ Ne X t ϕ
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- **AF** $EG\ p$ There will be always sometime in the future (AF) that I may suddenly start liking chocolate for the rest of time (EG).



Interpreting a CTL formula

Over paths:	Path-specific:
$A\phi \rightarrow \mathbf{A}ll \phi$	$X\phi \rightarrow \mathbf{NeX}t \phi$
$E\phi \rightarrow \mathbf{E}xists \phi$	$F\phi \rightarrow \mathbf{F}inally \phi$
	$G\phi \rightarrow \mathbf{G}lobally \phi$
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Encoding	Proposition
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- $AF EG p$ There will be always sometime in the future (AF) that I may suddenly start liking chocolate for the rest of time (EG).
- $EG AF p$

Interpreting a CTL formula

Over paths:	Path-specific:
$A\phi \rightarrow$ A ll ϕ	$X\phi \rightarrow$ Ne X t ϕ
$E\phi \rightarrow$ E xists ϕ	$F\phi \rightarrow$ F inally ϕ
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Encoding	Proposition
p	I like chocolate
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- $AG\ p$ I will like chocolate from now on, no matter what happens.
- $EF\ p$ It's possible I may like chocolate someday, at least for one day.
- $AF\ EG\ p$ There will be always sometime in the future (AF) that I may suddenly start liking chocolate for the rest of time (EG).
- $EG\ AF\ p$ This is a critical time in my life. Depending on what happens (E), it's possible that for the rest of time (G), there will always be some time in the future (AF) when I will like chocolate. However, if the wrong thing happens next, then all bets are off and there's no guarantee about whether I will ever like chocolate.
- $p\ AU\ q$

Over paths:	Path-specific:
$A\phi \rightarrow$ All ϕ	$X\phi \rightarrow$ NeXt ϕ
$E\phi \rightarrow$ Exists ϕ	$F\phi \rightarrow$ Finally ϕ
	$G\phi \rightarrow$ Globally ϕ
	$\phi_1 U \phi_2 \rightarrow \phi_1$ Until ϕ_2

Interpreting a CTL formula

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- $EG\ AF\ p$ This is a critical time in my life. Depending on what happens (E), it's possible that for the rest of time (G), there will always be some time in the future (AF) when I will like chocolate. However, if the wrong thing happens next, then all bets are off and there's no guarantee about whether I will ever like chocolate.
- $p\ AU\ q$ No matter what happens, I will like chocolate from now on. But when it gets warm outside, I don't know whether I still like it. And it will get warm outside someday.

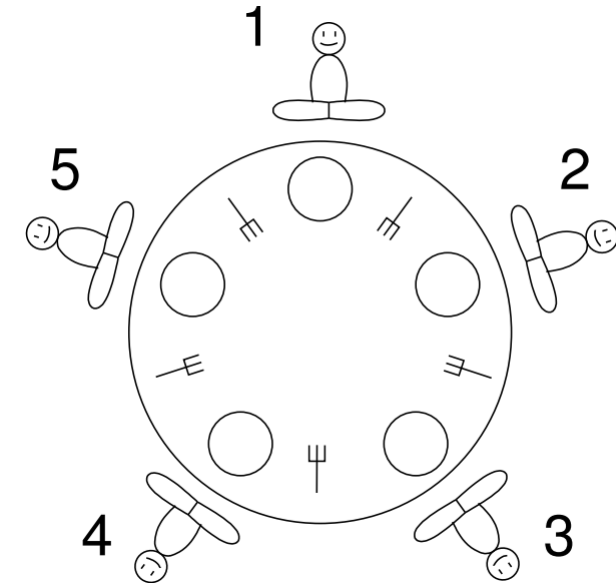
Specifying using a CTL formula

Over paths:	Path-specific:
$A\phi \rightarrow$ All ϕ	$X\phi \rightarrow$ NeXt ϕ
$E\phi \rightarrow$ Exists ϕ	$F\phi \rightarrow$ Finally ϕ
	$G\phi \rightarrow$ Globally ϕ
	$\phi_1 U \phi_2 \rightarrow \phi_1$ Until ϕ_2

Famous problem

Dining Philosophers

- Five philosophers are sitting around a table, taking turns at thinking and eating.
- Each needs two forks to eat.
- They put down forks only once they have eaten.
- There are only five forks.



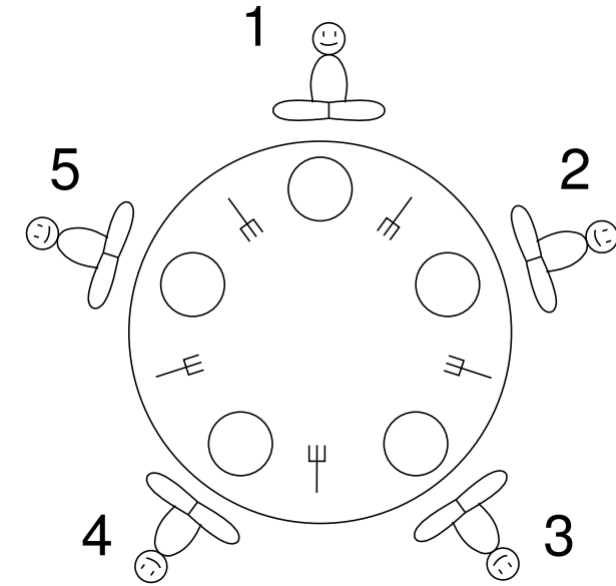
Atomic proposition

e_i : Philosopher i is currently eating.

Specifying using a CTL formula

Over paths:	Path-specific:
$A\phi \rightarrow$ A ll ϕ	$X\phi \rightarrow$ Ne X t ϕ
$E\phi \rightarrow$ E xists ϕ	$F\phi \rightarrow$ F inally ϕ
	$G\phi \rightarrow$ G lobally ϕ
	$\phi_1 U \phi_2 \rightarrow \phi_1$ U ntil ϕ_2

- “Philosophers 1 and 4 will never eat at the same time.”
- “Every philosopher will get infinitely many turns to eat.”
- “Philosopher 2 will be the first to eat.”



Specifying using a CTL formula

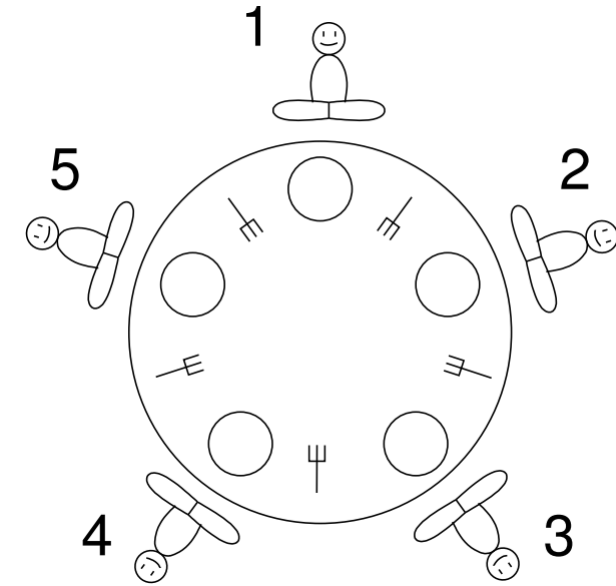
Over paths:	Path-specific:
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	$\phi_1 U \phi_2 \rightarrow \phi_1$ U ntil ϕ_2

- “Philosophers 1 and 4 will never eat at the same time.”

$$AG\neg(e_1 \cdot e_4)$$

- “Every philosopher will get infinitely many turns to eat.”

- “Philosopher 2 will be the first to eat.”



Specifying using a CTL formula

Over paths:	Path-specific:
$A\phi \rightarrow$ All ϕ	$X\phi \rightarrow$ NeXt ϕ
$E\phi \rightarrow$ Exists ϕ	$F\phi \rightarrow$ Finally ϕ
	$G\phi \rightarrow$ Globally ϕ
	$\phi_1 U \phi_2 \rightarrow \phi_1$ Until ϕ_2

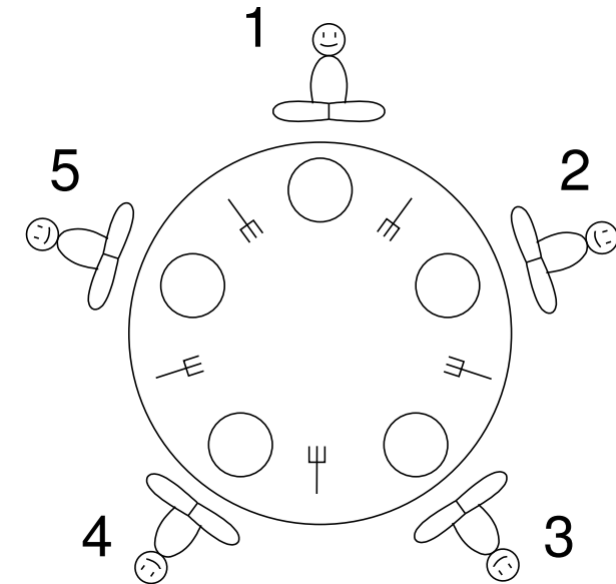
- “Philosophers 1 and 4 will never eat at the same time.”

$$AG\neg(e_1 \cdot e_4)$$

- “Every philosopher will get infinitely many turns to eat.”

$$AG(AFe_1 \cdot AFe_2 \cdot AFe_3 \cdot AFe_4 \cdot AFe_5)$$

- “Philosopher 2 will be the first to eat.”



Specifying using a CTL formula

Over paths:	Path-specific:
$A\phi \rightarrow$ All ϕ	$X\phi \rightarrow$ NeXt ϕ
$E\phi \rightarrow$ Exists ϕ	$F\phi \rightarrow$ Finally ϕ
	$G\phi \rightarrow$ Globally ϕ
	$\phi_1 U \phi_2 \rightarrow \phi_1$ Until ϕ_2

- “Philosophers 1 and 4 will never eat at the same time.”

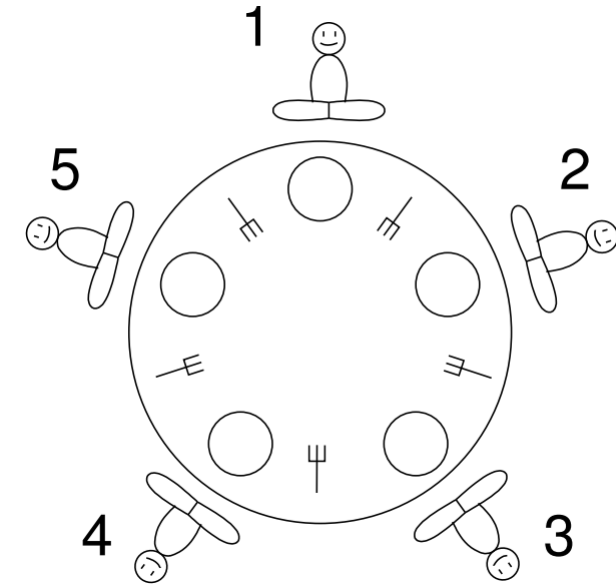
$$AG \neg (e_1 \cdot e_4)$$

- “Every philosopher will get infinitely many turns to eat.”

$$AG(AFe_1 \cdot AFe_2 \cdot AFe_3 \cdot AFe_4 \cdot AFe_5)$$

- “Philosopher 2 will be the first to eat.”

$$\neg (e_1 + e_3 + e_4 + e_5) AU e_2$$



Computing a CTL formula

Over paths:	Path-specific:
$A\phi \rightarrow \mathbf{A}ll \phi$	$X\phi \rightarrow \mathbf{NeX}t \phi$
$E\phi \rightarrow \mathbf{E}xists \phi$	$F\phi \rightarrow \mathbf{F}inally \phi$
	$G\phi \rightarrow \mathbf{G}lobally \phi$
	$\phi_1 U \phi_2 \rightarrow \phi_1 \mathbf{U}ntil \phi_2$

1. Define $[[\phi]]$ as the set of all states of the finite automaton for which CTL formula ϕ is true.
2. A finite automaton with initial state q_0 satisfies ϕ iff

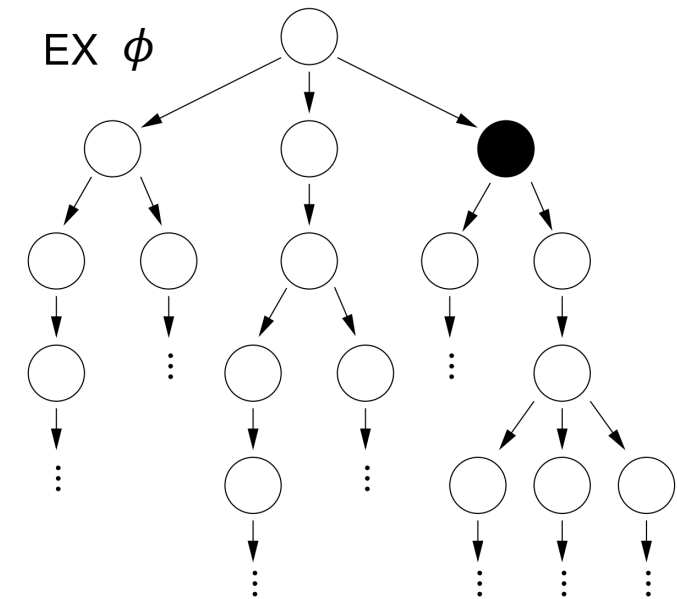
$$q_0 \in [[\phi]]$$

- Now, we can use our “trick”: computing with sets of states!
 - $\psi_{[[\phi]]}(q)$ is true if the state q is in the set $[[\phi]]$, i.e., it is a state for which the CTL formula is true.
 - Therefore, we can also say

$$q_0 \in [[\phi]] \equiv \psi_{[[\phi]]}(q_0) \text{ ————— characteristic function of the set } [[\phi]]$$

Computing a CTL formula: $EX \phi$

Over paths:	Path-specific:
$A\phi \rightarrow$ A ll ϕ	$X\phi \rightarrow$ Ne X t ϕ
$E\phi \rightarrow$ E xists ϕ	$F\phi \rightarrow$ F inally ϕ
	$G\phi \rightarrow$ G lobally ϕ
	$\phi_1 U \phi_2 \rightarrow \phi_1$ U ntil ϕ_2



Over paths:	Path-specific:
$A\phi \rightarrow$ A ll ϕ	$X\phi \rightarrow$ Ne X t ϕ
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Computing a CTL formula: $EX \phi$

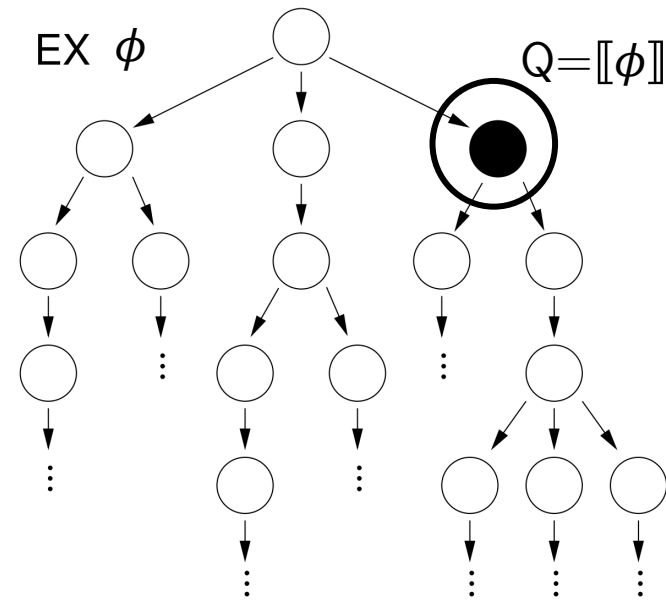
- Suppose that Q is the set of states for which the formula ϕ is true.

Sets

$$Q = \llbracket \phi \rrbracket$$

Characteristic functions

$$\psi_Q(q)$$



Over paths:	Path-specific:
$A\phi \rightarrow$ A ll ϕ	$X\phi \rightarrow$ Ne X t ϕ
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Computing a CTL formula: $EX \phi$

- Suppose that Q is the set of states for which the formula ϕ is true.
- Q' is the set of predecessor states of Q , i.e., the set of states that lead in one transition to a state in Q :

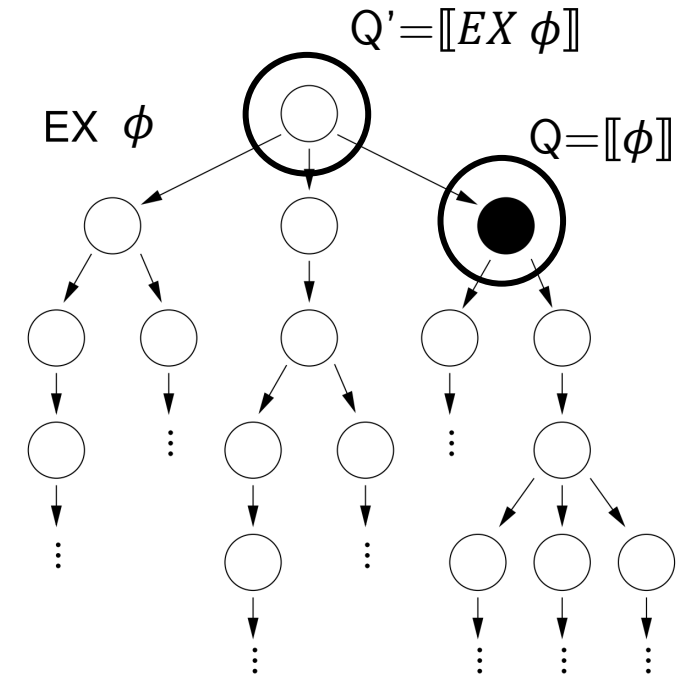
$$Q' = Pre(Q, \delta) = \{q' \mid \exists q : \psi_\delta(q', q) \cdot \psi_Q(q)\}$$

Sets

$$Q = \llbracket \phi \rrbracket \longrightarrow Q' = \llbracket EX\phi \rrbracket = Pre(\llbracket \phi \rrbracket, \delta)$$

Characteristic functions

$$\psi_Q(q) \longrightarrow \psi_{Q'}(q') = (\exists q : \psi_Q(q) \cdot \psi_\delta(q', q))$$



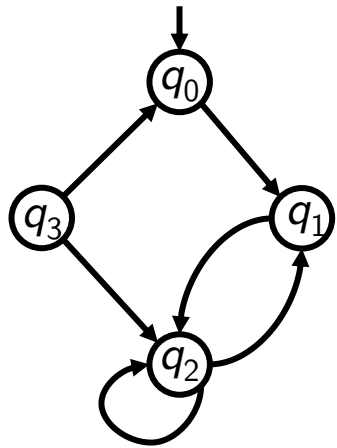
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Computing a CTL formula: $EX \phi$

- Example for $EX \phi$: Compute $EX q_2$

1. Define $\llbracket EX q_2 \rrbracket$: set of all states of the finite automaton for which CTL formula $EX q_2$ is true.

$$\llbracket q_2 \rrbracket = \{q_2\}$$

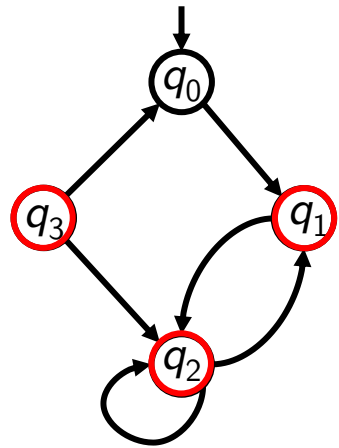


Over paths:	Path-specific:
$A\phi \rightarrow$ A ll ϕ	$X\phi \rightarrow$ Ne X t ϕ
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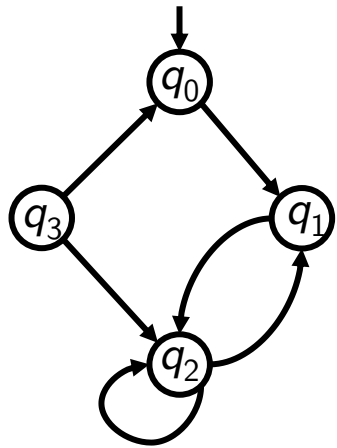
$$Q' = \llbracket EX q_2 \rrbracket = \underline{Pre(\{q_2\}, \delta)} = \{q_1, q_2, q_3\}$$

$$\{q' \mid \exists q : \psi_\delta(q', q) \cdot \psi_Q(q)\}$$

Over paths:	Path-specific:
$A\phi \rightarrow$ All ϕ	$X\phi \rightarrow$ NeXt ϕ
$E\phi \rightarrow$ Exists ϕ	$F\phi \rightarrow$ Finally ϕ
	$G\phi \rightarrow$ Globally ϕ
	$\phi_1 U \phi_2 \rightarrow \phi_1$ Until ϕ_2

Computing a CTL formula: $EX \phi$

- Example for $EX \phi$: Compute $EX q_2$



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$$\{q' \mid \exists q : \psi_\delta(q', q) \cdot \psi_Q(q)\}$$

2. A finite automaton with initial state q_0 satisfies $EX q_2$ iff $q_0 \in \llbracket EX q_2 \rrbracket$

As $q_0 \notin \llbracket EX q_2 \rrbracket = \{q_1, q_2, q_3\}$, the CTL formula $EX q_2$ is not true.

Over paths:	Path-specific:
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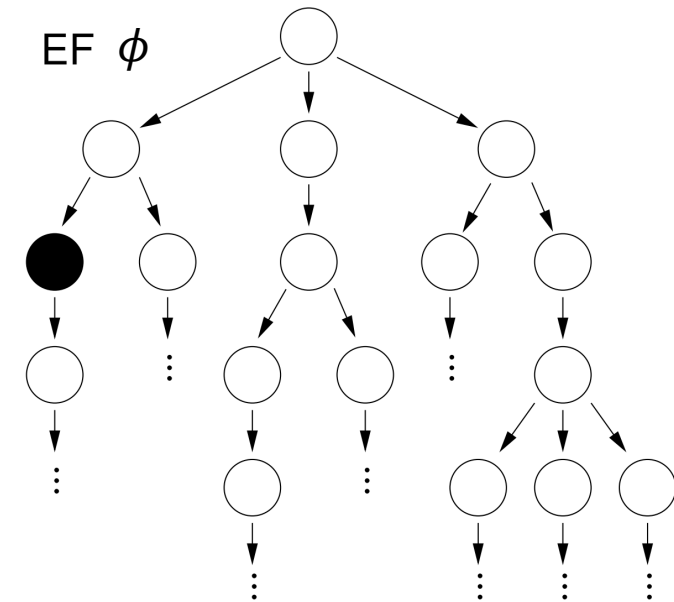
Computing a CTL formula: $EF \phi$

- Start with the set of states for which the formula ϕ is true.
- Add to this set the set of predecessor states. Repeat for the resulting set of states, ..., until we reach a fixed point.

$$Q_0 = \llbracket \phi \rrbracket$$

$$Q_i = Q_{i-1} \cup \text{Pre}(Q_{i-1}, \delta) \quad \text{for all } i > 1 \text{ until a fixed point } Q' \text{ is reached}$$

$$\llbracket EF\phi \rrbracket = Q'$$



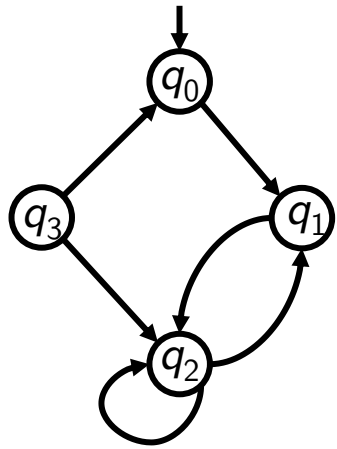
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Computing a CTL formula: $EF \phi$

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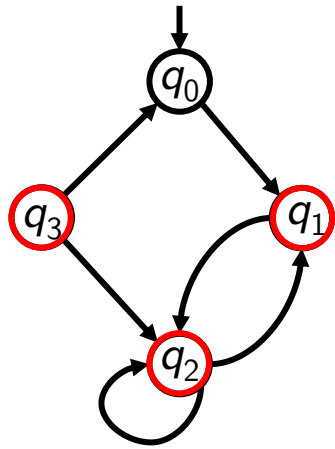


Over paths:	Path-specific:
$A\phi \rightarrow$ All ϕ	$X\phi \rightarrow$ NeXt ϕ
$E\phi \rightarrow$ Exists ϕ	$F\phi \rightarrow$ Finally ϕ
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	$\phi_1 U \phi_2 \rightarrow \phi_1$ Until ϕ_2

Computing a CTL formula: $EF \phi$

- Example for $EF\phi$: Compute $EF q_2$

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$$\{q' \mid \exists q \text{ with } \psi_Q(q) \cdot \psi_\delta(q', q)\} = \{q_1, q_2, q_3\}$$

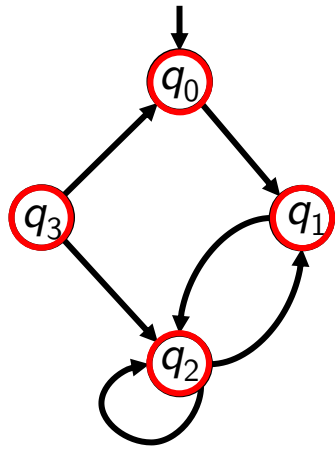
$$Q_1 = \{q_2\} \cup \underline{\text{Pre}(\{q_2\}, \delta)} = \{q_1, q_2, q_3\}$$

Over paths:	Path-specific:
$A\phi \rightarrow$ All ϕ	$X\phi \rightarrow$ NeXt ϕ
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Computing a CTL formula: $EF \phi$

- Example for $EF\phi$: Compute $EF q_2$

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$$Q_1 = \{q_2\} \cup \text{Pre}(\{q_2\}, \delta) = \{q_1, q_2, q_3\}$$

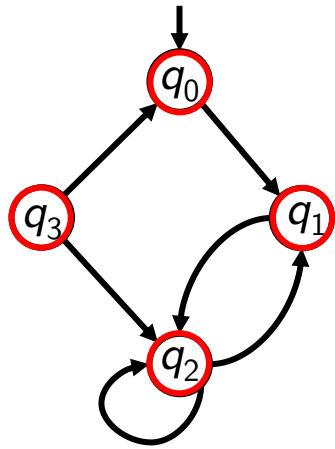
$$Q_2 = \{q_1, q_2, q_3\} \cup \text{Pre}(\{q_1, q_2, q_3\}, \delta) = \{q_0, q_1, q_2, q_3\}$$

Over paths:	Path-specific:
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$E\phi \rightarrow$ Exists ϕ	$F\phi \rightarrow$ Finally ϕ
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Computing a CTL formula: $EF \phi$

- Example for $EF\phi$: Compute $EF q_2$

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$$Q_1 = \{q_2\} \cup \text{Pre}(\{q_2\}, \delta) = \{q_1, q_2, q_3\}$$

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$$Q_3 = \{q_0, q_1, q_2, q_3\} \cup \text{Pre}(\{q_0, q_1, q_2, q_3\}, \delta) = \{q_0, q_1, q_2, q_3\}$$

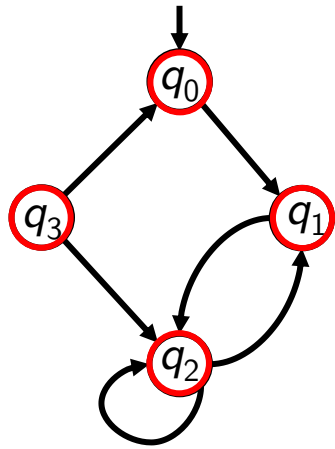
$$\llbracket EF q_2 \rrbracket = Q_3 = \{q_0, q_1, q_2, q_3\}$$

Over paths:	Path-specific:
$A\phi \rightarrow$ All ϕ	$X\phi \rightarrow$ NeXt ϕ
$E\phi \rightarrow$ Exists ϕ	$F\phi \rightarrow$ Finally ϕ
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Computing a CTL formula: $EF \phi$

- Example for $EF\phi$: Compute $EF q_2$

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$$\{q' \mid \exists q \text{ with } \psi_Q(q) \cdot \psi_\delta(q', q)\} = \{q_1, q_2, q_3\}$$

$$Q_1 = \{q_2\} \cup \text{Pre}(\{q_2\}, \delta) = \{q_1, q_2, q_3\}$$

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$$\llbracket EF q_2 \rrbracket = Q_3 = \{q_0, q_1, q_2, q_3\}$$

2. A finite automaton with initial state q_0 satisfies $EF q_2$ iff $q_0 \in \llbracket EF q_2 \rrbracket$

As $q_0 \in \llbracket EF q_2 \rrbracket = \{q_0, q_1, q_2, q_3\}$, the CTL formula $EF q_2$ is true.

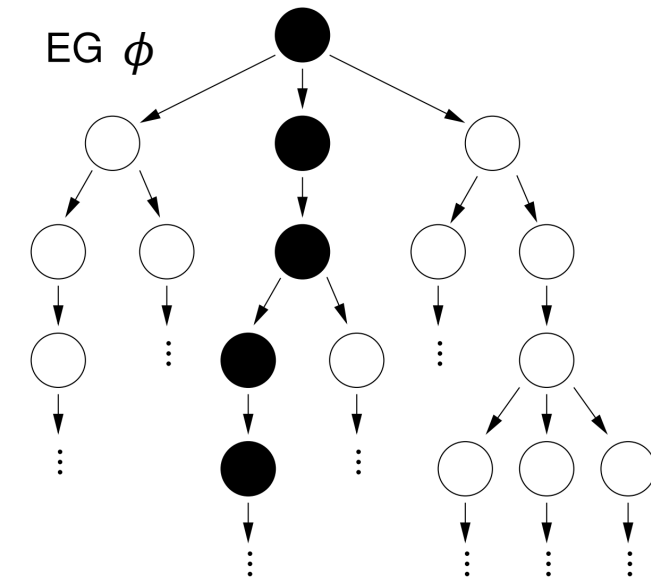
Over paths:	Path-specific:
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	$\phi_1 U \phi_2 \rightarrow \phi_1$ U ntil ϕ_2

Computing a CTL formula: $EG \phi$

- Start with the set of states for which the formula ϕ is true.
- Cut this set with the set of predecessor states. Repeat for the resulting set of states,..., until we reach a fixed point.

$$Q_0 = \llbracket \phi \rrbracket$$

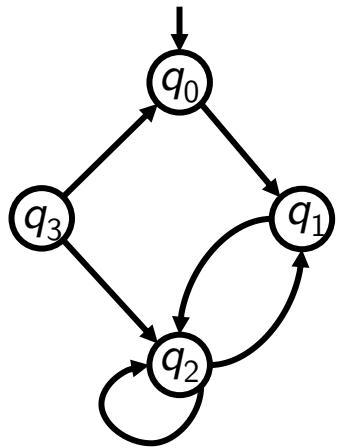
$$Q_i = Q_{i-1} \cap \text{Pre}(Q_{i-1}, \delta) \quad \text{for all } i > 1 \text{ until a fixed point } Q' \text{ is reached}$$



Over paths:	Path-specific:
$A\phi \rightarrow$ A ll ϕ	$X\phi \rightarrow$ Ne X t ϕ
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Computing a CTL formula: $EG \phi$

- Example for $EG \phi$: Compute $EG q_2$



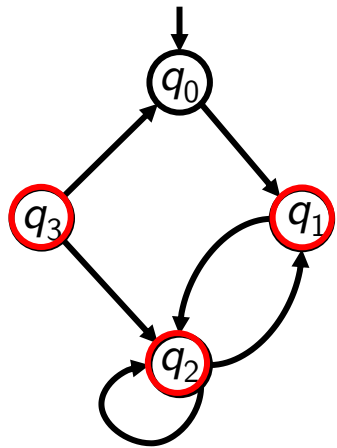
1. Define $\llbracket EG q_2 \rrbracket$: set of all states of the finite automaton for which CTL formula $EG q_2$ is true.

$$Q_0 = \llbracket q_2 \rrbracket = \{q_2\}$$

Over paths:	Path-specific:
$A\phi \rightarrow$ All ϕ	$X\phi \rightarrow$ NeXt ϕ
$E\phi \rightarrow$ Exists ϕ	$F\phi \rightarrow$ Finally ϕ
	$G\phi \rightarrow$ Globally ϕ
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Computing a CTL formula: $EG \phi$

- Example for $EG \phi$: Compute $EG q_2$



1. Define $\llbracket EG q_2 \rrbracket$: set of all states of the finite automaton for which CTL formula $EG q_2$ is true.

$$Q_0 = \llbracket q_2 \rrbracket = \{q_2\} \quad \{q' \mid \exists q \text{ with } \psi_Q(q) \cdot \psi_\delta(q', q)\} = \{q_1, q_2, q_3\}$$

$$Q_1 = \{q_2\} \cap \text{Pre}(\{q_2\}, \delta) = \{q_2\}$$

$$\llbracket EG q_2 \rrbracket = Q_2 = \{q_2\}$$

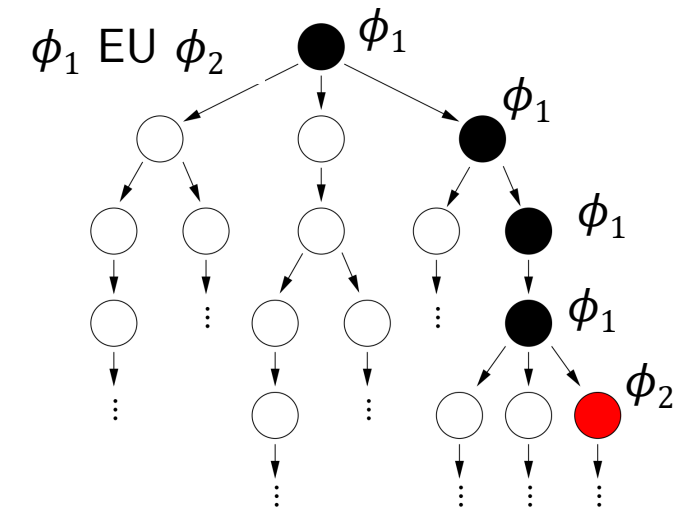
2. A finite automaton with initial state q_0 satisfies $EG q_2$ iff $q_0 \in \llbracket EG q_2 \rrbracket$

As $q_0 \notin \llbracket EG q_2 \rrbracket = \{q_2\}$, the CTL formula $EG q_2$ is not true.

Over paths:	Path-specific:
$A\phi \rightarrow$ A ll ϕ	$X\phi \rightarrow$ Ne X t ϕ
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	$\phi_1 U \phi_2 \rightarrow \phi_1$ U ntil ϕ_2

Computing a CTL formula: $\phi_1 EU \phi_2$

- Start with the set of states for which the formula ϕ_2 is true.
- Add to this set the set of predecessor states for which the formula ϕ_1 is true. Repeat for the resulting set of states we do the same,..., until we reach a fixed point.
- Like $EF \phi_2$; the only difference is that, on our path backwards, we always make sure that also ϕ_1 holds.



$$Q_0 = \llbracket \phi_2 \rrbracket$$

$$Q_i = Q_{i-1} \cup (\text{Pre}(Q_{i-1}, \delta) \cap \llbracket \phi_1 \rrbracket) \quad \text{for all } i > 1 \text{ until a fixed point is reached}$$

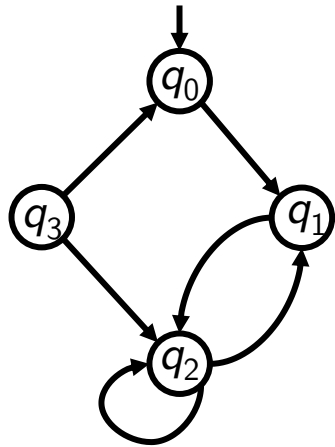
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Computing a CTL formula: $\phi_1 EU \phi_2$

- Example for $\phi_1 EU \phi_2$: Compute $q_0 EU q_1$

1. Define $\llbracket q_0 EU q_1 \rrbracket$: set of all states of the finite automaton for which CTL formula $q_0 EU q_1$ is true.

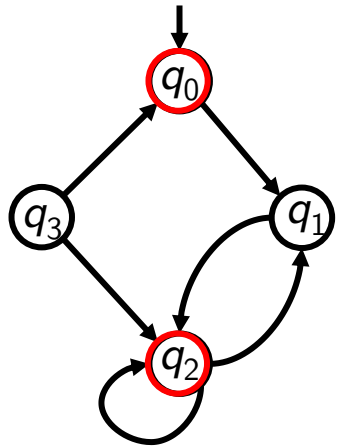
$$Q_0 = \llbracket q_1 \rrbracket = \{q_1\}$$



Over paths:	Path-specific:
$A\phi \rightarrow$ All ϕ	$X\phi \rightarrow$ NeXt ϕ
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Computing a CTL formula: $\phi_1 EU \phi_2$

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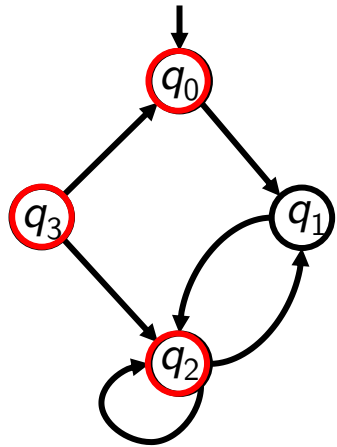
$$\{q' \mid \exists q \text{ with } \psi_Q(q) \cdot \psi_\delta(q', q)\} = \{q_0, q_2\}$$

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Computing a CTL formula: $\phi_1 EU \phi_2$

- Example for $\phi_1 EU \phi_2$: Compute $q_0 EU q_1$



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$$\llbracket q_0 EU q_1 \rrbracket = Q_2 = \{q_0, q_1\} \quad \{q_0, q_2, q_3\}$$

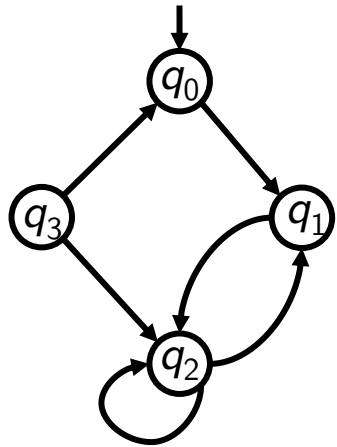
2. A finite automaton with initial state q_0 satisfies $q_0 EU q_1$ iff $q_0 \in \llbracket q_0 EU q_1 \rrbracket$

As $q_0 \in \llbracket q_0 EU q_1 \rrbracket = \{q_0, q_1\}$, the CTL formula $q_0 EU q_1$ is true.

Over paths:	Path-specific:
$A\phi \rightarrow$ All ϕ	$X\phi \rightarrow$ NeXt ϕ
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Computing a CTL formula: $\phi_1 EU \phi_2$

- Example for $\phi_1 EU \phi_2$: Compute $q_0 EU q_1$



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$$\llbracket q_0 EU q_1 \rrbracket = Q_2 = \{q_0, q_1\} \quad \{q_0, q_2, q_3\}$$

2. A finite automaton with initial state q_0 satisfies $q_0 EU q_1$ iff $q_0 \in \llbracket q_0 EU q_1 \rrbracket$

As $q_0 \in \llbracket q_0 EU q_1 \rrbracket = \{q_0, q_1\}$, the CTL formula $q_0 EU q_1$ is true.

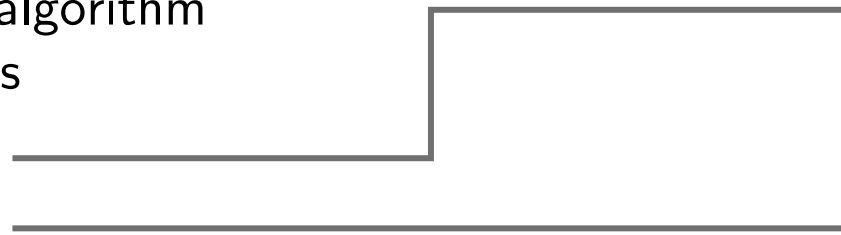
Compute other CTL expressions as:

$$AF\phi \equiv \neg EG(\neg\phi) \quad AG\phi \equiv \neg EF(\neg\phi) \quad AX\phi \equiv \neg EX(\neg\phi)$$

So... what is model checking exactly?

Model checking is an algorithm which takes two inputs

- a DES model M
- a formula ϕ



Finite automaton
Petri net
Kripke machine
...
CTL, LTL, ...

It explores the state space of M such as to either

- prove that $M \models \phi$, or
- return a trace where the formula does not hold in M . — a counter-example

Extremely useful!

- Debugging the model
- Searching a specific execution sequence

Efficient state representation

- Set of states as Boolean function
- Binary Decision Diagram representation

Computing reachability

- Leverage efficient state representation
- Explore successor sets of states

Today

Proving properties

- Temporal logic (CTL)
- Encoding as reachability problem

Conclusion and perspectives

Next week(s)

Petri Nets

- asynchronous DES model
- tailored model concurrent distributed systems
- capture an infinite state space with a finite model

————— a computer
a network

How they work?

How to use them for modeling systems?

How to **verify them**?

Your turn to practice!

after the break

1. Familiarise yourself with CTL logic and how to compute sets of states satisfying a given formula
2. Convert a concrete problem into a state reachability question
(adapted from state-of-the-art research!)

Any feedback?

Please fill out this short (anonymous) form!

The form will be available throughout the lecture—feel free to provide feedback at any point.



<https://forms.gle/7VUaidEVreS9uswa9>

Thanks for your attention and see you next week! 😊